Operating Instructions

GOSSEN METRAWATT

SYSKON | P500, P800, P1500, P3000 and P4500
Computer Controlled Laboratory Power Supplies

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☞ **Note**

These operating instructions describe devices as from firmware version 005, see chapter 2.4.1.

1 Initial Inspection – Warnings

When unpacking the instrument, make sure that the KONSTANTER and all included accessories are fully intact and have not been damaged during transport.

Unpacking

- Other than the usual care exercised in handling electronic equipment, no additional precautions are required when unpacking the instrument.
- The KONSTANTER is delivered in recyclable packaging, which provides for adequate protection during transport as substantiated by testing. If the instrument is repacked at a later point in time, the same packaging or its equivalent must be used.

Visual inspection

- Compare the order number or type designation included on the packaging and/or the serial plate with the particulars shown in the shipping documents.
- Make sure that all accessory components have been included (see chapter 14 "Options and Accessories").
- Inspect the packaging, as well as mechanical instrument and accessory components for possible transport damage.

Complaints

If damage is discovered, immediately file a claim with the freight forwarder (save the packaging!). If other defects are detected or in the event that service is required, inform your local representative, or contact us directly at the address included on the last page of this handbook.

Use for Intended Purpose

Use of the KONSTANTER for its intended purpose is only fulfilled if the instrument is used in accordance with the stipulations set forth in the respective operating instructions, and is operated within the specified power limits. The Konstanter may only be used by persons with appropriate technical knowledge, or who have received appropriate instruction.

In order to prevent danger during use, shock-proof connector cables must be used when connecting power consumers. The KONSTANTER's output values (U, I) must be adjusted such that no danger of overloading or destruction exists for the connected power consumer.

Only then can the safety of the user, the instrument and the device under test or the power consumer be assured.

Warnings and Safety Precautions

The KONSTANTER has been manufactured and tested in accordance with the electrical safety regulations listed under Technical Data as a safety class I device, and has been shipped from the factory in flawless technical safety condition. In order to maintain this condition and to assure safe operation, users must observe all notes and warnings included in these operating instructions.

Attention!

A note concerning operation, practical advice or other information which must be adhered to in order to prevent damage to the **KONSTANTER**, and to assure correct operation.

Warning!

An operating procedure, practical advice or other information which must be adhered to in order to assure safe operation of the **KONSTANTER**, and to prevent personal injury.
The most important warnings are summarized below.

Warning!

Protective Grounding, PE Connection
The KONSTANTER may only be placed into operation after the protective conductor has been connected. Interruption or disconnection of the protective conductor may result in danger for the user.
The device is connected to the mains by means of a 3 conductor cable with mains plug.

Warning!

Opening the Housing Covers
Remove the mains plug from the outlet before opening the housing. When the housing covers are opened, voltage conducting parts may be exposed. Any contact with these exposed conductive parts is life endangering. For this reason, the instrument may only be opened by trained personnel who are familiar with the dangers involved.

Warning!

Repair by Trained Personnel
Maintenance and repair work, as well as internal balancing, may only be performed by trained personnel who are familiar with the respective functions, and the dangers involved.
After the instrument has been disconnected from the mains, wait approximately 5 minutes in order to allow the capacitors to discharge themselves to safe voltage levels.

Warning!

Replacing Fuses
Only specified fuse types with the specified nominal current rating may be used to replace blown fuses (see Technical Data and specifications on the serial plate). Manipulation of the fuses and/or the fuse holder is prohibited.

Attention!

Impaired Safety
If it can be assumed that safe operation is no longer possible, the KONSTANTER must be removed from service and secured against inadvertent use. Safe operation is no longer possible:
– If the KONSTANTER demonstrates visible damage or transport damage
– If the KONSTANTER no longer functions
– After lengthy periods of storage under conditions which deviate from the specified storage conditions

Significance of Symbols

CE — Indicates European Conformity

This instrument fulfills the requirements of applicable European and national EC directives. This is confirmed by means of the CE mark. A corresponding declaration of conformity can be requested from GMC-I Messtechnik GmbH.

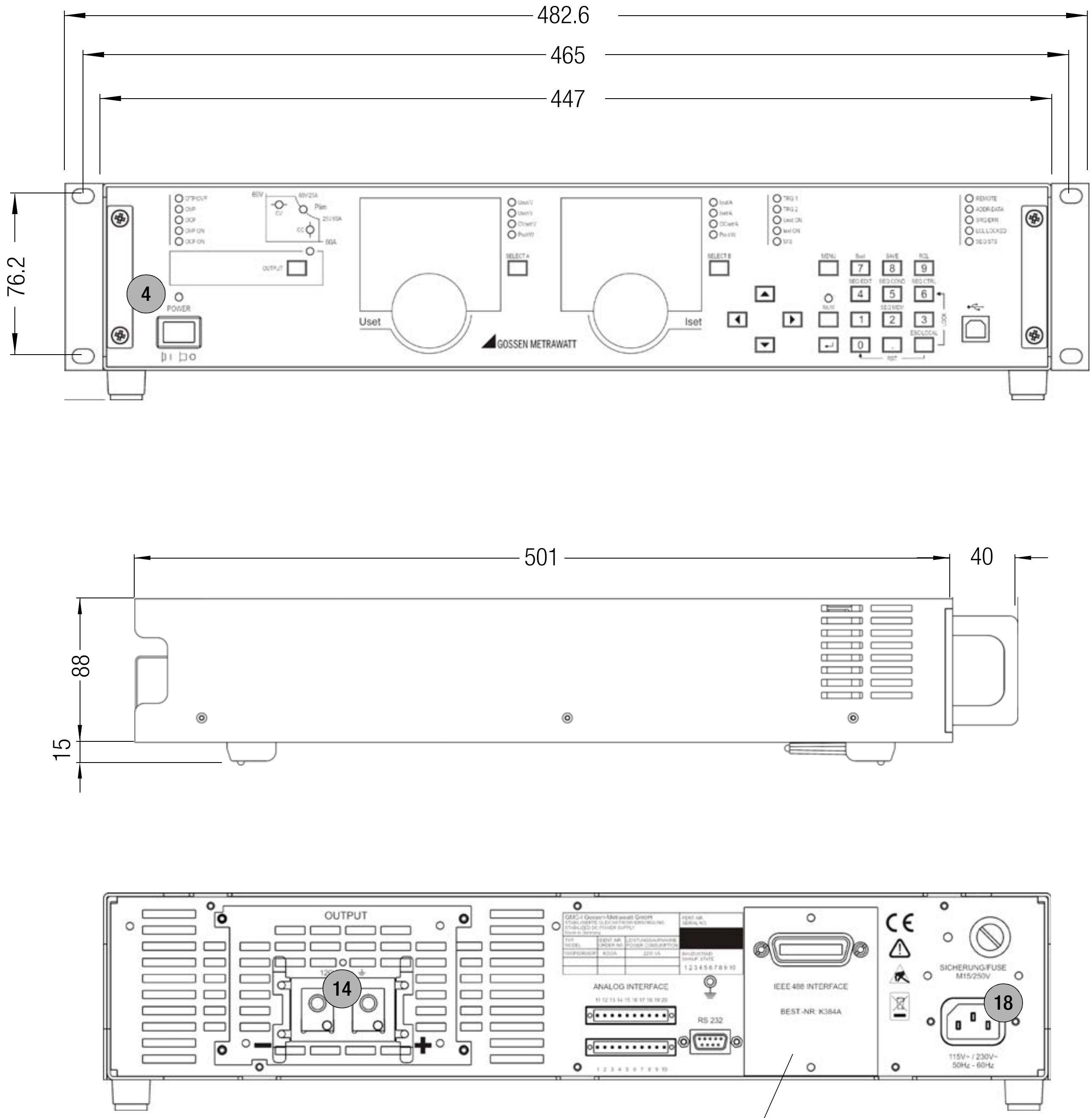
Observe ESDS guidelines

Warning concerning a point of danger (attention: observe documentation!)

The device may not be disposed of with the trash. Further information regarding the WEEE mark can be accessed at www.gossenmetrawatt.com by entering the search term WEEE.

2 Initial Start-Up – Dimensional Drawings

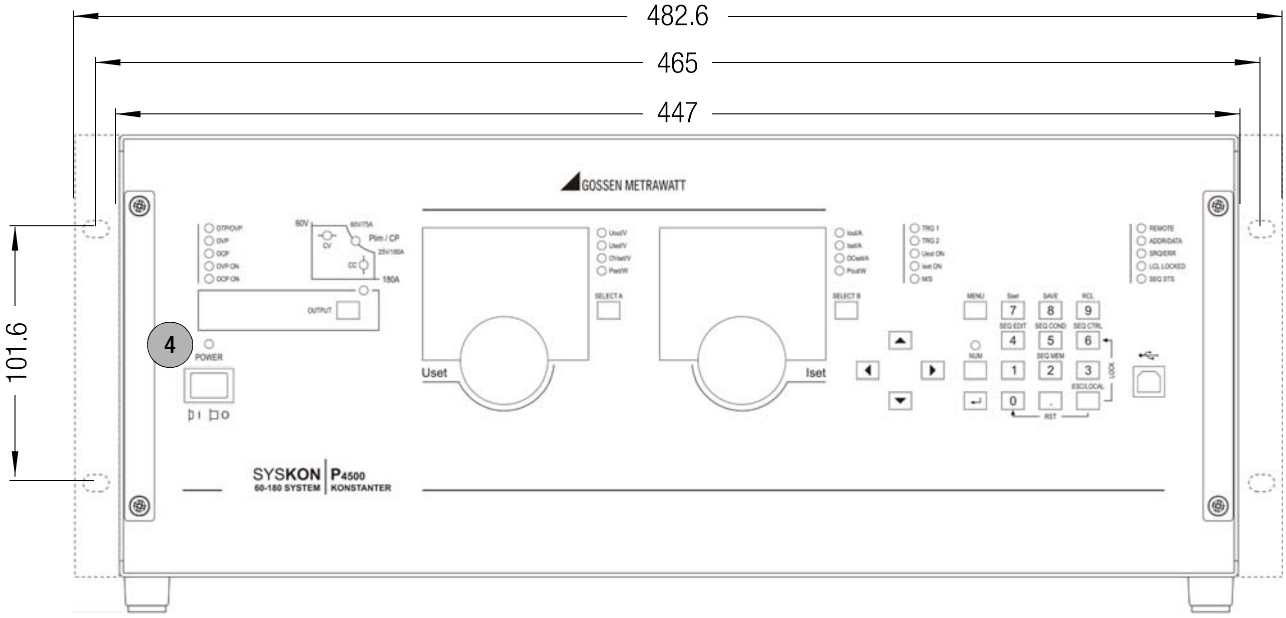
2.1 Dimensional Drawing SYSKON P500 / P800 / P1500

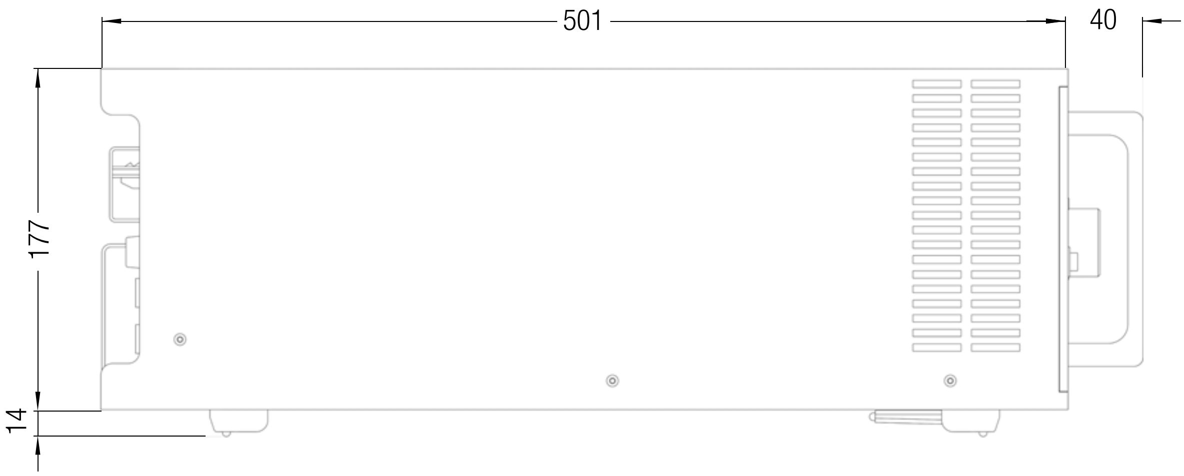


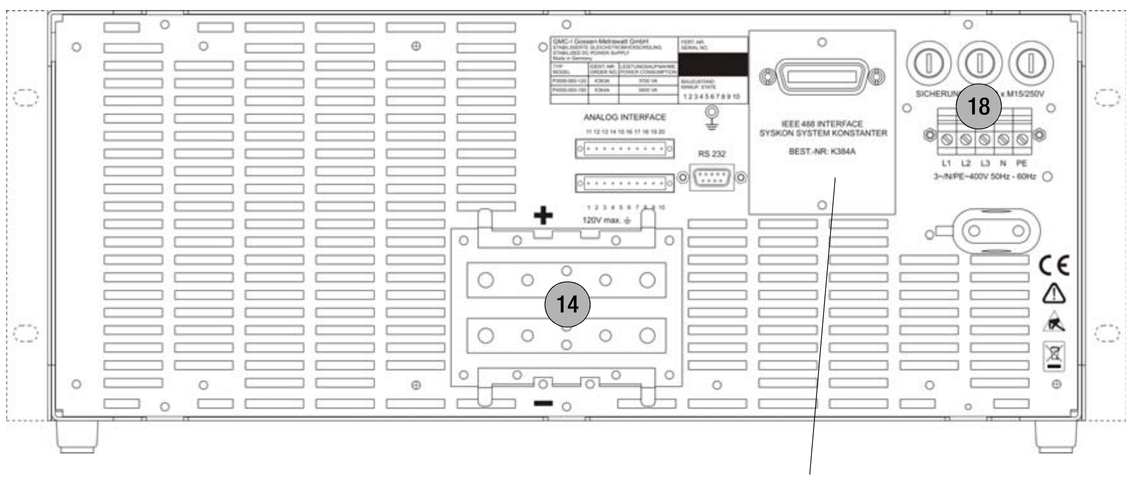
Installation position for optional IEEE-488 interface (material no. K384A).

All dimensions in mm

2.2 Dimensional Drawing SYSKON P3000 / P4500







Installation position for optional interface IEEE-488 (material no. K384A).

All dimensions in millimeter

2.3 Preparing for Operation

Note: Numbers in brackets make reference to the items listed in the dimensional drawing.

2.3.1 Installing the Optional GPIB Interface Module

Warning!

The device must be switched off when installing the interface module. **Remove the mains plug from the outlet.** The interface module may be damaged by electrostatic discharge. ESDS handling guidelines must be adhered to. Do not touch electrical contacts or components.

1. Unscrew the cover plate at the right-hand side of the rear housing panel.
2. Carefully remove the ribbon cable from the cable uptake and plug it in, being certain to observe coding as shown on the interface module.
3. Carefully insert the connected module into the opening and secure it with the previously removed cover plate screw.

2.3.2 Setup as Benchtop Device

The instrument is shipped as a benchtop device and the feet are already installed. The mounting tabs for installation to a 19" rack are shipped loose. The instrument can be set up as a benchtop device and placed into operation. Unimpaired ventilation of the instrument must be assured during setup.

2.3.3 Installation to a 19'' Device Cabinet

The SYSKON KONSTANTER housing allows for use as a benchtop instrument, as well as for installation to a 19'' rack.

The benchtop instrument can be quickly converted to a rack mount device:

1. Unscrew the handles at the front.
2. Pull out the filler strips at the sides and replace them with the included rack-mount fastening tabs.
3. Replace the front handles (if you prefer to leave the handles off, turn M4 screws with a maximum length of 8 mm into the threaded holes).
4. Unscrew the feet from the bottom of the housing.
5. Save all loose parts for possible future use.

Attention!

The instrument must be attached at both sides to guide rails inside the device cabinet. The guide rails, as well as the front panel mounting screws, are cabinet-specific and must be procured from your rack supplier.

2.3.4 Connection to the Mains

Warning!

Protective Grounding, PE Connection
The KONSTANTER may only be placed into operation after the protective conductor has been connected. Interruption or disconnection of the protective conductor may result in danger for the user.
The device is connected to the mains by means of a 3 conductor cable with mains plug.

Attention!

Before switching the SYSKON KONSTANTER on, it must be assured that available mains power complies with the supply power values specified at the mains connection on the back of the device.

SYSKON P500/P800/P1500: The device can be operated with either 115 or 230 V mains power. Full output power (1500 W) can be taken advantage of when operated with 230 V mains power. Due to resulting input current, only 750 W of output power can be supplied when operated with 115 V mains power.
SYSKON P3000/P4500: In order to exploit the full nominal power, the device must be operated with a 400 Volt 3-phase current system.

Integrated monitoring circuits detect mains power and limit output power in the event of overloading.

The instrument is connected to a mains outlet with earthing contact via the mains inlet connector [18] at the rear panel with the help of the included power cable (only included with the SYSKON P500/P800/P1500).

2.3.5 Connecting Power Consumers

The output leads are connected to the output terminal blocks [14] at the rear panel by means of ring-type cable lugs with the included screws. **(SYSKON P500/P800/P1500:** M6 x 10, **SYSKON P3000/P4500:** M8 x 12 and M6 x 10). In addition to this, 4 mm holes are also provided which are intended for the connection of any utilized measurement cables.

Connection:

- Remove the safety cap.
- Connect the output leads to the terminal blocks with the provided screws and washers.
- An adequate wire cross-section and correct polarity must be assured. It is advisable to twist the output leads and to identify polarity at both ends.
- Avoid exerting excessive force at the terminals.
- Align the leads to the openings in the safety cap.
- Snap the safety cap back into place.

In order to be able to take advantage of highly constant output voltage at the consumer even if long leads are used, sensing leads can be used to compensate for voltage drops within the output leads (see chapter 7).
The terminals for the sensing leads are located on the analog interface.

2.3.6 Connection to Computer Interfaces

Three interfaces are available on the instrument for computer-controlled operation.

The device is furnished with a USB port and an RS 232 interface as standard equipment.

A GPIB interface can be ordered as an optional module and installed as described. Installation at a later point in time is also possible.

The instrument cannot be remote controlled via more than one interface at a time. It is thus advisable to connect the desired interface only.

In order to avoid communications problems with the interfaces, only one interface should be connected to the computer. Problems may otherwise occur.

In order to assure that existing bus activity is not interfered with, all affected devices should be switched off while establishing the bus connection.

All of the interfaces have a common reference point (GND) which is connected to PE, and are isolated from the output in accordance with the specified electrical safety regulations.

a) **USB Port**
The type B USB plug is at the at the bottom right-hand side of the front panel. Appropriate USB drivers must be installed, which are on the included CD or can be downloaded from the Internet, see chapter 2.3.7.

b) **RS 232C Interface**
The socket connector for the RS 232 interface is on the instrument's rear panel. A 9-pin subminiature socket connector is used to this end.

RS 232C Interface: 9-pin subminiature socket connector DIN 41652

Connector pin assignments
Pin 2: TXD (transmit data)
Pin 3: RXD (receive data)
Pin 5: GND (ground)

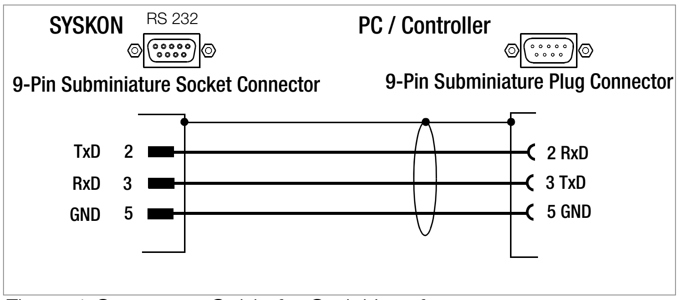


Figure 1:Connector Cable for Serial Interface

c) **GPIB or IEC Bus Interface (optional)**
This interface is optional and can be installed to the slot provided for this purpose on the rear panel.

IEEE 488/IEC 625 Interface Connection
24-pin IEEE 488 socket connector

IEEE 488/IEC 625 Interface Functions

SH1	– SOURCE HANDSHAKE
AH1	– ACCEPTOR HANDSHAKE
T6	– TALKER
L4	– LISTENER
TE0	No extended talker function
LE0	No extended listener function
SR1	– SERVICE REQUEST
RL1	– REMOTE / LOCAL
DC1	– DEVICE CLEAR
PP1	– PARALLEL POLL
DT1	– DEVICE TRIGGER
C0	– No controller function
E1 / 2	– Open collector driver
Codes / formats	Per IEEE 488.2

2.3.7 Driver update (USB device driver)

We recommend a driver update in the following cases:

- Replacement purchases of devices
(connecting new devices of the SYSKON range with a PC)
- retrofitting of interface cards
- firmware udate
- software update

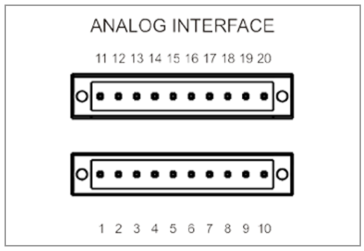
GMC-I Driver Control software can be downloaded from Gossen Metrawatt's website at:

www.gossenmetrawatt.com

The ZIP file can be unpacked in any desired directory. The setup file then appears in the directory. Installation is started by double clicking the setup file. A wizard guides you through the installation procedure.

2.3.8 Connecting the Analog Interface

The plug connection for the analog interface is located on the rear panel. Two 10-pin plug-in screw terminal connections are used to this end. The necessary connections for the selected analog control function can be made here. In order to keep cross interference with the analog signals to a minimum, it is advisable to use shielded connector cables. The individual signals are described under "Analog Interface".



2.4 Switching the Device On

After the described preparations have been completed, the device can be switched on. The mains switch is located at the bottom left-hand side of the front panel.

Start-Up Routine

After switching the device on, the POWER lamp [4] lights up and the fan is started. The microprocessor included in the device then starts a power-up test. The following operations are performed during the test routine (duration approximately 6 seconds):

- Reset all functional units (except battery-backed configuration memory)
- LED and display segment test
- Hardware/firmware version display, see chapter 2.4.1
- Line voltage range is detected, see chapter 2.4.2
- Initialization of the 2 (possibly 3) computer interfaces; if the device has been equipped with the optional "IEEE 488 interface", the selected IEC bus device address then appears briefly at the display (example: "Addr 12").
See chapter 6 main menu level SETUP DISPLAY & INTERFACE for changing the device address.
- Date display (internal clock)
- Time display (internal clock)
- Recall last settings if applicable
- Switch to (default after "*RST") display of measured values for voltage (Uout) and current (Iout)

After initial power-up, the device is set to its basic default configuration (see the table entitled "Adjustable Functions and Parameters" in chapter 10.1).

Upon shipment from the factory, the device is configured such that the setpoints for output voltage and current are set to zero, and the power output is set to off.
For further use, status after power on depends upon the selected device configuration.
This configuration is selected either manually with the help of the corresponding menu item, or by means of the POWER_ON command.

Attention!

Avoid switching the device on and off in a rapid, repeated fashion. This temporarily impairs the effectiveness of the inrush current limiting function, and may result in a blown fuse.

2.4.1 Table of Firmware Versions

Firmware Version	Memory Locations
Version 003	12 SETUP memory locations 1536 SEQUENCE memory locations
Version 004	15 SETUP memory locations 1700 SEQUENCE memory locations

2.4.2 Response after Power ON with Varying Line Voltage Ranges (230 V ↔ 115 V)

Up to and including Firmware Version 004

After „Power ON“, a distinction is made - on the basis of the line voltage detected - between the two available power ranges. When the line voltage is „low“, output power Pnom is reduced by half (see chapter 4.1).

The specified value „PSET < Pnom“ (and/or „PSET < Pnenn/2“ in the case of power derating), in turn, is the setting criterion for the function „Power control“. After an automatic change of Pnom it may be necessary to correct the PSET value for power control!

Power ON & Setting „Power_ON RST / SBY / RCL / ...“:

- „RST“ — Pnom is always readjusted in accordance with the detected line voltage.
- „SBY“, „RCL“ — A low line voltage always leads to a reduced Pnom value. If the device is subsequently switched on to a „high“ line voltage, the low Pnom value remains active until either:
  – a „RESET“ is performed (!)
  or
  – „Power“ is reconnected with parameter setting „POWER_ON RST“.

Changes between the line voltage ranges result in system messages, see Err AC-L and Err AC-H in chapter 11.

As from Firmware-Version 005

After „Power ON“, a distinction is made - on the basis of the line voltage detected - between the two available power ranges.

When the line voltage is „low“, output power is limited to approximately 55 % of the nominal power.
If the device is switched on in setting „POWER_ON RST“ at „low“ line voltage, the setting limit value is reduced to half the nominal power for parameter PSET.

The specified value „PSET < Pnom“ (and/or „PSET < Pnenn/2“ in the case of power derating), in turn, is the setting criterion for the function „Power control“.

Power ON & Setting „Power_ON RST / SBY / RCL / ...“:

- „RST“ — Pnom is always readjusted in accordance with the detected line voltage.
- „SBY“, „RCL“ — A low line voltage always leads to a reduced maximum output power. The setting limit values for parameter PSET, however, remain unchanged until either:
  – a memory recall of a corresponding device setting is performed
  or
  – „Power“ is reconnected with parameter setting „POWER_ON RST“.

Changes between the line voltage ranges result in system messages, see Err AC-L and Err AC-H in chapter 11.

3 Technical Description

Description

SYSKON KONSTANTERs (power factor control, single-output system power supplies) are manual and remote controllable DC power supplies for laboratory and system use. Thanks to modern switching controller technology, the devices are compact and lightweight despite high output power.

Active power factor control assures nearly sinusoidal mains input current.

The floating output features “safety separation” from the mains input as well as from the computer interfaces, and is classified as a safety extra-low voltage circuit (SELV) in accordance with VDE / IEC. Wide ranging nominal output power values are available from output voltage and output current.

The power output is voltage and current controlled with limiting to maximum withdrawable power.

Transition to the control modes is automatic in accordance with the selected setpoints and load circumstances.

The control loops are designed for short response times.

An automatically activated, dynamic sink (can be disabled) provides for quick discharging of the output capacitors.

Numerous protective functions and monitoring devices allow for ideal adaptation to actual conditions of use.

Features

The devices are generally equipped with a control panel and display, as well as an analog interface.

One USB port and one RS 232 interface are provided as standard equipment for integration into computer controlled systems. The drivers for the USB port are provided as accessories on the included CD ROM.

An IEEE 488 interface can be additionally installed to the device from the outside ,or retrofitted as an option.

Manual adjustment of voltage and current is accomplished by means of two rotary encoders with selectable resolution, or with the numeric keypad. Numerous additional functions can be accessed via keys.

Two 5-place digital LED displays read out measured values and settings. LEDs indicate the current operating mode, selected display parameters and the status of device and interface functions.

The analog interface makes it possible to adjust output voltage and current with the help of external control voltages. Monitor outputs read out an analog image of the voltage and current output quantities for further processing or additional displays.

These control inputs and monitor outputs can also be used to couple several devices for master-slave operation with parallel or series connection.

Two floating trigger inputs are available for controlling certain device functions. For example, they can be used to switch the output on and off, or to control sequences.

Furthermore, three signal outputs are included at the analog interface, two of which are floating. These can be activated depending upon various functions, and can thus be used to control external devices or sequences.

Applications Range

Konstanters are suitable for use wherever electronic modules with controlled direct voltage or controlled current need to be supplied with electrical power, especially in the fields of R&D, testing, production, test systems and training.

Thanks to their characteristic U-I-P curve, the devices have a broad working range, making it possible to cover a large range of applications with a single device.

Due to their short response times, SYSKON KONSTANTERs can be used for replication and simulation of onboard electrical systems, for example in automotive applications. Test signals specified in the corresponding standards can be generated. The fact that these voltage-current-time profiles can be saved to memory at the Konstanter for running independent sequences is highly advantageous. When used in test systems, it is thus possible to significantly reduce workload for the control computer. Further functions for test applications of this sort include the Min-Max function for acquiring extreme values and the tolerance band function which generates a signal when measured values do not lie within the specified tolerance limits.

The Konstanter thus serves as an autonomous test system for many applications.

Adjustable Functions (selection)

– Voltage and current setpoint values
– Voltage and current limit values (soft-limits)
– Activate / deactivate the output
– Overvoltage protection trigger value (OVP)
– Overcurrent protection trigger value (OCP)
– Delay time for reaction to overvoltage
– Selection of the desired reaction when OVP and OCP are triggered
– Delay time for reaction to overcurrent
– Performance after power on
– Reset device settings
– Save device settings
– Recall device settings, individually or sequentially
– Function selection for trigger input
– Configurable status and events management with enabling windows (via computer interface)
– Activate / deactivate digital displays

Retrievable Information (selection)

– Presently measured voltage and current values
– Minimum and maximum measured voltage and current values
– Current output power
– Current device settings
– Current device status (i.e. control mode, overtemperature etc.)
– Occurred events (i.e. mains failure, overtemperature, overvoltage, overload etc.)
– Device ID (via computer interface)

Protection and Additional Functions

– Sensor terminals protected against polarity reversal and automatic switching to auto-sensing
– Protection against excessive temperature
– Output protected against reverse polarity
– Front panel control disabling
– Backup battery for device settings memory
– Recognition of mains or phase failure
– Inrush current limiting

Performance After Power on

In the event of mains failure, it's important to specify which operating state the device will assume when power is restored. This may be extremely important if the device is used in long-term testing applications.

One of the following states can be selected:

– Reset = default setting (0 V, 0 A, output deactivated)
– Standby= last used configuration but with deactivated output
– Recall = last used configuration – same as when the instrument was last switched off, with active output if it was active prior to mains failure
– Recall a device configuration from setup memory

Set Output Voltage and Output Current

Output voltage and output current can also be adjusted using the rotary encoders or the numeric keypad if desired. The rotary encoders are used exclusively for adjusting voltage and current. The decimal place to be changed is selected with the scroll keys. Additional functions and parameters can be accessed and adjusted with the keys.

Switching the Input On and Off

The power output can be switched on and off by pressing the appropriate key, with a computer command or by applying a signal to the trigger input. When switched off, the output is highly resistive and is not electrically isolated from the power consumer. The LED on the key indicates status.

Protection and Additional Functions

A multitude of protection and additional functions have been integrated, for example:

- Limiting of the setting ranges for voltage and current
- Overvoltage protection (OVP) with adjustable response delay and reaction
- Overcurrent protection (OCP) with adjustable response delay and reaction
- Protection in the event of reversed polarity at the sensing leads
- Automatic switching to auto-sensing
- Protection against excessive temperature
- Output protected against reverse polarity
- Front panel control disabling
- Backup battery for device settings memory
- Mains failure detection
- Inrush current limiting
- Line voltage monitoring

Line Voltage Monitoring

To protect the device, power output is deactivated and disabled in the event of voltage dips or short-term interruptions. The device must be restarted with „Power ON".

Dynamic Sink

A dynamic sink is activated by the control loops as required for rapid discharging of the output capacitors.

This allows for short response times when switching to smaller setpoint values. Depending upon the application, the sink function can also be disabled.

Auto-Sensing

The device can be switched to sensing mode operation (remote sensing) in order to compensate for voltage drop at the output leads. Sensing lead terminals are available to this end at the analog interface. If the (–) negative sensing terminal is connected to the negative load point, the device is automatically switched to sensing mode operation. Maximum compensatable voltage drop is 1 V per output lead.

Front Panel Control Disabling

The controls can be disabled to prevent unauthorized operation by pressing the appropriate key, with a computer command or by applying a signal to the trigger input.

Analog Control Inputs

Voltage and current can also be adjusted by via the control inputs at the analog interface. A 5 V signal corresponds to 100% of the respective nominal value.

These inputs can be switched on and off using the keys, or with computer commands.

The controlled output quantity is the sum of the digital setpoint value and the specified value at the control input.

This function makes it possible to superimpose these control signals onto the output quantities.

Monitor Outputs

The actual values for output voltage and current can be acquired at the monitor outputs as a standardized signal (10 V corresponds to 100% nominal value).

Trigger Inputs

Two floating trigger inputs are available for controlling device functions. The following trigger input assignments can be selected:

– output = Switch the power output on and off
– local lock = Disable controls
– SQS = (**se**q**u**ence **s**tep) Step-by-step control of a stored sequence
– sequence = Start / stop the sequence function
– Analog input = Activate / deactivate the analog control inputs

Signal Outputs

Programmable Control Outputs

The analog interface is equipped with three digital control outputs for status messages to external monitoring devices, for switching external components on and off, or for coupling purposes.

The status of these outputs can be defined either directly, or depending upon the following device statuses:

– Output on or off
– Voltage or current regulation
– Sequence function running or finished
– SSET signal status for the sequence function
– Limit value message for the measuring function (tolerance band)

Min-Max Measured Value Memory

The Min-Max function automatically acquires and saves minimum and maximum voltage and current values.

Tolerance Band (in combination with Min-Max function)

Measured output values can be continuously compared with stored upper and lower tolerance band values. Evaluation is possible via the programmable control outputs.

Memory

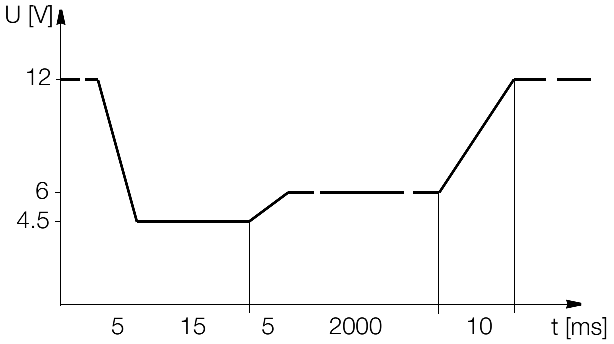
The memory function makes it possible to save and recall device configurations using a battery-backed memory module.
The memory module is equipped with two storage areas:

– Setup memory: 12/15 memory locations for complete configurations

– Sequence memory: 1536/1700 memory locations for the following sequence parameters: voltage setpoint USET, current setpoint ISET, dwell time TSET and function request FSET, with the ability to invoke subsequences

Sample Application

Generation of a characteristic voltage curve in an automotive electrical system when starting the engine



Note:

The drop times can be influenced by the input impedance of the DUT.

Balancing Function (adjust)

Offset and final values for setting and measured values for output quantities voltage and current are balanced digitally in the device.
The user can execute balancing as required with this function.

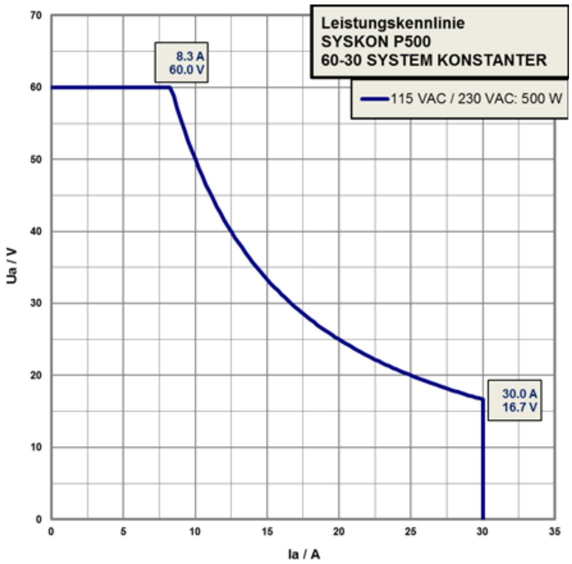
DAkkS Calibration Certificate

All SYSKON Konstanters are shipped with a DAkkS calibration certificate issued by our DAkkS test laboratory.

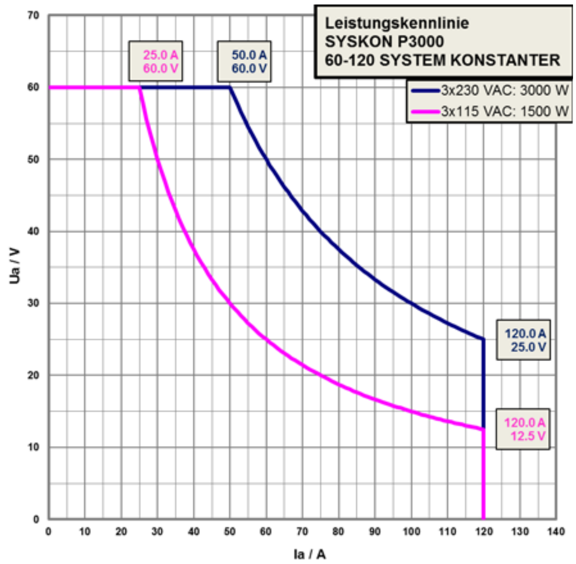
4 Technical Data

4.1 General Data

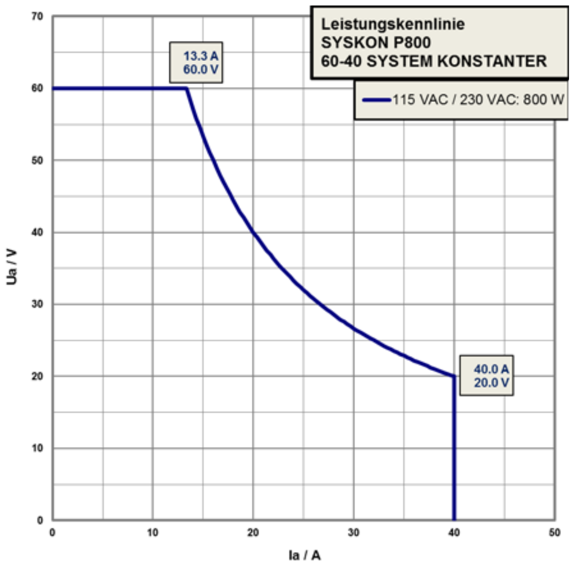
Output Operating Ranges, Characteristic U-I-P Curve SYSKON P500



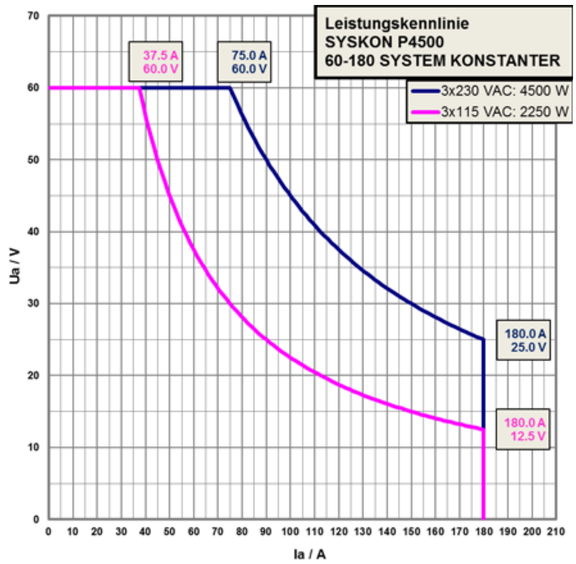
Output Operating Ranges, Characteristic U-I-P Curve SYSKON P3000



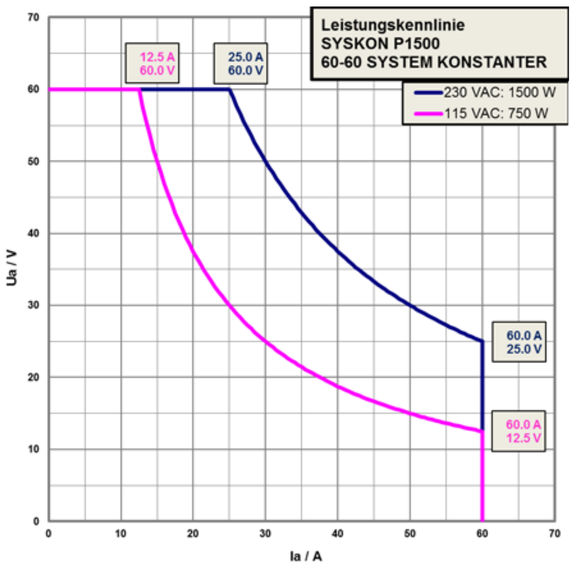
Output Operating Ranges, Characteristic U-I-P Curve SYSKON P800



Output Operating Ranges, Characteristic U-I-P Curve SYSKON P4500



Output Operating Ranges, Characteristic U-I-P Curve SYSKON P1500



Output

Regulator type	Primary switched-mode regulator
Operating modes	Adjustable constant voltage / constant current source with automatic sharp transition
Output insulation	Floating output with “safe electrical separation” from the mains input and computer interfaces
Allowable potential, output–ground	Max. 240 V DC

Capacitance, output–ground (housing)

SYSKON P500	typically 1000 nF
SYSKON P800	typically 1000 nF
SYSKON P1500	typically 1000 nF
SYSKON P3000	typically 1000 nF
SYSKON P4500	typically 1000 nF

Analog Interface

Functions	– Auto-sensing mode – 2 programmable trigger inputs – 3 programmable signal outputs – Voltage control input (0 ... 5 V) – Current control input (0 ... 5 V) – Voltage monitor output (0 ... 10 V) – Current monitor output (0 ... 10 V) – Master-slave parallel operation – Master-slave series operation – Auxiliary power output: 15 V / 60 mA

Computer Interfaces

- IEC-625 / IEEE 488 interface (optional)

- RS 232 interface

Transmission mode	asynchronous
Transmission speed	1200 to 115,200 baud, adjustable

- USB port

USB port: 4-pin, type B
USB 1.1 compatible with USB 2.0
Connector pin assignments 1: VCC, 2: D-, 3: D+, 4: GND

Transmission speed	9600 to 115,200 baud, adjustable

Power supply

Line voltage	115/230 V ~ + 10 / – 15%; 47 to 63 Hz
Inrush current	Max. 50 A_s
Mains fuse	SYSKON P500/P800/P1500: 1 x M 15 A / 250 V (6.3 x 32 mm), UL SYSKON P3000/4500: 3 x M15 A/250 V

Electrical Safety

Safety class	I
Measuring category	II for mains input I for output and interfaces
Fouling factor	2
Earth leakage current	< 2.5 mA_{RMS}

Electrical isolation	Test voltage
Output – mains	2.2 kV ~
Output – bus/ground	1.4 kV ~
Mains – bus/ground	2.2 kV –
Bus – ground	No electrical isolation

Applicated Standards

IEC 61010-1:2010
DIN EN 61010-1:2010
VDE 0411-1:2011
EN 61326

4.1.1 Electromagnetic Compatibility

SYSKON P500/P800/P1500

Generic standard	EN 61326-1: October 2006
Interference emission	EN 55022: class B
Interference immunity	EN 61000-4-2: feature A EN 61000-4-3: feature B EN 61000-4-4: feature A EN 61000-4-5: feature A EN 61000-4-6: feature A EN 61000-4-8: feature A EN 61000-4-11: feature A

SYSKON P3000/4500

Generic standard	EN 61326-1: October 2006
Interference emission	EN 55022: class A *
Interference immunity	EN 61000-4-2: feature B EN 61000-4-3: feature A EN 61000-4-4: feature B EN 61000-4-5: feature B EN 61000-4-6: feature A EN 61000-4-8: feature A EN 61000-4-11: feature B

* **Note:**
Approved for the deployment in industrial environment. The device may cause radio interferences in domestic areas.

4.1.2 Ambient Conditions

Temperature range	Operation:	0 to 40° C
	Storage:	–25 to +75° C
Atmospheric humidity	Operation:	≤ 75% rel. humidity, no condensation allowed
	Storage:	≤ 65% rel. humidity
Cooling	With integrated fan (temperature controlled)	
	Inlet vent:	Side panel
	Outlet vent:	Rear panel
Operating noise	Noise pressure level at a distance of 30 cm with fan set to low / high	
	Front	17 / 28 dBA
	Rear	22 / 32 dBA
	Left	17 / 28 dBA
	Right	20 / 31 dBA

4.2 Mechanical Data

Protection IP 00 for device and interface connections
IP 20 for housing

Table Excerpt Regarding Significance of IP Codes

IP XY (1st char. X)	Protection against penetration by solid particles	IP XY (2nd char. Y)	Protection against penetration by water
0	Not protected	0	Not protected
1	≥ 50.0 mm dia.	1	Vertical dripping
2	≥ 12.5 mm dia.	2	Dripping (15° inclination)

Design Benchtop device, suitable for installation to 19" cabinets

Article No.	Designation	Dimensions (W x H x D)	Weight
K346A	SYSKON P500-060-030	19" x 2 HE 447 x 102 (88) x 541 (501) mm	10 kg
K347A	SYSKON P800-060-040	19" x 2 HE 447 x 102 (88) x 541 (501) mm	10 kg
K353A	SYSKON P1500-060-060	19" x 2 HE 447 x 102 (88) x 541 (501) mm	10 kg
K363A	SYSKON P3000-060-120	19" x 4 HE 447 x 191 (177) x 541 (501) mm	16 kg
K364A	SYSKON P4500-060-180	19" x 4 HE 447 x 191 (177) x 541 (501) mm	20 kg
K384A	IEEE 488 interface (optional)		Approx. 0.14 kg

HE = standard height units

4.2.1 Terminals (rear panel)

Mains input SYSKON P1500:
10 A IEC inlet plug with earthing contact (L + N + PE)

SYSKON P3000/4500:
Connection terminals (min. 16 A) (L1 + L2 + L3 + N + PE)

Output SYSKON P1500:
Terminal blocks with thread for M6 screws and 4 mm dia. holes

SYSKON P3000/4500:
Terminal blocks with thread for M8 and M6 screws and 4 mm dia. holes

Analog interface / sensing leads Double-row plug connector with two 10-pole screw terminals

4.3 Electrical Data

Article Number / Type		K346A SYSKON P500-060-030	K347A SYSKON P800-060-040	K353A SYSKON P1500-060-060
Nominal Output Data	Voltage setting range	0 ... 60 V	0 ... 60 V	0 to 60 V
	Current setting range	0 ... 30 A	0 ... 40 A	0 to 60 A
	Power	max. 500 W	max. 800 W	Max. 1500 W
Output Characteristics (ppm and percentage values make reference to the respective setting or measured value)				
Setting resolution	Voltage	1 mV	1 mV	1 mV
	Current	1 mA	1 mA	1 mA
Setting accuracy (at 23 ±5 °C) Auto-sensing mode	Voltage	0.05 % + 30 mV	0.05 % + 30 mV	0.05% + 30 mV
Without auto-sensing		0.05 % + 48 mV	0.05 % + 48 mV	0.05% + 48 mV
	Current	0.05 % + 90 mA	0.05 % + 90 mA	0.05% + 90 mA
Temperature coefficient	Voltage	100 ppm	100 ppm	100 ppm
for Δ / K setting	Current	100 ppm	100 ppm	100 ppm
Setting accuracy via analog interface (at 23 ±5 °C)	Voltage	0.6 % + 120 mV	0.6 % + 120 mV	0.6% + 120 mV
$U_{setnom}/U_{setanalog}$ = 12; $I_{setnom}/I_{setanalog}$ = 12/24/36	Current	0.6 % + 120 mA	0.6 % + 120 mA	1.2% + 120 mA
Static system deviation Auto-sensing mode	Voltage	30 mV (< 500 µV/A)	30 mV (< 500 µV/A)	30 mV (< 500 µV/A)
at 100% load fluctuation Without auto-sensing		48 mV (< 800 µV/A;)	48 mV (< 800 µV/A;)	48 mV (< 800 µV/A;)
	Current	30 mA (< 500 µA/V)	30 mA (< 500 µA/V)	30 mA (< 500 µA/V)
Static system deviation	Voltage	5 mV	5 mV	5 mV
with 10% line voltage fluctuation	Current	5 mA	5 mA	5 mA
Residual ripple Voltage	Ripple: 10 Hz to 20 kHz	40 mV_{ss}	40 mV_{ss}	40 mV_{ss}
	Ripple: 10 Hz to 1 MHz	50 mV_{ss}	50 mV_{ss}	50 mV_{ss}
	Ripple + noise: 10 Hz to 10 MHz	60 mV_{ss} / 6 mV_{eff}	60 mV_{ss} / 6 mV_{eff}	60 mV_{ss} / 6 mV_{RMS}
Current	Ripple + noise: 10 Hz to 10 MHz	50 mA_{eff}	50 mA_{eff}	50 mA_{RMS}
	Tolerance	120 mV	120 mV	120 mV
Output voltage transient recovery time with sudden	ΔI = 10%	100 µs	100 µs	100 µs
load variation within range of 20 to 100% I_{nom}	ΔI = + 80% + approx. 800 A/ms	600 µs	500 µs	400 µs
and 20 to 100% U_{nom}	ΔI = – 80 % + approx. 1200 A/ms	950 µs	650 µs	500 µs
Output voltage over and undershooting with sudden				
load variation within a range of 20 to 100% I_{nom}	ΔI = 10%	150 mV	150 mV	150 mV
and 20 to 100% U_{nom}	ΔI = 80%	500 mV	550 mV	700 mV
Setting time for output voltage [1]	Tolerance	120 mV	120 mV	120 mV
where Uset step = 0 V → 60 V	No-load; nominal load [2]	2 ms / 2 ms	2 ms / 2 ms	2 ms / 2 ms
where Uset step = 60 V → 1 V	No-load; nominal load [2]	70 ms / 20 ms	70 ms / 15 ms	70 ms / 11ms
where Uset step = 0 V → 25 V	No-load; nominal load [2]	1.4 ms / 1.4 ms	1.4 ms / 1.4 ms	1.4 ms / 1.4 ms
where Uset step = 25 V → 1 V	No-load; nominal load [2]	16 ms / 5 ms	16 ms / 3 ms	16 ms / 3 ms
Output capacitor	Nominal value	2020 µF	2020 µF	2020 µF
Sink (continuous power)	Power	40 W – 65 W	40 W – 65 W	40 to 65 W
Measuring Function				
Measuring Range	Voltage	– 16.384 … + 98.300 V	– 16.384 … + 98.300 V	– 16.384 to + 98.300 V
	Current	– 32.766 … + 98.300 A	– 32.766 … + 98.300 A	– 2.766 to + 98.300 A
	Power	U x I	U x I	U x I
Measuring resolution	Voltage	2 mV	2 mV	2 mV
	Current	2 mA	2 mA	2 mA
	Power	100 mW	100 mW	100 mW
Measuring accuracy (at 23 ± 5 °C)	Voltage	0.05 % + 30 mV	0.05 % + 30 mV	0.05% + 30 mV
	Current	0.4 % + 90 mA	0.4 % + 90 mA	0.4% + 90 mA
	Power	0.5 % + 1 W	0.5 % + 1 W	0.5% + 1 W
Measured value temperature coefficient Δ / K	Voltage	50 ppm + 0.4 mV	50 ppm + 0.4 mV	0.4 mV + 50 ppm
	Current	100 ppm + 1 mA	100 ppm + 1 mA	1 mA + 100 ppm
Measuring accuracy (at 23 ± 5 °C) at analog interface	Voltage	0.4 % + 120 mV	0.4 % + 120 mV	0.4 % + 120 mV
$U_{actualnom}$ / $U_{actualanalog}$ = 6; $I_{actualnom}$ / $I_{actualanalog}$ = 6/12/18	Current	0.5 % + 180 mA	0.5 % + 180 mA	1.2 % + 180 mA
Protection and Additional Functions				
Output overvoltage protection Trigger value	Setting Range	3 … 80 V	3 … 80 V	3 to 80 V
	Setting resolution	20 mV	20 mV	20 mV
	Setting accuracy	±150 mV –10 mΩ x I_a	±150 mV –20 mΩ x I_a	±150 mV – 10 mΩ x I_a
Response time		200 µs	200 µs	200 µs
Output overcurrent protection Trigger value	Setting Range	1.5 … 40 A	2 … 53 A	3 to 80 A
	Setting resolution	20 mA	20 mA	20 mA
	Setting accuracy	–(1% + 350 mA) – 20 mA/V x U_a	–(1% + 350 mA) – 20 mA/V x U_a	–(1% + 350 mA) – 20 mA/V x U_a
Response time		200 µs	200 µs	200 µs
Reverse polarity protection load capacity	Continuous	30 A	40 A	60 A
Reverse voltage withstand capacity	Continuous	70 V –	70 V –	70 V –
Auto-sensing mode Compensatable voltage drop	Per output lead	1 V	1 V	1 V
General				
Power supply with 230 V~ nominal line voltage	Line voltage	**230 V~** + 10 / – 15 %,	**230 V~** + 10 / – 15 %,	**230 V~** + 10 / – 15%,
Power consumption	At nominal load, 100%	47 … 63 Hz	47 … 63 Hz	47 to 63 Hz
	At no load	700 VA; 650 W	1050 VA; 1000 W	1925 VA; 1865 W
		96 VA; 37 W	96 VA; 37 W	96 VA; 37 W
Power supply with 115 V~ nominal line voltage	Line voltage	**115 V~** + 10 / – 15 %,	**115 V~** + 10 / – 15 %,	**115 V~** + 10 / – 15%,
Power consumption	At nominal load, 50%	47 … 63 Hz	47 … 63 Hz	47 to 63 Hz
	At no load	800 VA; 750 W	1175 VA; 1150 W	1125 VA; 1100 W
		55 VA; 36 W	55 VA; 36 W	55 VA; 36 W
Max. power loss	At a nominal load 500 W/800 W/1500 W (230 V~)	150 W	200 W	365 W
	At a nominal load 500 W/800 W/750 W (115 V~)	250 W	350 W	350 W
Efficiency	At a nominal load 500 W/800 W/1500 W (230 V~)	77 %	80 %	80%
	At a nominal load 500 W/800 W/750 W (115 V~)	66 %	70 %	68%
Switching frequency, PFC / DC/DC	Typical	47 kHz / 230 kHz	47 kHz / 230 kHz	47 kHz / 230 kHz
Inrush current	Max.	50 A_s	50 A_s	50 A_s
Mains fuse (6.3 x 32 mm, UL)		1 x M 15 A / 250 V	1 x M 15 A / 250 V	1 x M 15 A / 250 V
MTBF (mean time between failures)	at 40 °C	> 50,000 h	> 50,000 h	> 50,000 hours

[1] at maximum current setting not including processing time for the previous voltage setting command

[2] Nominal load: Rload = $Uset^2$ / Pnom

Article Number / Type			K363A SYSKON P3000-060-120	K364A SYSKON P4500-060-180
Nominal Output Data		Voltage setting range	0 ... 60 V	0 ... 60 V
		Current setting range	0 ... 120 A	0 ... 180 A
		Power	max. 3000 W	max. 4500 W
Output Characteristics (ppm and percentage values make reference to the respective setting or measured value)				
Setting resolution		Voltage	1 mV	1 mV
		Current	2 mA	3.125 mA
Setting accuracy (at 23 ±5 °C)	Auto-sensing mode	Voltage	0.07 % + 48 mV	0.1 % + 48 mV
	Without auto-sensing		0.07 % + 60 mV	0.1 % + 60 mV
		Current	0.1 % + 135 mA	0.15 % + 180 mA
Temperature coefficient		Voltage	100 ppm	100 ppm
for Δ / K setting		Current	100 ppm	100 ppm
Setting accuracy via analog interface (at 23 ±5 °C)		Voltage	0.6 % + 150 mV	0.6 % + 150 mV
$U_{setnom}/U_{setanalog}$ = 12; $I_{setnom}/I_{setanalog}$ = 12/24/36		Current	1.2 % + 180 mA	1.2 % + 240 mA
Static system deviation	Auto-sensing mode	Voltage	60 mV (< 500 µV/A)	90 mV (< 500 µV/A)
at 100% load fluctuation	Without auto-sensing		96 mV (< 800 µV/A)	144 mV (< 800 µV/A)
		Current	60 mA (< 1000 µA/V)	90 mA (< 1500 µA/V)
Static system deviation		Voltage	7 mV	10 mV
with 10% line voltage fluctuation		Current	30 mA	60 mA
Residual ripple	Voltage	Ripple: 10 Hz to 20 kHz	60 mV_{ss}	80 mV_{ss}
		Ripple: 10 Hz to 1 MHz	75 mV_{ss}	100 mV_{ss}
		Ripple + noise: 10 Hz to 10 MHz	90 mV_{ss} / 10 mV_{eff}	120 mV_{ss} / 15 mV_{eff}
	Current	Ripple + noise: 10 Hz to 10 MHz	70 mA_{eff}	100 mA_{eff}
		Tolerance	120 mV	120 mV
Output voltage transient recovery time with sudden		ΔI = 10%	400 µs	500 µs
load variation within range of 20 to 100% I_{nom}		ΔI = + 80% + approx. 800 A/ms	1200 µs	1600 µs
and 20 to 100% U_{nom}		ΔI = – 80 % + approx. 1200 A/ms	1900 µs	2500 µs
Output voltage over and undershooting with sudden				
load variation within a range of 20 to 100% I_{nom}		ΔI = 10%	200 mV	250 mV
and 20 to 100% U_{nom}		ΔI = 80%	1200 mV	1300 mV
Setting time for output voltage [1]		Tolerance	120 mV	120 mV
where Uset step = 0 V → 60 V		No-load; nominal load [2]	4 ms / 15 ms	7 ms / 19 ms
where Uset step = 60 V → 1 V		No-load; nominal load [2]	70 ms / 11 ms	70 ms / 11 ms
where Uset step = 0 V → 25 V		No-load; nominal load [2]	1.2 ms / 6 ms	2.4 ms / 11 ms
where Uset step = 25 V → 1 V		No-load; nominal load [2]	16 ms / 6 ms	16 ms / 6 ms
Output capacitor		Nominal value	4040 µF	6060 µF
Sink (continuous power)		Power	80 W – 130 W	120 W – 195 W
Measuring Function				
Measuring Range		Voltage	– 16.384 … + 98.300 V	– 16.384 … + 98.300 V
		Current	– 65.532 … + 196.600 A	– 98.298 … + 294.900 A
		Power	U x I	U x I
Measuring resolution		Voltage	2 mV	2 mV
		Current	4 mA	6 mA
		Power	100 mW	100 mW
Measuring accuracy (at 23 ± 5 °C)		Voltage	0.07 % + 48 mV	0.1 % + 48 mV
		Current	0.6 % + 120 mA	0.8 % + 180 mA
		Power	0.7 % + 2 W	1 % + 3 W
Measured value temperature coefficient Δ / K		Voltage	50 ppm + 0.6 mV	50 ppm + 0.8 mV
		Current	100 ppm + 2 mA	100 ppm + 3 mA
Measuring accuracy (at 23 ± 5 °C) at analog interface		Voltage	0.6 % + 180 mV	0.8 % + 180 mV
$U_{actualnom}$ / $U_{actualanalog}$ = 6; $I_{actualnom}$ / $I_{actualanalog}$ = 6/12/18		Current	1.2 % + 240 mA	1.2 % + 300 mA
Protection and Additional Functions				
Output overvoltage protection	Trigger value	Setting Range	3 … 80 V	3 … 80 V
		Setting resolution	20 mV	20 mV
		Setting accuracy	±150 mV –20 mΩ x I_a	±150 mV –20 mΩ x I_a
	Response time		200 µs	200 µs
Output overcurrent protection	Trigger value	Setting Range	6 … 160 A	9 … 240 A
		Setting resolution	50 mA	100 mA
		Setting accuracy	–(1% + 500 mA) – 40 mA/V x U_a	–(1% + 700 mA) – 60 mA/V x U_a
	Response time		200 µs	200 µs
Reverse polarity protection load capacity		Continuous	120 A	180 A
Reverse voltage withstand capacity		Continuous	70 V –	70 V –
Auto-sensing mode	Compensatable voltage drop	Per output lead	1 V	1 V
General				
Power supply with 230 V~ nominal line voltage		Line voltage	3x230/400 V~ + 10 / – 15 %	3x230/400 V~ + 10 / – 15 %
			47 … 63 Hz	47 … 63 Hz
Power consumption		At nominal load, 100%	3810 VA; 3710 W	5660 VA; 5500 W
		At no load	100 VA; 45 W	110 VA; 55 W
Power supply with 115 V~ nominal line voltage		Line voltage	3x115/200 V~ + 10 / – 15 %	3x115/200 V~ + 10 / – 15 %
			47 … 63 Hz	47 … 63 Hz
Power consumption		At nominal load, 50%	2215 VA; 2180 W	3305 VA; 3255 W
		At no load	73 VA; 48 W	92 VA; 60 W
Max. power loss		At a nominal load 3000 W/4500 W (230 V~)	710 W	1100 W
		At a nominal load 1500 W/2250 W (115 V~)	680 W	1030 W
Efficiency		At a nominal load 3000 W/4500 W (230 V~)	81 %	82 %
		At a nominal load 1500 W/2250 W (115 V~)	69 %	69 %
Switching frequency, PFC / DC/DC		Typical	47 kHz / 230 kHz	47 kHz / 230 kHz
Inrush current		Max.	50 A_s	50 A_s
Mains fuse (6.3 x 32 mm, UL)			3 x M 15 A / 250 V	3 x M 15 A / 250 V
MTBF (mean time between failures)		at 40 °C	> 40,000 hours	> 30,000 hours

1) at maximum current setting not including processing time for the previous voltage setting command

2) Nominal load: Rload = $Uset^2$ / Pnom

4.3.1 Reference Conditions

Ambient temperature	23 °C ±2 K
Relative humidity	40 ... 60 %
Warm-up time	30 minutes

Output operating characteristics (ppm and percentage specifications refer to the respective setting and/or measured value)

5 Controls, Display Elements and Terminals

5.1 Front Panel SYSKON P500 / P800 / P1500

Control Mode Status Display

CV LED lights up — Constant voltage regulating mode: Uout ≈ Uset
LED **Plim / CP*** lights up — **yellow:** Pout > Pnom (OL) **green*:** PSET < Pnom progr. (CP)
CC LED lights up — Constant current regulating mode: Iout ≈ Iset

Protective Functions and Status Displays

Events:

OTP/OVP LED lights up — Overtemperature protection triggered or output voltage ≥ 80 V exceeded, ⇨ OUTPUT = off
OVP LED lights up — Overvoltage detection triggered, oUSEt and oUdLY parameter values exceeded (prerequisite: oUP parameter = on) ⇨ OUTPUT = off
OCP LED lights up — Overcurrent detection triggered, ocSEt and ocdLY parameters exceeded (prerequisite: ocP parameter = on) ⇨ OUTPUT = off

Settings:

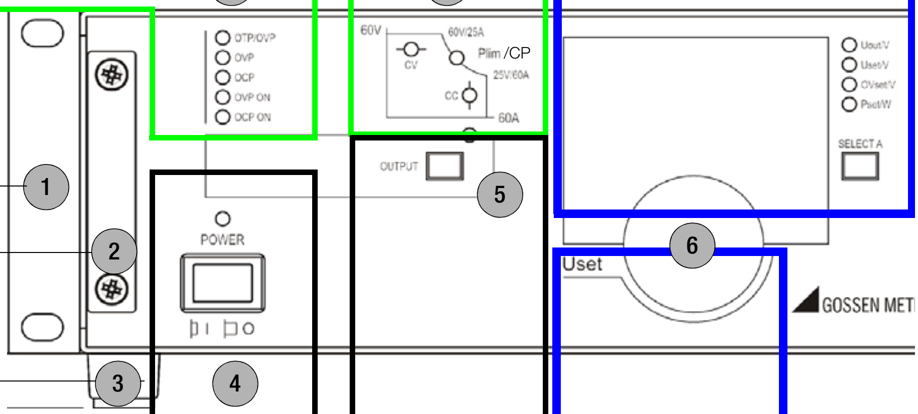
OVP ON LED lights up — Overvoltage shutdown is activated (oUP parameter in device setup menu = on)
OCP ON LED lights up — Overcurrent shutdown is activated (ocP parameter in device setup menu = on)

Display A

Standard display: measured voltage value Uout, display function is changed by pressing the SELECT A key or by turning the rotary knob. Adjust resolution (select decimal place) with the ◁ and ▷ scroll keys

Select A

Display selection:
Uout → Uset → OVset → Pset



Mains Switch

POWER LED lights up — Device is switched on
POWER switch — Switches the device on and off

Power Output On/Off Key

OUTPUT LED lights up — Output is active
OUTPUT switch — Switches the power output on and off

Rotary Encoder for Voltage

Voltage setpoint Uset – adjust output voltage Uset
Condition: UL_L (lower setting limit) ≤ Uset ≤ UL_H (upper setting limit)

When the rotary encoder is activated the display is switched to Uset (LED) and the cursor becomes active – the selected decimal place blinks at the display and can be selected with the ◁ and ▷ scroll keys.
The new setpoint becomes effective immediately.

Uset adjusting alternatives	**Activate by turning the rotary encoder, or select with Select A Uset**	
Scroll keys	◁ ▷: select decimal place	△▽: immediately increase or reduce Uset
Numeric keypad	Entry of numeric values, Uset LED blinks	Execute with ↵, or abort with ESC

* valid as from revision level 02 and firmware version 004. In the case of hardware revision level < 02, the LED lights up yellow in both cases.

Display B

Standard display: measured current value Iout, display function is changed by pressing the SELECT A key or by turning the rotary knob. Adjust resolution (select decimal place) with the ◁ and ▷ scroll keys.

Select B

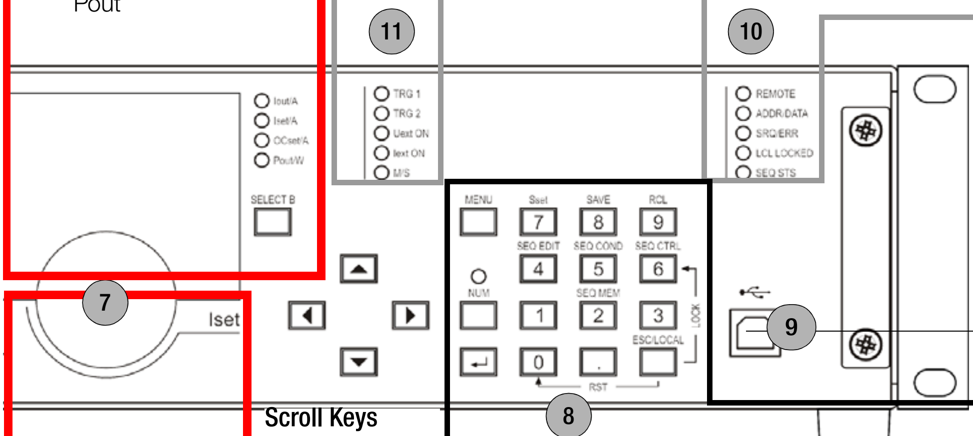
Display selection:
Iout → Iset → OCset → Pout

Status Displays

TRG1 LED lights up	Trigger signal 1 is active
TRG2 LED lights up	Trigger signal 2 is active
Uext ON LED lights up	Voltage input via analog interface is active
Iext ON LED lights up	Current input via analog interface is active
M/S LED lights up	Master-slave function

Device Status Displays

REMOTE LED lights up	Remote control is active
ADDR/DATA LED lights up	Addressing / data transmission is active
SRQ/ERR LED lights up	Service request / error
LCL LOCKED LED lights up	Control panel is disabled
SEQ STS LED lights up	Sequence function in HOLD status
blinks	Sequence is active (RUN)



Computer Interface

USB port

Scroll Keys

△ Increase Uset, Iset or parameter values
▽ Reduce Uset, Iset or parameter values
◁ Select entry position or scroll within the main menu level
▷ Select entry position or scroll within the main menu level

Numeric Keypad – Menu Functions

MENU	Adjustment of parameters and functions
Sset	Switching function: display and adjust signal level
SAVE	Save basic device settings (device parameters)
RCL	Recall basic device settings
SEQ ...	Sequence functions: **EDIT**, **COND**ITION, **C**ON**TR**O**L**, **MEM**ORY
NUM	Numeric entry, if active the ENTER LED lights up:
↵	transfer setting value or acknowledge selection
ESC/LOCAL	Return from menu level to standard display, abort of entry, ...
Lock	ESC/LOCAL + SEQ CTRL: disable control panel, press and hold ESC longer than 4 seconds: enable control panel
RST	ESC/LOCAL + 0: reset device settings to default values

Rotary Encoder for Current

Current setpoint Iset – adjust output current setpoint

Condition: IL_L (lower setting limit) ≤ Iset ≤ IL_H (upper setting limit)

When the rotary encoder is activated, the display is switched to Iset (LED) and the cursor becomes active – the selected decimal place blinks at the display and can be selected with the ◁ and ▷ scroll keys The new setpoint becomes effective immediately.

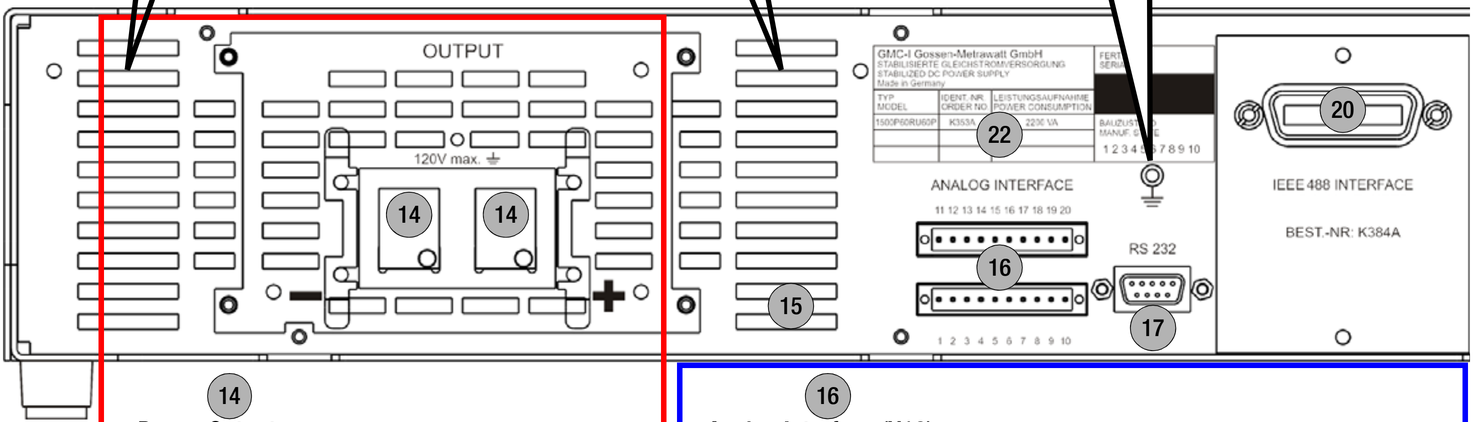
Iset adjusting alternatives	**Activate by turning the rotary encoder, or select with Select B Iset**	
Scroll keys	◁ ▷: select decimal place	△▽: immediately increase or reduce Iset
Numeric keypad	Entry of numeric values, Uset LED blinks	Execute with ↵, or abort with ESC

Air Vents

In order to assure adequate cooling of the device, the outlet vents for the integrated fans may not be covered.

Ground Terminal (earth terminal)

The output or cable shields can be grounded here if shielded cables or control cables are used for the analog interface.



14 Power Output

Terminals for connecting the power consumer.

This is a floating output and can be grounded with the positive or the negative pole.

Output connections may only be connected and disconnected when the output is inactive (OUTPUT OFF)! Danger of arcing!

Connecting the Power Consumer

The output leads are connected to the terminal blocks by means of ring-type cable lugs with the included M6 x 10 screws. Measurement cables can be additionally connected to the 4 mm holes.

- Remove the safety cap.
- Connect the output leads to the terminal blocks with the provided screws and washers.
- An adequate wire cross-section and correct polarity must be assured. It is advisable to twist the output leads and to identify polarity at both ends.
- Avoid exerting excessive force at the terminals.
- Align the leads to the openings in the safety cap.
- Snap the safety cap back into place.

In order to prevent danger during use, shock-proof connector cables must be used when connecting power consumers.

16 Analog Interface (X13)

- Remote control for output voltage and current
- External measurement of output voltage and current
- Connection of sensing leads in order to compensate for voltage drops in the output leads
- Linking of several devices for master-slave operation
- Vary internal output resistance
- Control of a selected device function via the floating trigger input

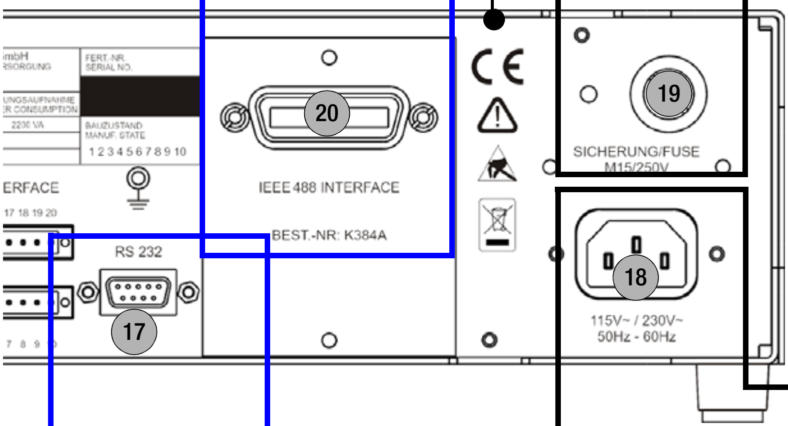
Terminal		Allocation	Meaning
Bottom Row of Terminals	1	TRG 1 +	Trigger input 1, plus
	2	TRG 1 –	Trigger input 1, minus
	3	TRG 2 +	Trigger input 2, plus
	4	TRG 2 –	Trigger input 2, minus
	5	SIG 1 +	Signal output 1, collector
	6	SIG 1 –	Signal output 1, emitter
	7	SIG 2 +	Signal output 2, collector
	8	SIG 2 –	Signal output 2, emitter
	9	SIG 3 +	Signal output 3, collector
	10	AGND 2	Auxiliary power AGND via fusing resistor 2
Top Row of Terminals	12	+15 V	Auxiliary power, +15 V
	12	AGND 1	Auxiliary power AGND via fusing resistor 1
	14	Uext +	External control voltage for analog voltage setpoint (plus); U(Uext+); Uana = +ku x U(Uext+)
	15	Uext –	External control voltage for analog voltage setpoint (minus); U(Uext-); Uana = -ku x U(Uext-)
	15	Iext +	External control voltage for analog current setpoint (plus); U(Iext+); Iana = +ki x U(Iext+)
	16	Iext –	External control voltage for analog current setpoint (plus); U(Iext+); Iana = +ki x U(Iext+)
	17	U MON	Voltage monitor with reference to AGND 1
	18	I MON	Current monitor with reference to AGND 1
	19	SENSE +	Sensing input, plus
	20	SENSE –	Sensing input, minus

Computer Interface

IEEE 488 (option)

Mains fuse

Protects the mains power input. Use only the type specified here.



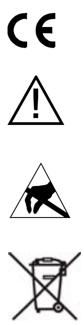
Computer interface

RS232

Mains Connection

Mains supply power must comply with the values specified here.

Symbols



Indicates EC conformity

Warning concerning a point of danger (attention: observe documentation!)

Observe ESDS directives

The device may not be disposed of with the trash. Further information regarding the WEEE mark can be accessed on the Internet at www.gossenmetrawatt.com by entering the search term WEEE.

Control Mode Status Display

CV LED lights up	Constant voltage regulating mode: Uout ≈ Uset
LED **Plim / CP*** lights up	**yellow:** Pout > Pnom (OL) **green*:** PSET < Pnom progr. (CP)
CC LED lights up	Constant current regulating mode: Iout ≈ Iset

Protective Functions and Status Displays

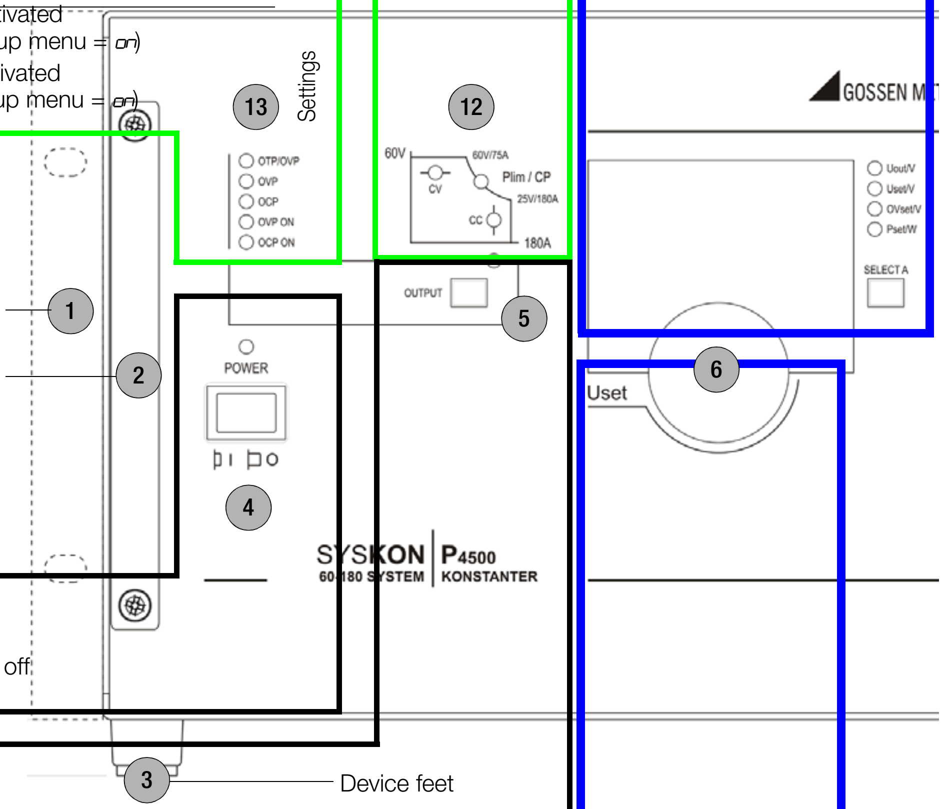
OTP/OVP LED lights up	Overtemperature protection triggered or output voltage ≥ 80 V exceeded, ⇨ OUTPUT = off
OVP LED lights up	Overvoltage detection triggered, oUSEt and oUdLY parameter values exceeded (prerequisite: oUP parameter = on) ⇨ OUTPUT = off
OCP LED lights up	Overcurrent detection triggered, ocSEt and ocdLY parameters exceeded (prerequisite: ocP parameter = on) ⇨ OUTPUT = off
OVP ON LED lights up	Overvoltage shutdown is activated (oUP parameter in device setup menu = on)
OCP ON LED lights up	Overcurrent shutdown is activated (ocP parameter in device setup menu = on)

Display A

Standard display: measured voltage value Uout, display function is changed by pressing the SELECT A key or by turning the rotary knob. Adjust resolution (select decimal place) with the ◁ and ▷ scroll keys

Select A

Display selection:
Uout → Uset → OVset → Pset



Mains Switch

POWER LED lights up	Device is switched on
POWER switch	Switches the device on and off

Power Output On/Off Key

OUTPUT LED lights up	Output is active
OUTPUT switch	Switches the power output on and off

Rotary Encoder for Voltage

Voltage setpoint Uset – adjust output voltage Uset

Condition: UL_L (lower setting limit) ≤ Uset ≤ UL_H (upper setting limit)

When the rotary encoder is activated the display is switched to Uset (LED) and the cursor becomes active – the selected decimal place blinks at the display and can be selected with the ◁ and ▷ scroll keys.
The new setpoint becomes effective immediately.

Uset adjusting alternatives	Activate by turning the rotary encoder, or select with Select A Uset	
Scroll keys	◁ ▷: select decimal place	△▽: immediately increase or reduce Uset
Numeric keypad	Entry of numeric values, Uset LED blinks	Execute with ↵, or abort with ESC

* valid as from revision level 02 and firmware version 004. In the case of hardware revision level < 02, the LED lights up yellow in both cases.

Display B

Standard display: measured current value Iout, display function is changed by pressing the SELECT A key or by turning the rotary knob. Adjust resolution (select decimal place) with the ◁ and ▷ scroll keys.

Select B

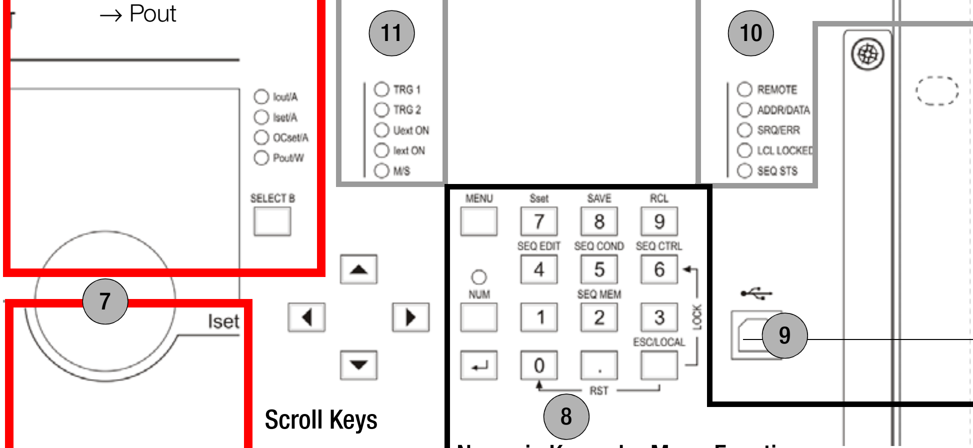
Display selection:
Iout → Iset → OCset → Pout

Analog Interface / Status Displays

TRG1 LED lights up	Trigger signal 1 is active
TRG2 LED lights up	Trigger signal 2 is active
Uext ON LED lights up	Voltage input via analog interface is active
Iext ON LED lights up	Current input via analog interface is active
M/S LED lights up	Master-slave function

Device Status Displays

REMOTE LED lights up	Remote control is active
ADDR/DATA LED lights up	Addressing / data transmission is active
SRQ/ERR LED lights up	Service request / error
LCL LOCKED LED lights up	Control panel is disabled
SEQ STS LED lights up	Sequence function in HOLD status
blinks	Sequence is active (RUN)



Computer Interface

USB port

Scroll Keys

- △ Increase Uset, Iset or parameter values
- ▽ Reduce Uset, Iset or parameter values
- ◁ Select entry position or scroll within the main menu level
- ▷ Select entry position or scroll within the main menu level

Numeric Keypad – Menu Functions

MENU	Adjustment of parameters and functions
Sset	Switching function: display and adjust signal level
SAVE	Save basic device settings (device parameters)
RCL	Recall basic device settings
SEQ ...	Sequence functions: **EDIT**, **CONDI**TION, **CONTRO**L, **MEM**ORY
NUM	Numeric entry, if active the ENTER LED lights up:
↵	transfer setting value or acknowledge selection
ESC/LOCAL	Return from menu level to standard display, abort of entry, ...
Lock	ESC/LOCAL + SEQ CTRL: disable control panel, press and hold ESC longer than 4 seconds: enable control panel
RST	ESC/LOCAL + 0: reset device settings to default values

Rotary Encoder for Current

Current setpoint Iset – adjust output current setpoint

Condition: IL_L (lower setting limit) ≤ Iset ≤ IL_H (upper setting limit)

When the rotary encoder is activated, the display is switched to Iset (LED) and the cursor becomes active – the selected decimal place blinks at the display and can be selected with the ◁ and ▷ scroll keys The new setpoint becomes effective immediately.

Iset adjusting alternatives	Activate by turning the rotary encoder, or select with Select B Iset	
Scroll keys	◁ ▷: select decimal place	△▽: immediately increase or reduce Iset
Numeric keypad	Entry of numeric values, Uset LED blinks	Execute with ↵, or abort with ESC

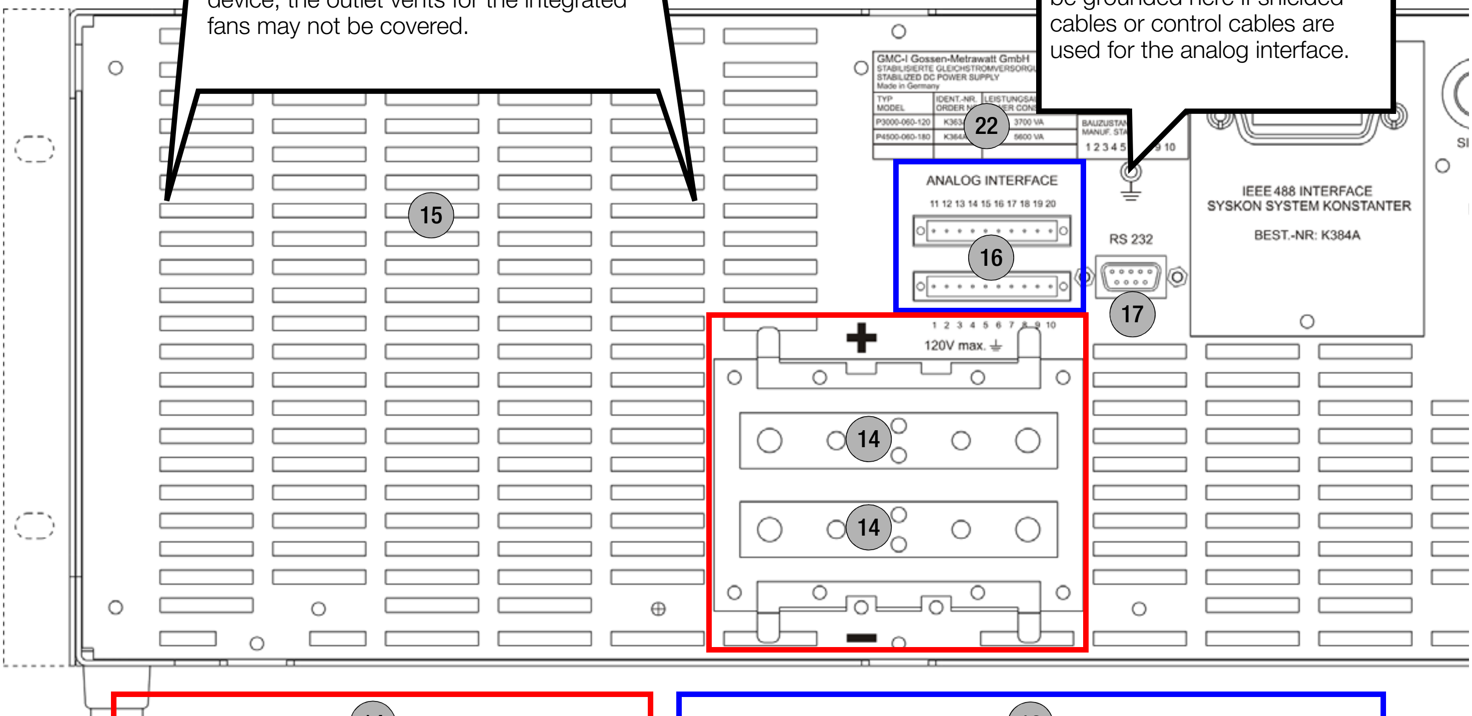
5.4 Rear Panel SYSKON P3000, P4500

Air Vents

In order to assure adequate cooling of the device, the outlet vents for the integrated fans may not be covered.

Ground Terminal (earth terminal)

The output or cable shields can be grounded here if shielded cables or control cables are used for the analog interface.



Power Output (14)

Terminals for connecting the power consumer.

This is a floating output and can be grounded with the positive or the negative pole.

Output connections may only be connected and disconnected when the output is inactive (OUTPUT OFF)! Danger of arcing!

Connecting the Power Consumer

The output leads are connected to the terminal blocks by means of ring-type cable lugs with the included M6 x 10 screws. Measurement cables can be additionally connected to the 4 mm holes.

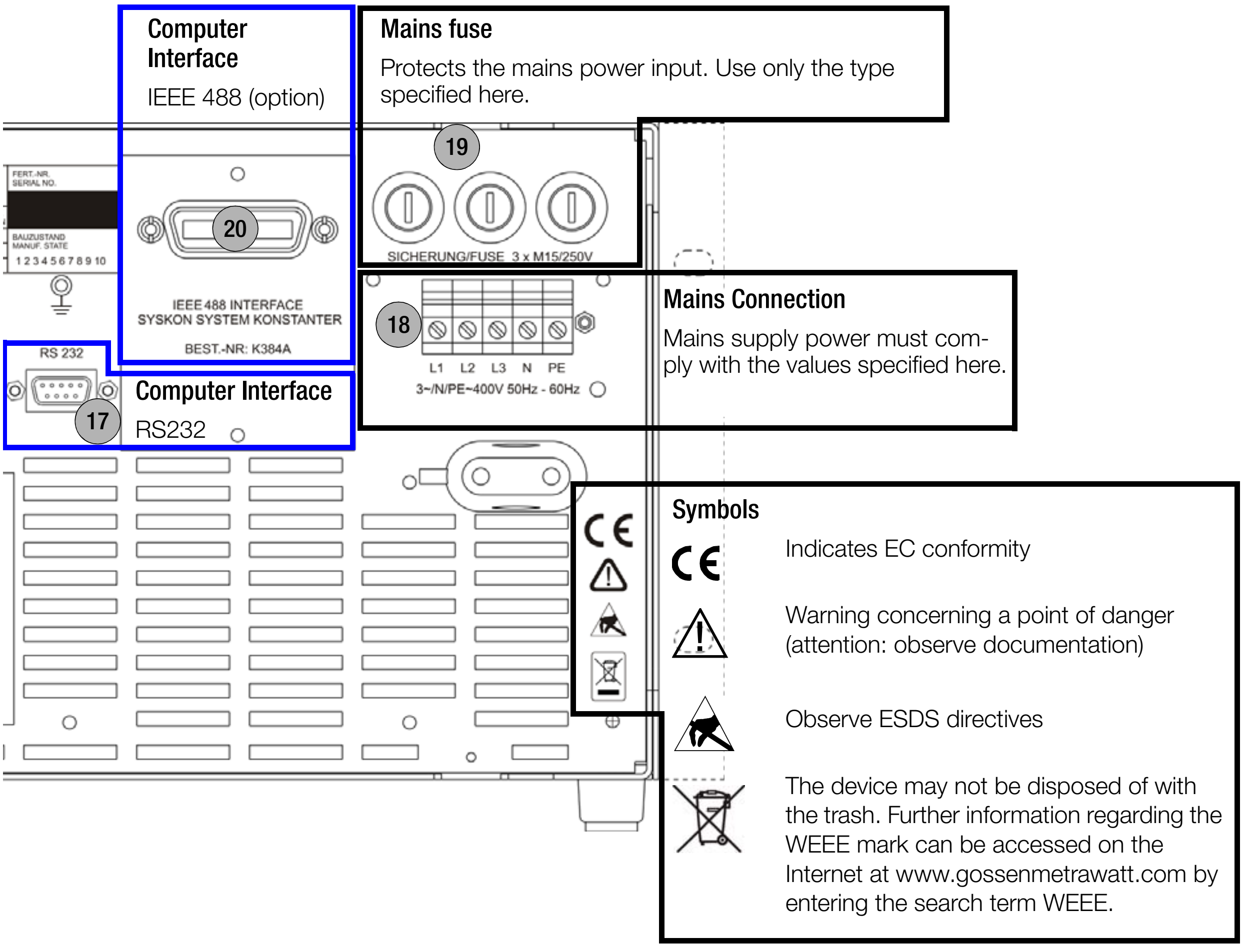
- Remove the safety cap.
- Connect the output leads to the terminal blocks with the provided screws and washers.
- An adequate wire cross-section and correct polarity must be assured. It is advisable to twist the output leads and to identify polarity at both ends.
- Avoid exerting excessive force at the terminals.
- Align the leads to the openings in the safety cap.
- Snap the safety cap back into place.

In order to prevent danger during use, shock-proof connector cables must be used when connecting power consumers.

Analog Interface (X13) (16)

- Remote control for output voltage and current
- External measurement of output voltage and current
- Connection of sensing leads in order to compensate for voltage drops in the output leads
- Linking of several devices for master-slave operation
- Vary internal output resistance
- Control of a selected device function via the floating trigger input

Terminal		Allocation	Meaning
Bottom Row of Terminals	1	TRG 1 +	Trigger input 1, plus
	2	TRG 1 –	Trigger input 1, minus
	3	TRG 2 +	Trigger input 2, plus
	4	TRG 2 –	Trigger input 2, minus
	5	SIG 1 +	Signal output 1, collector
	6	SIG 1 –	Signal output 1, emitter
	7	SIG 2 +	Signal output 2, collector
	8	SIG 2 –	Signal output 2, emitter
	9	SIG 3 +	Signal output 3, collector
	10	AGND 2	Auxiliary power AGND via fusing resistor 2
Top Row of Terminals	12	+15 V	Auxiliary power, +15 V
	12	AGND 1	Auxiliary power AGND via fusing resistor 1
	14	Uext +	External control voltage for analog voltage setpoint (plus); U(Uext+); Uana = +ku x U(Uext+)
	15	Uext –	External control voltage for analog voltage setpoint (minus); U(Uext-); Uana = -ku x U(Uext-)
	15	Iext +	External control voltage for analog current setpoint (plus); U(Iext+); Iana = +ki x U(Iext+)
	16	Iext –	External control voltage for analog current setpoint (plus); U(Iext+); Iana = +ki x U(Iext+)
	17	U MON	Voltage monitor with reference to AGND 1
	18	I MON	Current monitor with reference to AGND 1
	19	SENSE +	Sensing input, plus
	20	SENSE –	Sensing input, minus


Computer Interface
IEEE 488 (option)
Mains fuse
Protects the mains power input. Use only the type specified here.
19
SICHERUNG/FUSE 3 x M15/250V
FERT.-NR.
SERIAL NO.
BAUZUSTAND
MANUF. STATE
1 2 3 4 5 6 7 8 9 10
20
IEEE 488 INTERFACE
SYSKON SYSTEM KONSTANTER
BEST.-NR: K384A
18
L1 L2 L3 N PE
3~/N/PE~400V 50Hz - 60Hz
Mains Connection
Mains supply power must comply with the values specified here.
RS 232
17
Computer Interface
RS232
Symbols
Indicates EC conformity
Warning concerning a point of danger (attention: observe documentation)
Observe ESDS directives
The device may not be disposed of with the trash. Further information regarding the WEEE mark can be accessed on the Internet at www.gossenmetrawatt.com by entering the search term WEEE.

6 Menu Structure and Parameters

	Main menu level			Submenu level			Parameters level		Parameters level	
MENU	Display A	Display B		Display A	Display B		Display A	Display B	Display A	Display B
	SEtUP	dEUi c		dEUi c	LiMit		UL_L	00.00	UL_H (A)	60.000
	SETUP DEVICE		→	Limit value parameter		→	Voltage setting limit value, L = lower, U = upper			
	Setup menu		↵	dEUi c	oUP	↵	oUP (B)	on	oUdLY	00.00
			←	Overvoltage menu		←	Overvoltage protection on/off		Overvoltage delay time	
			ESC	dEUi c	ocP	ESC	ocP	oFF	ocdLY	00.00
				Overcurrent menu			Overcurrent protection on/off		Overcurrent delay time	
				dEUi c	cFG_d		Pon	rSt	SSEt 7	oFF
							Device settings after power on			
	SEtUP	dPY IF	→	dPY IF	dPY	→	dPY-A	Uo	dPY-b	Io
	SETUP DISPLAY & INTERFACE		↵	Digital display settings		↵	Display A – standard display: Uo		Display B – standard display: Io	
	Display and interface menu		←	dPY IF	An IF	←	trG-1	oFF	trG-2	oFF
			ESC	Analog interface settings		ESC	Trigger input 1 on/off		Trigger input 2 on/off	
				dPY IF	bUS		Addr	12	bAUd	9600
				Interface settings			Device address [6] (IEEE488)		Transmission speed (RS232)	
▷	SEtUP	SEQ		SEQ	ctrL		SEQ 6	Go	SEQ	HoLd
◁	SETUP SEQUENCE		→	Access sequence		→	Start sequence (RUN), **footnote 3**		Stop sequence	
	Sequence menu		↵	SEQ	cond i	↵	SEQ-n 5	0	Strt	0097
			←	Sequence settings		←	Sequence no. (subsequence) **footnote 1**		Start address	
			ESC	SEQ	Edit	ESC	MEM-A 4	0 100	USEt	39.000
				Edit sequence					Voltage setpoint	
				SEQ	MEM		LoAd 2	0 105	StorE	0 105
				Memory functions			Load sequence value		Save as sequence value	
	SEtUP	MEAS	→	MEAS	MM-U I	→	MM-U I	oFF	U_	9.992
	SETUP MEASUREMENT		↵	EXTREME MEASUREMENT		↵	Min-Max memory		Minimum measured voltage value	
	Measuring menu		←	MEAS	U I-cS	←	MEAS	U I_cS	Uc_	0.000
			ESC			ESC				
				MEAS	cFG_M		M-UP	3	M-tAb	
				MEAS	SPEc		rLOAd **footnote 5**	30..531		
	AUX		→	InFo		→	L-Err	000	ErA	3
	AUXILIARY		↵	Events and status memory		↵	Last error no.		Events memory A	
	Memory and calibration menu		←	UErS I		←	rEL	01..001	UPd	no
			ESC	Firmware revision		ESC	Firmware version		Firmware update	
				AdJUS	7.10.11		UoFF	#	UFS	#
				Balancing routine	Balancing date		Voltage setpoint zero point		Voltage setpoint upper limit	
							◁		▷	

(A) Set parameter (example: upper limit value for voltage setpoint)

UL_H 60000	↵	Acknowledge selection.
UL_H 60000	◁ ▷	Select entry position (decimal place). Number blinks, NUM LED key lights up.
UL_H 40000	△ ▽	Increase/decrease value – alternative: Enter value directly with the numeric keypad.
UL_H 40000	↵	Acknowledge parameter or abort procedure with ESC
	ESC	Jump back to higher menu level.

(B) Select parameter – switch function on/off.

oUP oFF	↵	Acknowledge selection.
oUP on	△ ▽	Select status (here: off, on, r01 ... r12/r15*).
oUP on	↵	Acknowledge parameter.

* /r15 as from firmware version 004

Key

SEtUP SEQ	LED display (display A / B)
SEtUP SEQ (shaded)	Parameter not yet set
#	Setting value is displayed, after which the measured value is entered and acknowledged with ↵.
◁ ▷	Scroll within the parameters level. Select parameters.
↵	Select submenu or parameters level.
ESC	Jump back to higher menu level.
6	Hot key for direct parameter selection

Parameters level		Parameters level		Parameters level		Parameters level		Parameters level		Parameters level	
Display A	Display B	Display A	Display B	Display A	Display B	Display A	Display B	Display A	Display B	Display A	Display B
IL_L	00.00	IL_H	60.000								
Current setting limit value, L = lower, U = upper											
oUSEt	40.000										
Overvoltage protection trigger value											
ocSEt	80.000										
Overcurrent protection trigger value											
Si nF	oFF	c-dYn	r	SAUE 8	01	rcL 9	01	t 16	14 20	2006	08 04
						Footnote 4		Footnote 5	Time (hhmm)	Year (YYYY)	M/D (mmdd)
ddc	15										
Display delay time											
SiG-1	oFF	SiG-2	oFF	SiG-3	oFF	A1_U	oFF	A1_I	oFF		
Signal input 1 on/off		Signal input 2 on/off		Signal input 3 on/off		Voltage input on/off		Current input on/off			
db	8	Pb	nonE	Sb	1	USb	115.2k				
Number of data bits (RS232)		Parity bit (RS232)		Stop bit (1 or 2) (RS232)		Transmission speed (USB COM-Port)					
	Footnote 2						Footnote 2				
SEq	cont	SEq	StoP	SEq	Strt	SEq	StEP	SEq	bStP	SEq	ESc
Resume sequence		Stop sequence		Jump to start address		Forward step-by-step		Backwards step-by-step		Exit sequence	
StoP	0123	rEP	cont	tdEF	1.000						
Stop address		Repeat sequence		Default time							
ISEt	10.000	tSEt	tdEF	FSEt	nF						
Current setpoint		Dwell time	Default time	Function							
SEq_c	0105	SEq_c	St-SP	SEq_r	0101	SEq_i	0108				
Delete memory location 105.		Delete start-stop mem. loc.		Delete & shift mem. loc.		Paste & shift mem. loc.					
U-	9.998	I_	0.204	I-	0.212						
Max. measured voltage value		Min. measured current value		Max. measured current value							
Uc-	60.000	Ic_	0.000	Ic-	60.000						
M-cFG		EM_U		EM_I							
Erb	0	Erc	0	crA	1	crb	0				
Events memory B		Events memory C		Status memory A		Status memory B					
IoFF	#	IFS	#								
Current setpoint zero point		Current setpoint upper limit									

◁ ▷

Additional key functions:
With sequence status RUN (after GO or CONT)

- ↵ [ENTER] HOLD
- ESC [ESC] Abort at actual address
- 0 [0] Abort and jump to final value

With sequence status STOP (after Strt, Hold, StEP or bStP)

- △ [UP] STEP
- ▽ [DOWN] BACKSTEP
- ↵ [ENTER] CONT
- ESC [ESC] Abort at actual address
- 0 [0] Abort and jump to final value

See sequence status diagram chapter 10.3

*) The sequence is also aborted at the actual address, when turning an increment knob or pressing a select button. (sequence-status READY)

1 Allows for viewing and processing of the following "condi (condition) parameters" in setup memory n specified by "Seq-n" (application: subsequences)

2 Entry of numeric value n# is additionally possible, start address ≤ n ≤ stop address, → resume sequence at memory location n#

3 Other display options can be selected while a sequence is being executed with the ◁ and ▷ keys:
The display does not return automatically to the standard display setting with this option, but rather when the sequence function has been completed or aborted.

▷ ◁

		< Selected standard display setting
MEM-A	0005	Current memory location address
rrEP	cont	Remaining number of repetitions
SEq-n	00	Run is part of the main sequence
FSEt	__rU	Sequence function parameter
tSEt	tdEF	Memory location-specific dwell time
USEt ●	ISET ●	For example calculated intermediate values for a ramp function
Uout ●	IOUt ●	Momentary measured values

4 The ◁ and ▷ keys can be used as follows for scrolling while a selected RCL function is being executed (displays A and B blink until the selection is acknowledged with the ENTER key, or until the function is otherwise aborted).

▷ ◁

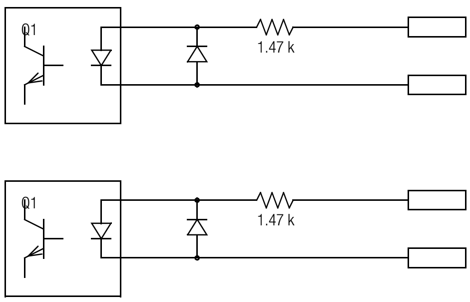
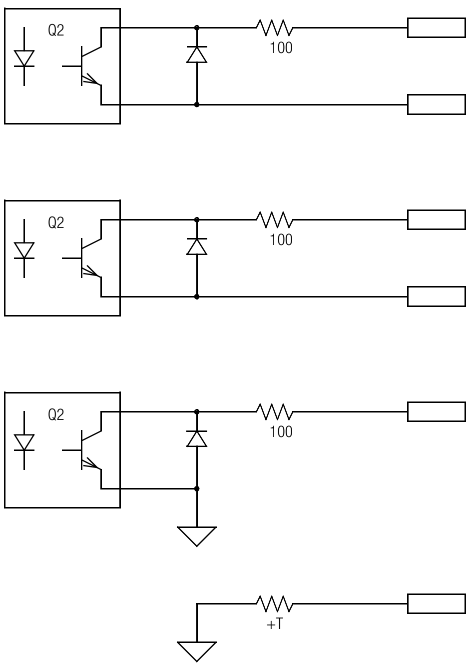
rcL	02	Access setup register 02
outP	on	
USEt	12.000	
ISEt	25.000	
PSEt	1500..0	
ouP	on	
oUSEt	80..00	
ocP	oFF	
ocSEt	80.00	
Pon	rSt	
trG-1	oFF	
trG-2	oFF	
A1-U	oFF	
I	oFF	
Strt	0001	
StoP	0005	

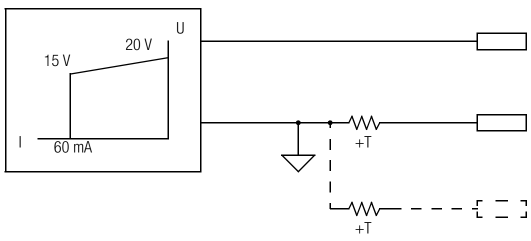
5) Display function does not change automatically back to standard display

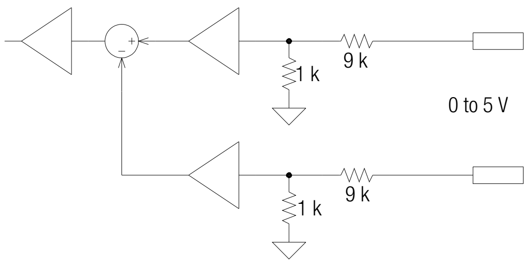
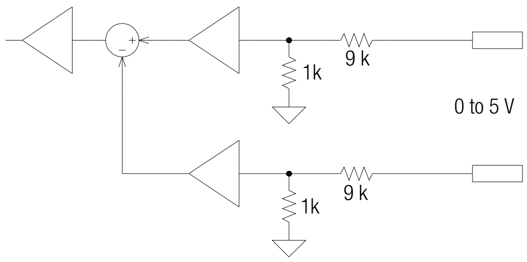
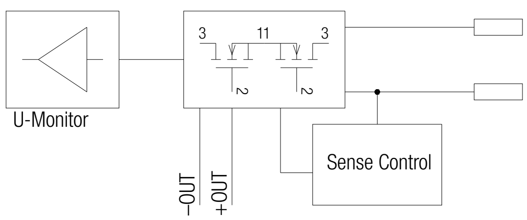
6) the modification of a device address is not accepted until restarting the KONSTANTER.

7 Analog Interface

7.1 Connector pin assignments

Interface Type	Circuit Diagram	Function	Terminal	Meaning
TRG		TRG 1 +	1	**Trigger Inputs** • Floating digital control inputs for controlling a device function defined by SEtUP/dPYIF/AnIF/trG 1 txt and SEtUP/dPYIF/AnIF/trG 2 txt • Low signal: –18 V ≤ Us ≤ + 1 V • High signal: + 4 V ≤ Us ≤ + 18 V • Current consumption: Is = (Us – 2 V) / 1.47 kΩ
		TRG 1 –	2	
		TRG 2 +	3	
		TRG 2 –	4	
SIG		SIG 1 +	5	**Signal Outputs** • Two floating digital status signal outputs • One digital status signal output with reference to AGND (2) • SIG 1±, SIG 2± and SIG 3+ indicate the statuses defined by SEtUP/dPYIF/AnIF/SiG 1 txt, SEtUP/dPYIF/AnIF/SiG 2 txt and SEtUP/dPYIF/AnIF/SiG 3 txt. • Signal type: open collector • Max. switching voltage: 30 V DC • Max. switching current: 20 mA
		SIG 1 –	6	
		SIG 2 +	7	
		SIG 2 –	8	
		SIG 3 +,	9	
		AGND 2	10	

Interface Type	Circuit Diagram	Function	Terminal	Meaning
U_H		+15 V	11	**+15 V (output)** • This auxiliary voltage output (15 to 18.5 V DC with reference to AGND 1 or AGND 2) can be used to control the trigger inputs, or to supply power to external components (e.g. reference element for generating control voltages). • The output is equipped with electronic current limiting to approximately 60 mA, and is short-circuit proof to AGND 1 and AGND 2. **AGND 1 and AGND 2 (analog ground = reference point)** • Reference point for the analog and digital control inputs and outputs • These terminals are internally connected to the minus pole of the power output via a reversible fuse with a rating of 110 mA. **The following is recommended:** • Use AGND 1 as a reference for the analog terminals on the upper terminal strip (pins 13 through 18). • Use AGND 2 as a reference for the digital terminals on the bottom terminal strip (pins 1 through 9).S
		AGND 1	12	
		AGND 2	10	

Interface Type	Circuit Diagram	Func-tion	Terminal	Meaning
U_{set}		Uext + Uext –	13 14	**Uext +, Uext – (input)** • Analog (differential) voltage input with reference to AGND for controlling the output voltage setpoint. The following applies with activated analog setpoint (SEtUP/dPYIF/AnIF/AI_U on): Uset = USET + ku x U(Uext +) – ku x U(Uext –) Uset = Resulting output voltage setpoint USET = Voltage setpoint, selected manually or digitally U(Uext+) = External control voltage (0 ... 5 V ≙ 0 ... +Usetnom) with reference to AGND 1 U(Uext –) = External control voltage (0 ... 5 V ≙ 0 ... –Usetnom) with reference to AGND 1 ku = Control coefficient = Usetnom / 5 V Usetnom = 60 V (SYSKON P1500-060-060) • Input impedance: a total of 10 kΩ each to AGND (1)
I_{set}		Iext + Iext –	15 16	**Iext +, Iext – (input)** • Analog (differential) voltage input with reference to AGND for controlling the output current setpoint. The following applies with activated analog setpoint (SEtUP/dPYIF/AnIF/AI_I on): Iset = ISET + ki x U(Iext +) – ki x U(Iext –) Iset = Resulting output current setpoint ISET = Current setpoint which has been selected manually or digitally U(Iext +) = External control voltage (0 ... 5 V ≙ 0 ... –Isetnom) with reference to AGND 1 U(Iext –) = External control voltage (0 ... 5 V ≙ 0 ... –Isetnom) with reference to AGND 1 ki = Control coefficient = Isetnom / 5 V Isetnom = 60 A (SYSKON P1500-060-060) • Input impedance: a total of 10 kΩ each to AGND (1)
Monitor	 	U MON I MON	17 18	**U MON (output)** • Analog voltage output with reference to AGND (1). Voltage is proportional to output voltage Uout detected by the sensing leads. 0 ... 10 V ≙ 0 ... Uoutnom. Uoutnom = 60 V (SYSKON P1500-060-060) • The output has an internal resistance of 8 kΩ and is short-circuit proof. **I MON (output)** • Analog voltage output with reference to AGND (1). Voltage is proportional to internally measured output current Iout. 0 ... 10 V ≙ 0 ... Ioutnom. Ioutnom = 60 A (SYSKON P1500-060-060). • The output has an internal resistance of 8 kΩ and is short-circuit proof.
Sense		SENSE + SENSE –	19 20	**SENSE +, SENSE – (input)** • For connection of sensing leads for 4-wire operation – allows for compensation of voltage drops (to 2 x 1 V) at long leads. • Switching to 4-wire operation takes place automatically when the SENSE – lead is connected to the appropriate output pole or negative load pole.

7.2 Auto-sensing mode

Function

Output voltage values required for voltage measuring and control circuits can be acquired directly at the consumer instead of at the output terminals with the help of the SENSE + and SENSE – sensing lead terminals at the analog interface. Sensing mode operation (remote sensing) offers the following advantages:

- In the constant voltage regulating mode, current related voltage drops occurring in the output leads have practically no effect on voltage supplied to the consumer. Voltage at the output terminals is automatically increased to compensate for voltage drops.
- In the constant current regulating mode, voltage limiting at the consumer is independent of output current.
- Since the voltage value provided by the measuring function is relative to the voltage value acquired at the sensing leads, load parameters such as power consumption and load resistance can be more accurately determined.

The parameters and limit values included in figure 7.2, and in the chapter entitled “Electrical Data”, apply to operation with the sensing leads.

Connection

- The two sensing lead terminals at the analog interface (SENSE + and SENSE –) must be connected to their respective output poles at the desired point (generally speaking as close to the consumer as possible).
- It is advisable to twist and/or shield the sensing leads in order to minimize interference (connect shield to the ground terminal of the negative output pole).
- Long output and sensing lead impedances may result in control fluctuations at the output, especially with capacitive consumers. This effect can be counteracted by connecting capacitors (CS+, CS-) between the SENSE and output terminals (see figure 7.2). If the output leads are twisted, their impedance can be reduced as well.
- Incorrect connection of the sensing leads does not damage the KONSTANTER, although it results in the following reversible events:
  - Polarity reversal at sensing leads or interrupted output lead: If output voltage is not being limited at the KONSTANTER by means of current regulation, it climbs to well above the selected value which finally triggers overvoltage protection and immediately deactivates the output.
  - Interrupted SENSE + lead:
    Voltage between the output terminals increases by approximately 15%.
  - Interrupted SENSE – lead:
    The sensing terminals are deactivated (automatic return to local sensing).

If the sensing leads have been connected incorrectly, rising voltage between the output terminals is not acquired by the measuring function.

Cs+, Cs-	= 10 µF to 220 µF
Us+, Us-	≤ 1 V
Is+	≈ U_{outS} / 180 kΩ
Is–	≈ 0.3 mA

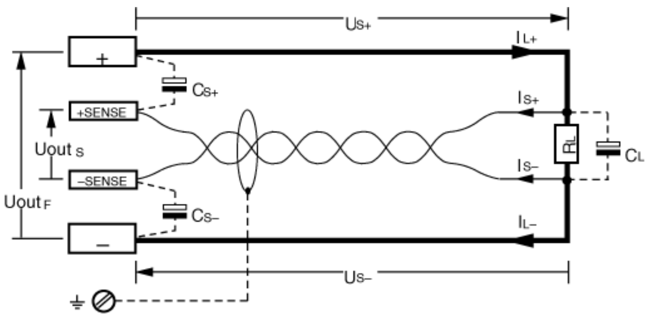


Figure 7.2 Connecting the Consumer for Sensing Mode Operation

Activation

- The remote sensing mode function is activated automatically after the SENSE – terminal has been connected to the corresponding output pole.
- The function is deactivated once again by interrupting this connection.

7.3 Status Signal Outputs

Function

- The KONSTANTER is equipped with three digital open collector outputs for indicating status.
  - Two floating outputs SIG 1 ±, SIG 2 ± and
  - One with reference to AGND:SIG 3 +
- The device status or event to be indicated is independent for all three signal outputs.
  Selection is made by setting the following functions:
  - SEtUP/dPYIF/AnIF/SiG-1 txt,
  - SEtUP/dPYIF/AnIF/SiG-2 txt and
  - SEtUP/dPYIF/AnIF/SiG-3 txt
    (see chapter 6, “Menu Structure” and chapter 7, “Operating Commands”).
- As a status signal for monitoring devices
- For controlling external output relays

Application

- Triggering of certain device functions can be synchronized by means of connection to the trigger inputs of other KONSTANTERs.

Connection

- Values for connection –
  Max. switching voltage: 30 V DC
  Max. switching current: 20 A
- If you want to use the signal outputs to send status signals to external monitoring devices, pull-up resistors must be used in order to achieve appropriate levels.
  The status signal outputs can be connected to the + 15 V terminal with pull-up resistors (at least 1 kΩ), in order to generate an active high signal of + 15 V.

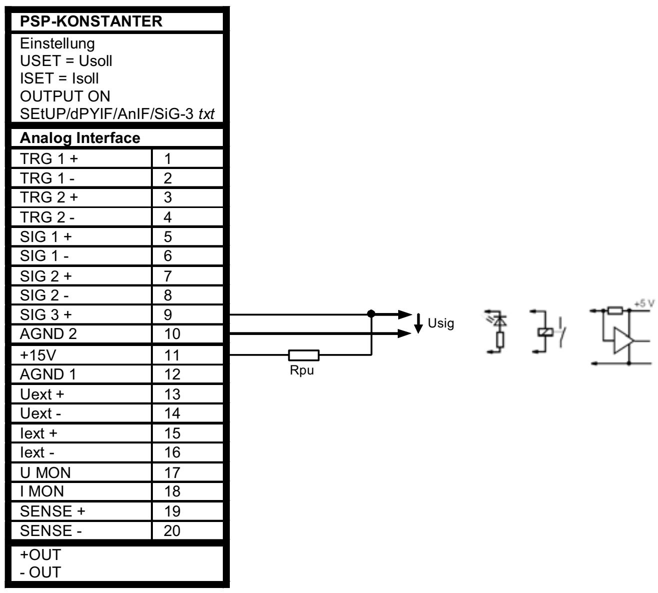


Figure 7.3 Wiring Examples for Status Signal Outputs

Setting Parameters for Status Signal Outputs

txt	Meaning – Allocation	Level
OFF	SIG n: direct off	passive high
ON	SIG n: direct on	active low
OUT	OUTPUT ON	passive high
	OUTPUT OFF	active low
MODE	OFF or CV	passive high
	CC or OL	active low
SEQ	READY/STOP	passive high
	RUN	active low
SSET	OFF	passive high
	ON	active low
U_LO [1]	Umeas ≥ w1	passive high
	Umeas < w1	active low
U_HI [1]	Umeas ≤ w2	passive high
	Umeas > w2	active low
I_LO [1]	Imeas ≥ w3	passive high
	Imeas < w3	active low
I_HI [1]	Imeas ≤ w4	passive high
	Imeas > w4	active low

1 The signal outputs can be logically linked using the comparison function. The comparative values are defined by parameters w1, w2, w3 and w4 from the UI_C_SET command. Momentary measured voltage and current values are compared with these parameters and evaluated.

7.4 Regulating Output Voltage

Function

Output voltage Uout can be set by means of external control voltage Usu = U(Uext +) – U(Uext –) via control inputs Uext + (non-inverting) and Uext – (inverting).

- The voltage control input functions as a differential voltage input:
- The following applies with activated analog setpoint (SEtUP/dPYIF/AnIF/AI_U on):
  Uset = USET + ku x U(Uext +) – ku x U(Uext –)
  - Uset = Resulting output voltage setpoint
  - USET = Voltage setpoint which has been selected manually or digitally
  - U(Uext +) = External control voltage (0 ... 5 V ≙ 0 ... +Usetnom) with reference to AGND (1)
  - U(Uext –) = External control voltage (0 ... 5 V ≙ 0 ... –Usetnom) with reference to AGND (1)
  - ku = Control coefficient = U_{setnom} / 5 V
  - U_{setnom} = 60 V (SYSKON P1500-060-060)
- Max. adjusting error:
  SYSKON P1500: ±0.2% Unom ±0.6% setting value
  SYSKON P3000: ±0.25% Unom ±0.6% setting value
  SYSKON P4500: ±0.25% Unom ±0.6% setting value.
- Input resistance: 10 kΩ each

Notes

- The control inputs are not floating inputs: Their reference point, AGND (1), is connected to the negative pole of the power output.
- Connecting grounded circuits to the control input may result in erroneous settings due to leakage current or ground loops.
- If the reference point of control voltage Usu is connected to the negative output pole at the load side, the inverting input must be connected to this point (connection b in figure 7.4). Influences resulting from voltage drops in the output lead are thus avoided.
- If control voltage is isolated from the output, connect Uext – to AGND (1) (connection a in figure 7.4).
- If remote adjustment of output voltage is to be accomplished by means of a potentiometer, wiring can be laid out as shown in figure 7.4.
- Usu can also be applied as an alternating voltage, for example in order to superimpose manually selected direct voltage USET with interference signals. The maximum operating frequency of modulated output voltage depends upon voltage amplitude, the setting selected for current limiting and load, and thus cannot be defined with a simple formula. It is increased as amplitude is decreased, and as current limiting and load are increased.

Connection

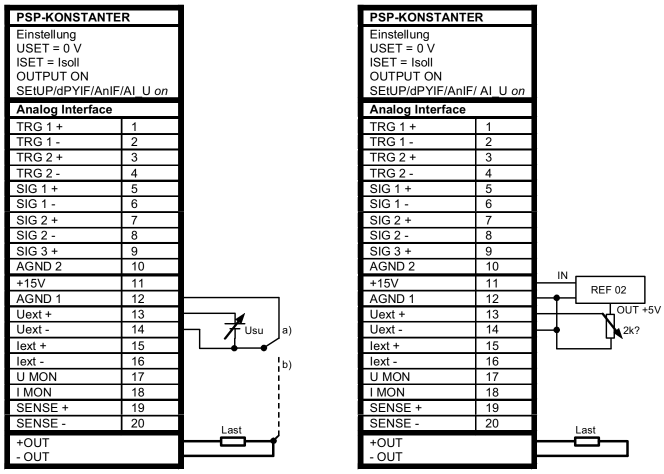


Figure 7.4 Wiring for Controlling Output Voltage with External Voltage / External Potentiometer

7.5 Controlling Output Current

Function

Output current Iout can be set with external voltage Usi = U(Iext +) – U(Iext –) via control inputs Iext + (non-inverting) and Iext – (inverting).

- The current control input functions as a differential voltage input:
- The following applies with activated analog setpoint (SEtUP/dPYIF/AnIF/AI_I on):
  Iset = ISET + ki x U(Iext +) – ki x U(Iext –)
  - Iset = Resulting output current setpoint
  - ISET = Current setpoint which has been selected manually or digitally
  - U(Iext +) = External control voltage (0 ... 5 V ≙ 0 ... +Isetnom) with reference to AGND (1)
  - U(Iext –) = External control voltage (0 ... 5 V ≙ 0 ... –Isetnom) with reference to AGND (1)
  - ki = Control coefficient = Isetnom / 5 V
  - I_{setnom} = 60 A (SYSKON P1500-060-060)
- Max. adjusting error:
  SYSKON P1500: ±0.2% Inom ±1.2% setting value
  SYSKON P3000: ±0.15% Inom ±1.2% setting value
  SYSKON P4500: ±0.133% Inom ±1.2% setting value
- Input resistance: 10 kΩ each

Notes

- The control inputs are not floating inputs: Their reference point, AGND (1), is connected to the negative pole of the power output.
- Connecting grounded circuits to the control input may result in erroneous settings due to leakage current or ground loops.
- If the reference point of control voltage Usi is connected to the negative output pole at the load side, the inverting input must be connected to this point (connection b in figure 7.5). Influences resulting from voltage drops in the output lead are thus avoided.
- If control voltage is isolated from the output, connect Iext – to AGND (1) (connection a in figure 7.5).

- If remote adjustment of output current is to be accomplished by means of a potentiometer, wiring can be laid out as shown in figure 7.5.
- Usi can also be applied as an alternating voltage, for example in order to superimpose manually selected direct current ISET with interference signals. To a great extent, the maximum operating frequency of modulated output current depends upon the output current value, as well as the voltage amplitude which results from the prevailing load, and thus cannot be defined with a simple formula. It is increased as amplitude is decreased, and as load is increased.

Connection

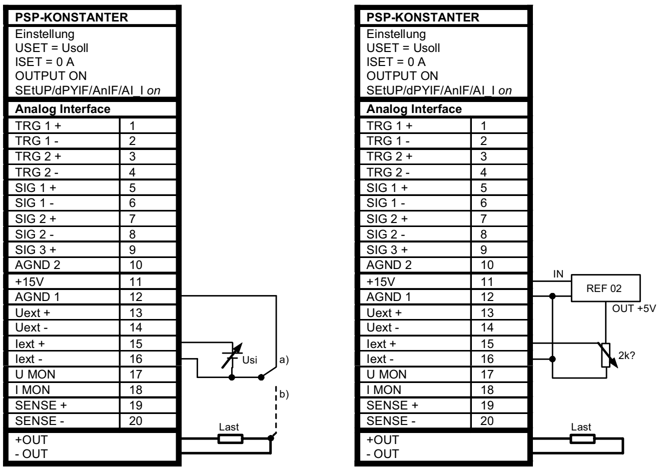


Figure 7.5 Wiring for Controlling Output Current with External Voltage / External Potentiometer

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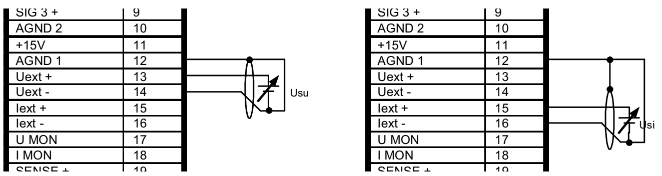
Attention!

Control inputs Uext +, Uext – and Iext +, Iext – should only be connected with shielded cable.
Connect the shield to the AGND (1) reference point.



7.6 Voltage Monitoring Output

Function

- The U MON terminal reads out voltage Umu with reference to AGND (1), which is proportional to output voltage Uout.
- U MON serves as a control voltage for master-slave series connection.
- However, U MON can also be used for external measuring, monitoring and recording.
- The following applies:
  Umu = Uout x kmu x kload (kload = 1: 0 ... 10 V ≙ 0 ... Uoutnom)
  kmu = 10 V / Uoutnom; U-monitor coefficient
  kload = Rload / (Rload + Ri); load coefficient
  Ri(U MON)= 8 kΩ; U-monitor internal resistance
  Rload = Load resistance (internal resistance of the measuring instrument)
  Uoutnom = 60 V (SYSKON P1500-060-060)
- Max. error for Umu/kmu (where Rload > 10 MΩ):
  SYSKON P1500: ±0.2% Unom ±0.4% actual value
  SYSKON P3000: ±0.3% Unom ±0.6% actual value
  SYSKON P4500: ±0.3% Unom ±0.8% actual value

Notes

- U MON is not a floating output: Its reference point, AGND (1), is connected to the negative output pole.
- Connecting grounded measuring circuits to the monitor output may result in erroneous measurements due to leakage current or ground loops.
- The voltage monitoring output makes reference to output voltage acquired at the sensing leads.
- The monitor output is short-circuit proof.
  Internal resistance is 8 kΩ.

Connection

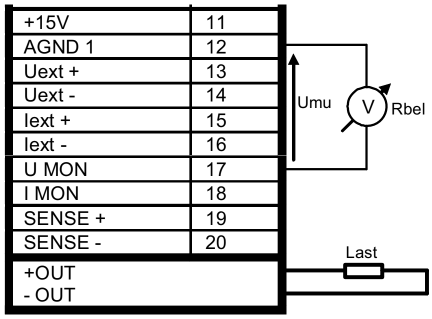


Figure 7.6 Voltage Monitor Wiring

7.7 Current Monitoring Output

Function

- The I MON terminal reads out voltage Umi with reference to AGND (1), which is proportional to output current Iout.
- I MON serves as a control voltage for master-slave parallel connection.
- However, I MON can also be used for external measuring, monitoring and recording.
- The following applies:
  Umi = Iout x kmi x kload (kload = 1: 0 ... 10 V ≙ 0 ... Ioutnom)
  kmi = 10 V / Ioutnom; I-monitor coefficient
  kload = Rload / (Rload + Ri); load coefficient
  Ri(I MON)= 8 kΩ; I-monitor internal resistance
  Rload = Load resistance (internal resistance of the measuring instrument)
  Ioutnom = 60 A (SYSKON P1500-060-060)
- Max. error for Umi/kmi (where Rload > 10 MΩ):
  SYSKON P1500: ±0.3% Inom ±1.2% actual value
  SYSKON P3000: ±0.2% Inom ±1.2% actual value
  SYSKON P4500: ±0.167% Inom ±1.2% actual value

Notes

- I MON is not a floating output: Its reference point, AGND (1), is connected to the negative output pole.
- Connecting grounded measuring circuits to the monitor output may result in erroneous measurements due to leakage current or ground loops.
- The monitor output is short-circuit proof.
  Internal resistance is 8 kΩ.

Connection

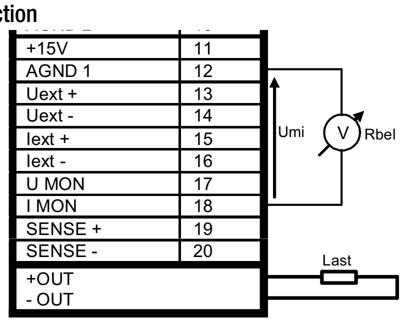


Figure 7.7 Current Monitor Wiring

7.8 Trigger Inputs

Function

- Floating optocoupler inputs TRG 1± and TRG 2± allow for remote control of a device function with the help of a binary signal.
- The function to be controlled is selected by manually or digitally configuring the trigger mode (SEtUP/dPYIF/AnIF/trG 1 txt or SEtUP/dPYIF/AnIF/trG 2 txt).

Connection

- Connect the control signal between TRG 1(2) + and TRG 1(2) –.

Signal level:

Low signal: – 18 V ≤ Us ≤ + 1 V

High signal: + 4 V ≤ Us ≤ + 18 V

Current consumption: Is = (Us – 2 V) / 1.47 kΩ

- The TRIGGER input can be driven with the + 15 V output at the analog interface via any desired switch (figure 7.8).

Warning!

Trigger inputs TRG 1± and TRG 2± are floating inputs and are functionally isolated from the output current circuit. This functional isolation is not equivalent to “safety separation” as specified in electrical safety regulations.

Note

The trigger inputs are sampled by the digital control unit approximately every 10 ms. After a signal change has been detected, repeated querying ensues at short time intervals (suppression of switch bouncing and interference pulses). This means that:

- Trigger signal pulses must have a minimum duration of 14 ms in order to assure reliable recognition.
- A delay of 1 to 15 ms may occur between application of the control signal and triggering of the controlled function.

Connection

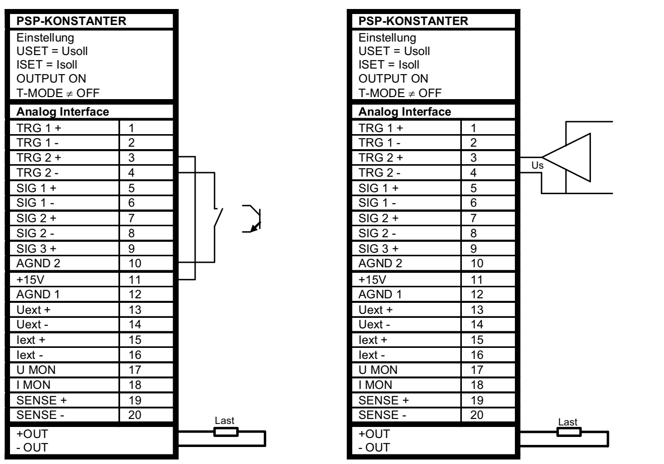


Figure 7.8 Controlling the Trigger Input with a Switching Element / External Signal

Trigger Function Setting Parameters

Parameters		Meaning
OFF		Trigger input function is deactivated, trigger signals have no effect.
OUT	OUTPUT	Trigger signal acts upon the OUTPUT: output on/off.
	Low	OUTPUT depends upon manual setting or programming command.
	Edge Low → High	OUTPUT remains OFF or OUTPUT is switched OFF.
	High	OUTPUT is OFF and cannot be activated (neither manually nor by means of a program command).
	Edge High → Low	The OUTPUT is activated; exception: OTP or OVP.
SQS	Step function	Memory recall (step-by-step sequence control)
	Edge Low → High	Start trigger signal
	High	– The trigger signal is a high pulse with a duration of less than 800 ms. – A high pulse with a duration > 1.0 s resets the address counter to the start address at any point in time, and execution begins with the next trigger signal.
	Edge High → Low	The high → low edge of the (short) trigger signal results in step-by-step control of the currently selected sequence, regardless of the specified time and number of repetitions. Recall of the memory’s contents begins with the START address. Each trigger signal increasers the address by 1, until the STOP address is reached. The next pulse once again causes execution of the contents of the START address.
SEQ	SEQUENCE	Sequence execution control
	Edge Low → High	The SEQUENCE function is started beginning with the start address (SEQUENCE GO).
	Edge High → Low	Ends sequence execution by jumping to the stop address
LLO	LOCAL LOCKED	Front panel control disabling
	Low	All front panel controls are functional.
	High	All front panel controls are disabled except for the mains switch, and activation is not possible with the LOCAL key.
MIN	MINMAX	Storage of Min-Max values for U and I is controlled when the MINMAX function is activated (MINMAX ON)(UI_ ON).
	Low	The Min-Max function is active.
	Edge Low → High	The Min-Max function is deactivated. Values in the Min-Max memories remain unchanged.
	High	The Min-Max function is inactive.
	Edge High → Low	Values in the Min-Max memories are reset and replaced with momentary output values. The Min-Max function is activated.
AIX	Analog Input	Uext, Iext
	Low	Analog setpoints not switched through
	High	Analog setpoints switched through
AIU	Analog Input	Uext
	Low	Analog setpoint not switched through
	High	Analog setpoint switched through
AII	Analog Input	Iext
	Low	Analog setpoint not switched through
	High	Analog setpoint switched through

7.9 Parallel Connection

If output current from a single KONSTANTER is insufficient for the respective application, the outputs of any number of KONSTANTERs can be parallel connected.

Attention!

If outputs with different nominal voltages are parallel connected, all outputs must be limited to the lowest utilized nominal voltage value. The ULIM parameter is used to select this setting.

7.9.1 Direct Parallel Connection

Function

- Easiest way to provide the consumer with more current than is available from a single r KONSTANTER.
- KONSTANTERs with differing nominal output voltages can be used. However, all voltage setpoints must be set or limited to the same value.
- This setup is less suitable for the constant voltage regulating mode.

Wiring

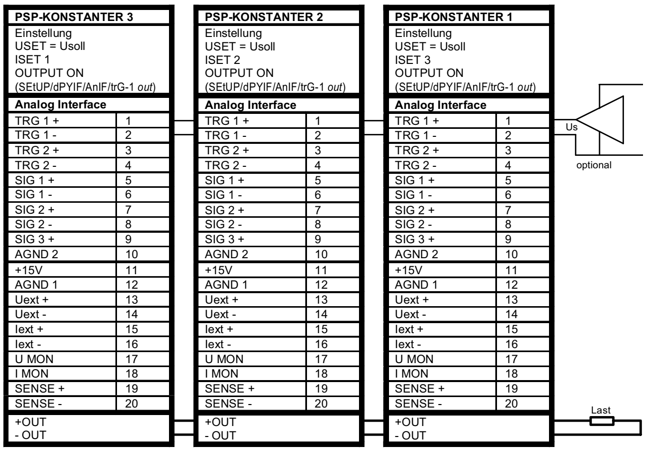


Figure 7.9.1a Wiring for Direct Parallel Connection

Settings

- Deactivate all outputs.
- Adjust voltage setpoint USET at all parallel connected KONSTANTER to approximately the same value:
- Uset = USET1 = USET2 = USET3 = ... = USETn
- Adjust current setpoints ISET such that they add up to the desired cumulative current value Iset:
- Iset = ISET1 + ISET2 + ISET3 + ... + ISETn
- Activate the outputs.

Functional Principle

- After switching the outputs on, load current is initially supplied by the KONSTANTER with the highest voltage setting.
- If load resistance is continuously reduced, load current is continuously increased.
- When load current reaches the ISET value selected for the output which is momentarily supplying power to the consumer, current limiting is activated at this output.
- If load resistance is further decreased, current regulation reduces output voltage until the voltage value of the output with the next lower setting is reached.
- As of this point in time, this KONSTANTER also supplies a portion of the load current.
- This procedure is continued until load current triggers current regulating at the output with the lowest voltage setting when the setpoint value for cumulative current is reached.
- This output maintains constant load current until the load resistor is short-circuited.

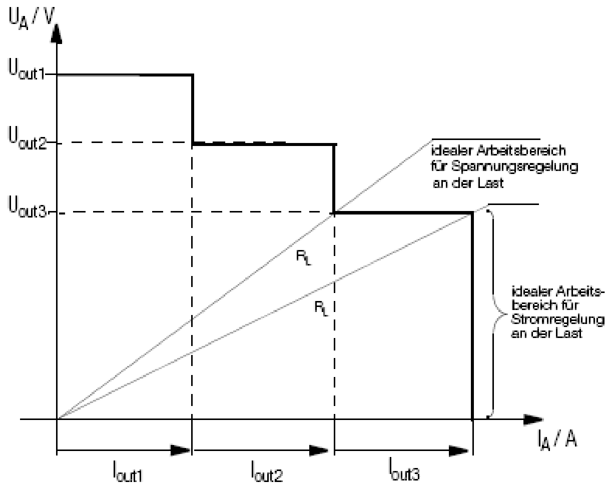


Figure 7.9.1b U / I Diagram for Direct Parallel Connection

Notes

- Slightly varying voltages occur at the individual outputs as a result of setting tolerances.
- In the event of larger voltage differences, an electronic sink is activated at the outputs with lower voltage settings.
- The sink controller attempts to reach the lower voltage value by limiting power consumption.
- Neither the KONSTANTERs nor the power consumer are damaged as a result.
- If problems occur with the measurement of load current, the KONSTANTERs should be linked by means of master-slave parallel connection.
- The outputs can be activated and deactivated commonly by connecting the trigger inputs in parallel (see figure 7.9.1a, optional connection) or series (setting: “SEtUP/dPYIF/AnIF/trG-1 out”).

7.9.2 Master-Slave Parallel Connection

Function

As opposed to direct parallel connection, master-slave parallel connection offers significant advantages:

- Equally suitable for voltage and current regulation
- Output parameters (output voltage, cumulative current limiting) are set entirely by the master device.
- All interconnected KONSTANTERs are equally loaded.

Wiring

- Define one power supply as a master device.
- Connect master and slave devices as shown in figure 7.9.2.
- Connect the output leads.
- Balance the individual output current values. Keep connector cables as short as possible, and use the largest possible conductor cross-section. Execute balancing with Rsym (set potentiometer to approx. 2 kΩ).

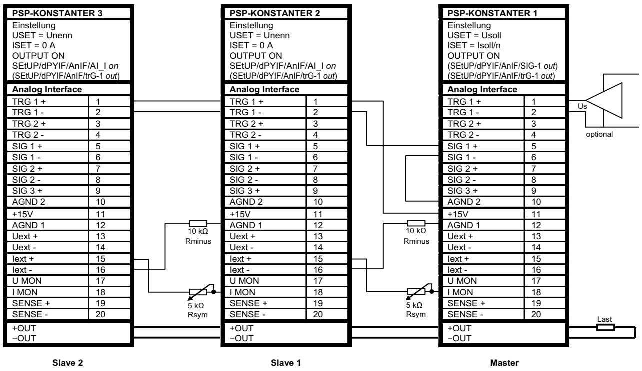


Figure 7.9.2 Wiring for Master-Slave Parallel Connection

Settings

Initial power-up:

- Short circuit the load.
- Switch the master on (mains) and configure settings:

  (Pon rcl) if desired

  OUTPUT off

  USET = Uset Desired output voltage

  ISET = Iset / n

  Iset: desired cumulative output current;
  n: number of devices
  Only valid if nominal data are identical for all devices, see notes.

- Switch slave 1 on (mains) and configure:

  (Pon rcl) if desired

  USET > USET master

  The voltage setpoint at the slave devices must be set at least 1% higher than at the master device, e.g. to maximum.

  ISET = 0 A Deactivate the ISET rotary knob if applicable by setting ILIM to 0 A.

  SEtUP/dPYIF/AI_I on

  Activates the analog current setpoint

- Use the same procedure for additional slave devices.
- Press the OUTPUT ON key at the slave(s) and the master.
- Check output current at the slave device displays.
- Output current at each of the slaves can be precisely matched to master output current by adjusting Rsym.
- Changes appear immediately at the respective display.
- Undo short-circuiting of the load.

From this point on, setting and regulation of (cumulative) output parameters are controlled entirely by the master device.

Power-up after initial settings:

Devices can be switched on and off in any desired order.

Functional Principle

The master controls output current of the downstream device (slave 1) via the slave's current control input with the help of the current monitoring signal.

Slave 1 functions as a master device for the next downstream slave (slave 2), and so forth.

Cumulative output current is thus always proportional to master output current.

Notes

KONSTANTERs with differing nominal values:

The KONSTANTER with the smallest nominal voltage value must always be used as the master device.

The voltage setting range of the other KONSTANTERs must be limited to this lowest value using the ULIM parameter.

General

- The current regulator's dynamics can be slowed down in order to achieve more stable performance. Select the following setting to this end "SEtUP/dEVic/CFG d/C dYn L".
- Rsym can be implemented as a 2 kΩ fixed resistor; adjusting error for the slaves is increased somewhat as a result.
- A wire connection can be used instead of Rsym and Rminus can be omitted, if no precise setpoint value is required for cumulative output current. In this case, each slave device supplies slightly more current than the master device.
- If analog interface connector cables and the sensing leads are longer than 1 meter, shielded cable should be used. The shield is connected to the ground terminal on the housing or to - OUT.
- The master device's measuring function acquires commonly generated output voltage for all interconnected KONSTANTERs, but only acquires its own output current.
- The individual measured current values for each of the interconnected KONSTANTERs must be added together in order to arrive at cumulative output current.
- In order to assure that the slaves' OUTPUT ON status is activated along with the master's OUTPUT ON status via the signal output and trigger input circuit as shown in figure 7.9.2, "SEtUP/dPYIF/AnIF/SiG-(x1) out" must be selected at the master and "SEtUP/dPYIF/AnIF/trG-(x2) out" must be selected at the slaves, (x1) and (x2) in example 1.
  The master's OUTPUT ON status can be optionally controlled via the trigger input – setting at the master: "SEtUP/dPYIF/AnIF/trG-(x3) out", (x3) in example 1.

7.10 Series Connection

If output voltage from a single KONSTANTER is insufficient, or if you want to generate a ± voltage, the outputs of several KONSTANTERs can be connected in series.

Warning!

Maximum allowable cumulative voltage for series connection is 240 V (or 480 V with grounded neutral point).

7.10.1 Direct Series Connection

Attention!

If outputs with differing nominal values are series connected, the highest selected current value is present at all outputs in the event of short-circuit. However, the internal reverse-voltage protection diode is only rated for nominal current of the respective device (see reverse voltage withstand under “Electrical Data”). For this reason, all current setpoints must be set to the lowest nominal current value of all interconnected devices.

The ILIM parameter is used to select this setting.

Function

- The easiest way to supply the consumer with more voltage than is available from a single KONSTANTER
- Easy wiring
- Less suitable for constant current regulating mode.

Wiring

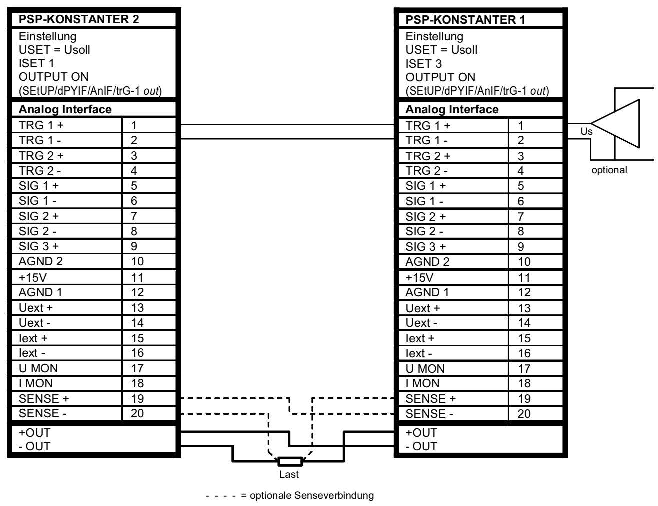


Figure 7.10.1a Wiring for Direct Series Connection

Settings

- Deactivate all outputs.
- Adjust current setpoint ISET at all series connected KONSTANTER to approximately the same value:
- Iset = ISET1 = ISET2 = ISET3 = ... = ISETn
- Adjust voltage setpoints USET such that they add up to the desired cumulative voltage value Uset:
- Uset = USET1 + USET2 + USET3 + ... + USETn
- Activate the outputs.

Functional Principle

The sum of all individual output voltages is made available to the power consumer.

If load resistance is continuously reduced, all of the outputs deliver the same load current at first.

When load current reaches the lowest selected current setpoint value, current regulating is triggered at the respective output.

If load resistance is further reduced, this output maintains constant load current until its output voltage has dropped to 0 V.

If even further reduction of load current occurs, the affected output is forced by the other outputs to generate a negative voltage. As of approximately –0.5 V, the internal reverse-voltage protection diode becomes conductive.

Load current can once again climb, until current regulation is activated at the output with the next higher current setpoint value.

This procedure is continued until load current triggers current regulating at the output with the highest current setpoint value.

Current is held constant by this last output until short-circuiting occurs.

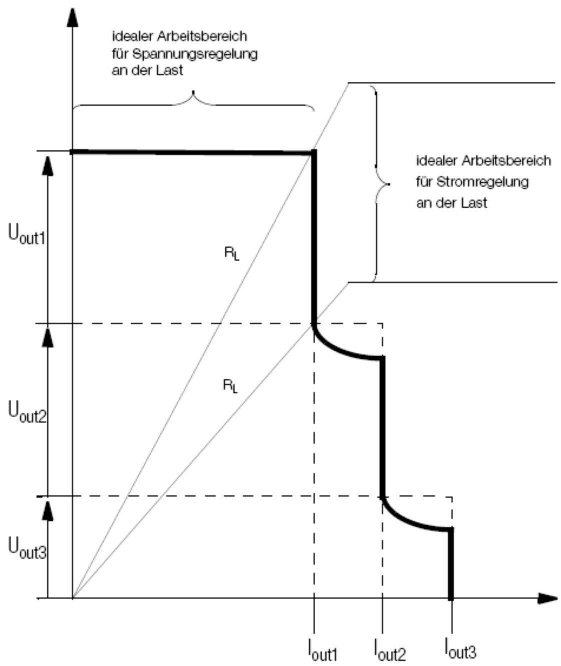


Figure 7.10.1b U / I Diagram for Direct Series Connection

Note

The outputs can be activated and deactivated commonly by connecting the trigger inputs in parallel (see figure 7.10.1a, optional connection) or series (setting: “SEtUP/dPYIF/AnIF/trG 1 out”).

7.10.2 Master-Slave Series Connection

Function

As opposed to direct series connection, master-slave series connection offers significant advantages:

- Equally suitable for voltage and current regulation
- Output parameters (cumulative output voltage, current limiting) are set entirely by the master device.
- All interconnected KONSTANTERs are equally loaded.

Wiring

- Define one power supply as a master device.
- Connect master and slave devices as shown in figure 7.10.2.
- Connect the output leads to the series circuit phase terminals.
- Balance the individual output voltage values with Rsym.

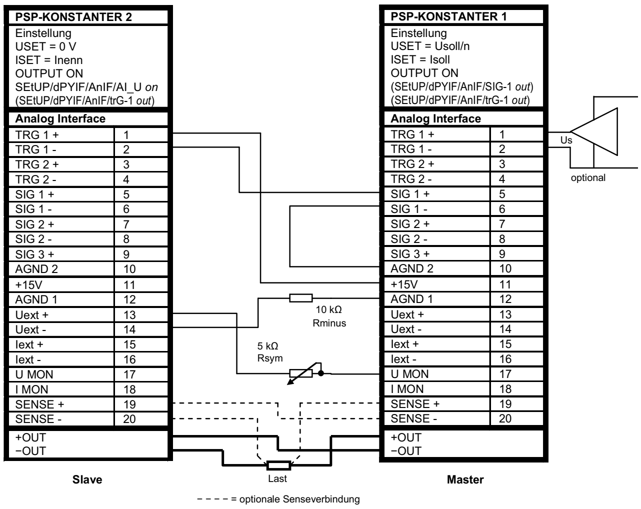


Figure 7.10.2 Wiring for Master-Slave Series Connection

Settings

Initial power-up:

- Do not load the outputs (idle).
- Switch the master on (mains) and configure settings:

  (Pon rcl) if desired

  OUTPUT off

  USET = Uset/n Uset: cumulative output voltage
  n: number of devices
  Only valid if nominal data are identical for all devices, see notes.

  ISET = Iset Current limit value
- Switch slave 1 on and configure:

  (Pon rcl) if desired

  USET = 0 VThe USET rotary knob can be deactivated if applicable by setting ULIM to 0 V.

  ISET > ISETmaster
  The current setpoint at the slave devices must be set at least 1% higher than at the master device, e.g. to maximum.

  SEtUP/dPYIF/AI_U on
  Activates the analog voltage setpoint
- Use the same procedure for additional slave devices.
- Press the OUTPUT ON key at the master.
- Check output voltage at the KONSTANTER displays.
- Output voltage at each of the slaves can be precisely matched to master output voltage by adjusting Rsym. Changes appear immediately at the respective display.
- Connect the load.

From this point on, setting and regulation of (cumulative) output parameters are controlled entirely by the master device.

Power-up after initial settings:

Devices can be switched on and off in any desired order.

Functional Principle

The master controls output voltage of the downstream KONSTANTER (slave 1) via the slave's voltage control input with the help of the voltage monitoring signal.

Slave 1 functions as a master device for the next downstream slave (slave 2), and so forth.

Cumulative output voltage is thus always proportional to master output voltage.

Notes

KONSTANTERs with differing nominal values:

The KONSTANTER with the smallest nominal current value must always be used as the master device.

The current setting range of the other KONSTANTERs must be limited to this lowest value with the ILIM parameter.

General

- If analog interface connector cables and the sensing leads are longer than 1 meter, shielded cable should be used.
- The shield is connected to the ground terminal on the housing, or to –OUT.

General

- Rsym can be implemented as a 2 kΩ fixed resistor; adjusting error for the slaves is increased somewhat as a result.
- If Rminus is omitted, the standard value for Rsym is increased to 122 kΩ.
- If analog interface connector cables and the sensing leads are longer than 1 meter, shielded cable should be used. The shield is connected to the ground terminal on the housing or to - OUT.
- The same current value is available from all KONSTANTERs. For this reason, current measured at the master device is sufficient for the measurement of load current.
- The individual measured voltage values for each of the interconnected KONSTANTERs must be added together in order to arrive at cumulative output voltage.
- In order to assure that the slaves' OUTPUT ON status is activated along with the master's OUTPUT ON status via the signal output and trigger input circuit as shown in figure 7.10.2, "SEtUP/dPYIF/AnIF/SiG-(x1) out" must be selected at the master and "SEtUP/dPYIF/AnIF/trG-(x2) out" must be selected at the slaves, (x1) and (x2) in example 1.
  The master's OUTPUT ON status can be optionally controlled via the trigger input – setting at the master: "SEtUP/dPYIF/AnIF/trG-(x3) out", (x3) in example 1.

7.11 Varying the Internal Output Resistance Value

Function

In the voltage regulating mode, internal output resistance has a value of close to 0 Ω.

The internal output resistance value can be increased for certain applications, for example simulation of long output cables or weak automotive batteries. The selected (open-circuit) output voltage is reduced in proportion to increasing load (figure 7.11 a)

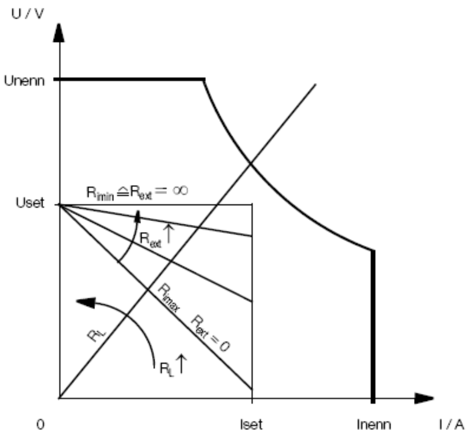


Figure 7.11a Output Voltage with Reference to Load

Calculation

The following applies:

$$R_i = \frac{20kW}{18kW + R_{ext}} \times \Omega$$ where ∞ ≥ Rext ≥ 0 Ω

$$R_{ext} = \frac{20kW}{R_i} \times W - 18k\Omega$$ where 0 Ω < Ri ≤ 1.11 Ω

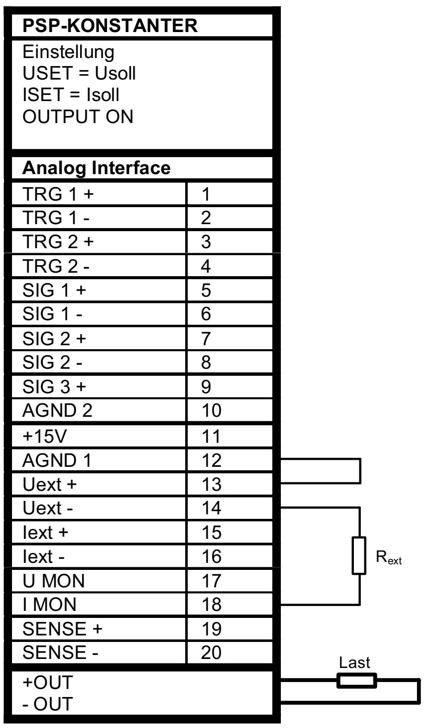


Figure 7.11b Wiring for Varying Internal Resistance

8 Descriptions of Operating Commands

All setting and query commands are described and listed alphabetically in the following pages.

Commands with an asterisk (*) are at the beginning of the list.

Each heading includes the command, along with its abbreviation.

Insofar as query commands exist (identified with a question mark ?), they are listed as well.

The next line (with the hand symbol) indicates how the respective command can be executed manually. If keys are required, they are mentioned as well.

The note “Menu” indicates that the respective command can be executed from the menu.

If no manual procedure for executing the command exists, this is indicated with a long dash (—).

Details on Memory Locations

Depending on the firmware version, a different number of memory lodations is available, see table below.

Firmware Version	Memory Locations
Version 003	12 SETUP memory locations 1536 SEQUENCE memory locations
Version 004	15 SETUP memory locations 1700 SEQUENCE memory locations

Function „General-RESET“ (manual operation only)

Function „General-RESET“ deletes the complete user memory: setup memory, sequence memory, interface settings.

The default values are set, see default settings of the respective setting commands.

The following data remain unchanged: Device balancing parameters, production/serial number as well as time and date setting.

Attention!
Before performing a „General-RESET“, we recommend that you note or save your setting parameters, e.g. via the STORE command.

To perform a „General-RESET“, press and hold the cursor keys ◁ and ▷ during „POWER ON“ until „rdy“ blinks in the display.

*CLS – Clear Status

—

Function

The *CLS command clears all event registers and the status byte register, except for the MAV bit (Message AVailable). Any existing service requests are cancelled.

Addressing status	Unchanged
Input and output buffers	Unchanged
Service request SRQ	Cleared
Status byte register STB	Cleared except for MAV bit
Event registers ESR, ERA, ERB, ERC	Cleared
Enable registers ESE, ERAE, ERBE, ERCE, SRE, PRE	Unchanged
Set or stored parameters	Unchanged

The *CLS setting command also clears the error number list (first 3 parameters) in the response to the “ERROR? query command:

“ERROR 000,000,000,xxx”

Setting Command

Syntax: **`*CLS`**

*DDT, *DDT? – Define Device Trigger

—

Function

A list of commands including up to 80 characters can be entered to a register with the “define device trigger” command. The *DDT command list is executed after receiving the *TRG device message or the IEC bus command GET (GROUP EXECUTE TRIGGER). The content of the DDT register can be read out with the *DDT? query command. Maximum response string length: 80 characters.

Setting Command

Syntax: ***DDT** *command*[*/command*][*/command*] ...
|— max. 80 characters ——|

Default setting or after RESET (*RST): DDT memory cleared

Note: A slash (/) must be used as the delineating character between commands in the DDT string instead of a semicolon (;).

All specified device messages (setting and query commands) are allowable as parameters except for the *TRG command.

Query Command

Syntax: **`*DDT?`**

Sample response string: **`USET 10;ISET 5.6;OUT ON`**

Note: The delineating slashes (/) appear once again as semicolons (;) in the response string.

Comments

In order to prevent the generation of query errors, a blank (space) is returned if the DDT register is empty.

If the maximum DDT string length is exceeded, all characters in excess of the allowable number are ignored and an execution error message is generated.

The received command list is not checked for correct syntax and limit values until the trigger command is received.

If an execution error occurs, the DDT register can be read out with the *DDT? command, but its content cannot be executed (execution error message is generated again).

The DDT register is not changed or cleared when the trigger command is executed.

*ESE, *ESE?, *PRE, *PRE?, *SRE, *SRE?, ERAE, ERAE?, ERBE, ERBE?, ERCE, ERCE? – Enable registers

—

Function

The enable registers determine which bit(s) from the corresponding event or status byte register is/are capable of influencing the respective group message. The respective group message remains set (1 = TRUE), as long as at least one bit which has been enabled to this end has a status of TRUE.

This allows for selective enabling or disabling of an SRQ and/or the individual status message "IST" due to an occurred event (masking).

The device is equipped with six enable registers. They can be written to and read separately. Queries, the *CLS command and device functions do not cause any changes to the contents of these registers. They can be cleared by entering a value of "0" (e.g. *ESE 0). The enable registers are non-volatile, and are only cleared by means of device shutdown if the non-volatile PSC flag is set to 1.

Designation	Setting Command	Query Command
Event standard enable reg. (ESE)	*ESE *n*	*ESE?
Parallel poll enable register (PRE)	*PRE *n*	*PRE?
Service request enable reg. (SRE)	*SRE *n*	*SRE?
Event enable register A (ERAE)	ERAE *n*	ERAE?
Event enable register B (ERBE)	ERBE *n*	ERBE?
Event enable register C (ERCE)	ERCE *n*	ERCE?

n = decimal equivalent of register content ($0 \leq n \leq 255$).

Sample Setting Command
Syntax: **`*ESE`** *n*

Sample Query Command
Syntax: **`*ESE`**?
Sample response string: **`*ESE`** 255

*ESR?, ERA?, ERB?, ERC? – Event Register Query

Menu (for ERA?, ERB?, ERC?)

Function

The event register provides information concerning events which have occurred within the device since the last query. They acquire and save status changes which have occurred for specific device functions. The corresponding bit is set in the event register when the respective event occurs.

For example, the CME command error bit is set in the ESR event standard register upon receipt of an incorrect programming command. This bit remains set, even if correct commands are subsequently transmitted to the device. The CME bit is not reset until the ESR register is queried.

The device is furnished with four 8-bit event registers, each of which can be individually queried. When an event register is queried, its content is deleted. The *CLS command (CLEAR STATUS) can be used to clear all event registers.

Designation	Query Command
Event standard register (ESR)	*ESR?
Event register A (ERA)	ERA?
Event register B (ERB)	ERB?
Event register C (ERC)	ERC?

Each response consists of a whole number $0 \leq n \leq 255$, where *n* corresponds to the decimal equivalent of the content of the respective register.

An enable register is assigned to each event register.

*IDN? – Device Identification Query

—

Function

In response to this query, the device identifies itself by providing information regarding manufacturer, type designation, serial number, hardware revision level and firmware revision level.

Query Command
Syntax: **`*IDN?`**
Sample response string:
"GMC-I GOSSEN-METRAWATT,
PSP1500P060RU060P,xxxxxxxxxxxxxxx,01.004"
manufacturer,
type,serial_number,hardware_revision,software_revision
Fixed response string length: 63 characters

*IST? – Individual Status Query

—

Function

Command for directly querying parallel poll information, derived from the status byte.

The status byte is not reset by this query.

Query Command
Syntax: **`*IST?`**
Response string: **`0`** or **`1`**

*LRN? – Device Settings Query (LEARN)

—

*LRN? reads out current device settings.

*LRN? i (i = 1 through 12/15) reads out the respective device settings which have been saved to setup memories 1 through 12/15 [for a more precise formulation refer to command *SAV 1 through 12/15].

Function

In response to the *LRN? query command, the device supplies a list of nearly all adjustable functions along with current parameter settings.

Query Command
Syntax: **`*LRN?`**
Sample response string (after *RST):

```
"OUTPUT OFF;USET +000,000;ISET
+000,000;PSET +01500.0;UL_L +000,000;UL_H
+060,000;IL_L +000,000;IL_H +060,000;OVP
ON;OVSET +080,000;OV_DELAY 00,000;OCP
OFF;OCSET +080,000;OC_DELAY 00,000;POW-
ER_ON RST;T_MODE OFF,OFF;ANALOG_IN OFF,
 OFF;SINK  ON;C_DYN R;MEAS_LPF 3;MINMAX
OFF;SIG123  OFF, OFF, OFF;SSET OFF;FSET
 CLR;TDEF 00,001;TSET 00,000;START_STOP
0001.0001;REPETITION 000;DISPLAY UO, IO"
```

Variant: **`*LRN?`** ***i***

(i) = optional parameter, specifies address in setup memory #i = 1 - 12/15. **`*LRN? i`** reads the "*LRN?" data record out of setup memory ($01 \leq i \leq 12/15$).

Fixed response string length: 390 characters

*OPC, *OPC? – Operation Complete Query

✋ —

Function

The operation complete function (OPC) allows for synchronization of the controller and the device:

Information indicating whether or not the previous instructions in the command string have been processed can thus be evaluated.

There are two possible procedures:

Bit 0 is set in the *ESR register with the *OPC command.

Setting Command

Syntax: ***OPC**

A “1” is transmitted as a result following the *OPC? command.

Query Command

Syntax: ***OPC?**

Comment

Further evaluation options are described in the chapter entitled “Status and Events Management”.

*PSC, *PSC? – Power-On Status Clear

✋ —

Function

The power-on status clear flag (PSC) determines whether or not the contents of the enable registers will be cleared when the device is shut down.

The PSC flag can be set and queried:

Setting Command

Syntax: ***PSC *n***
Value range: n = 0, 1
Default setting
or after RESET (*RST): 0

Query Command

Syntax: ***PSC?**
Sample response string: **0**

Parameters List

Param-eter	Content	Meaning
n	0	Enable registers will not be cleared
	1	Enable registers will be cleared

Comment

The PSC flag setting is retained, even after the device has been switched off or execution of the *CLS command.

*RCL – Recalling Stored Settings

✋ RCL

Function

Settings which have been previously saved to battery-backed memory with the *SAV command (SAVE) can be recalled and activated with *RCL (RECALL).

Remarks

The function for recalling a device setting from setup memory can be used for other commands by entering a text parameter (Rxx).

Example: **`POWER_ON R01`** means that the memory content of setup memory 1 is recalled at power-up.

Setting Command

Syntax: ***RCL *n***

Parameters List

Register number n
n = 1 through 12/15
n = 99 (undo after *RST, *RCL #, ...)
Parameter type: numeric (whole number)

Recalls a parameter set from setup memory. Setting parameters stored to the specified register number are used for the current device settings: The status which was active before the **`RCL n`** command was executed can be restored with the **`RCL 99`** command.

*RST – Reset Device Settings to Default Values

✋ ESC/LOCAL & 0

Function

After executing the reset function, the device is set to its basic default configuration (see the table entitled “Adjustable Functions and Parameters” in chapter 10.1).

Note: A period of approximately 30 seconds should be allowed to elapse after the *RST command, before the next command is executed.

Default settings:

```
“OUTPUT OFF;USET +000,000;ISET
+000,000;PSET +01500.0;UL_L +000,000;UL_H
+060,000;IL_L +000,000;IL_H +060,000;OVP
ON;OVSET +080,000;OV_DELAY 00,000;OCP
OFF;OCSET +080,000;OC_DELAY 00,000;POW-
ER_ON RST;T_MODE OFF,OFF;ANALOG_IN OFF,
 OFF;SINK  ON;C_DYN R;MEAS_LPF 3;MINMAX
OFF;SIG123  OFF, OFF, OFF;SSET OFF;FSET
 CLR;TDEF 00,001;TSET 00,000;START_STOP
0001.0001;REPETITION 000;DISPLAY UO, IO”

UI_C_Set
+000,000.+000,000.+000,000.+000,000
```

Setting Command

Syntax: ***RST**

*SAV – Saving Device Settings
☝ SAVE

Function

Current device settings can be saved to battery-backed memory with the *SAV (SAVE) execution command.

Setting Command

Syntax: **`*SAV`** ***n***

Parameters List

Register number n
n = 1 through 12/15
Parameter type: numeric (whole number)

Comments

All data stored with the SAVE function are retained in battery-backed memory when the device is switched off.

*STB? – Status Byte Register Query
☝ —

Function

Command for querying the status byte register (STB).

The status byte register contains:

– The status of group messages from the four event registers (bits 1, 2, 3 and 5)
– The status of the output buffer (empty → MAV bit = 0, not empty → MAV bit = 1)
– The status of MSS group messages masked with the SRE enable register from internal bits 0 through 5

This query command has been replicated to a great extent for operation with a serial interface (RS 232 or USB).

Register content can be read out:

a) **With the *STB? command:**
The response is a data string consisting of a whole number 16 ≤ *n* ≤ 127, where n corresponds to the decimal equivalent of the register's content.
With this querying method the value of *n* is always ≥ 16, because at least the response string was saved to the output buffer, and the MAV bit was thus set.

b) **By means of serial polling** (IEC bus only):
The device responds with its status byte as a "one byte message" in reply to the SPE (SERIAL POLL ENABLE) addressed interface command.
With this querying method bit 6 indicates the RQS status, and is reset to "0" after completion of serial polling.

The *CLS (CLEAR STATUS) command clears the status byte register except for the MAV bit, and cancels any SRQ messages.

*TRG – Device Trigger Function
☝ —

Function

A command or a list of commands which has been previously defined by means of the *DDT string (DEFINE DEVICE TRIGGER) is executed with this command.

The device accepts this command as a device message via all integrated PC interfaces.

Setting Command

Syntax: **`*TRG`**

Comments

If trigger action has not been defined (empty DDT memory), bit 4 (EXE, execution error) is set in the standard event register upon receipt of the device trigger command.

The *TRG command may not be used as part of the DDT command.

The DDT register is not changed or cleared when the trigger command is executed.

*TST? – Starting the Self-Test
☝ —

Function

Upon receipt of the *TST? query command, the device starts a self-test and reads out test results to the output buffer as a response string.

The *TST? query generates a response of either "0" (= test passed) or "1" (= test failed). If the self-test is failed, the "TCE" bit is also set in event register C.

The following is checked:

Balancing Test

Testing is conducted to determine whether or not the device has been balanced.
If the device has not been balanced, or if the balancing procedure was interrupted, error numbers 91 and 66 are read out .

Query Command

Syntax: **`*TST?`**
Response string: **`0`** or **`1`**

*WAI – Wait to Continue
☝ —

Function

The ***WAI** command is of no significance for programming the KONSTANTER.

It serves to synchronize the interface protocol in accordance with the IEC 488.2 standard.

Setting Command

Syntax: **`*WAI`**

ADJUST – Balancing / Calibration Function
Menu

Function

Attention!
This procedure replaces directly the reference parameters referring to the accuracy of the Konstanter. Please check carefully before starting this procedure.
The factory settet adjustment was done with high precise instruments as shown in DAkkS calibration certificate.

When starting the adjust function, the right display shows the last presetted calibration date (format Y.MM.DD)

Attention!
This procedure may only be executed if no other power consumers are connected. They might otherwise be damaged, because the upper range limits are read out automatically (OUTPUT ON).
The entire procedure can be executed either manually or PC controlled.

The following parameters can be balanced with this procedure:

Voltage setpoint USET (offset value and upper range limit) and measured voltage value UOUT (offset value and upper range limit).

Current setpoint ISET (offset value and upper range limit) and measured current value IOUT (offset value and upper range limit).

Sufficiently accurate measuring instruments for voltage and current are required for this procedure. The measured values must be entered as parameter W during the respective balancing step, either at the keypad or at the PC.

Appropriate error messages are generated and displayed as **UNCAL** if balancing fails or if it is interrupted with the **ADJUST EXIT** command.

ADJUST Procedure

The following sequence must be adhered to:
Uoff (offset value), Ufs (upper range limit), Ioff (offset value), Ifs (upper range limit)

Setting Commands

Voltage offset
Syntax: **ADJUST Uoff**
The Konstanter selects a small voltage offset value.
Read measured value ***w*** at the measuring instrument and transmit it to the Konstanter with the following command.

Syntax: **ADJUST Uoff, *w***

Upper voltage range limit
Syntax: **ADJUST Ufs**
The Konstanter sets output voltage to the upper range limit. Read measured value ***w*** at the measuring instrument and transmit it to the Konstanter with the following command.

Syntax: **ADJUST Ufs, *w***

Current offset
Syntax: **ADJUST Ioff**
The Konstanter selects a small current offset value.
The Konstanter must be short circuited via the ammeter or connected to a suitable resistive load for current balancing.

Attention!
Change the test setup for current measurement with a suitable ammeter. The measuring instrument must be capable of processing the maximum occurring current value.

Read measured value ***w*** at the measuring instrument and transmit it to the Konstanter with the following command.

Syntax: **ADJUST Ioff, *w***

Upper current range limit
Syntax: **ADJUST Ifs**
The Konstanter selects a small voltage offset value.
Read measured value ***w*** at the measuring instrument and transmit it to the Konstanter with the following command.

Syntax: **ADJUST Ifs, *w***

After the procedure has been completed, the date from the internal clock is saved as a balancing date.

An error message is generated when the procedure is aborted or an error has occured. In the adjust menu an **UNCAL** is displayed instead of the adjust date. The adjust parameters are replaced by internal default values.
The ***TST?** query generates a „1“.
After a new „power on“ the last active adjust parameters including its actual date are refreshed and becomes active.
The ***TST?** query generates a “0”.

Interrupting the balancing procedure
Syntax: **ADJUST EXIT**

ANALOG_IN, ANALOG_IN? – Connection of Analog Control Inputs Uext, Iext (Uset, Iset)
Menu

Function

This command allows for direct or linked connection of the analog control inputs for voltage and current.

The txt1 parameter determines the switching parameter for the Uext input, and the txt2 parameter applies to the Iext input.

The control inputs at the analog interface can be switched directly with the OFF and ON parameters.

The “ON/OFF” switching status can be set indirectly by entering the “SSET” parameter to the ANALOG_IN setting command, depending upon FSET (with the sequence function) or the SSET command.

When the switching statuses are queried, the momentary switching status, namely ON, OFF or SSET, is always returned as a response.

Note: While the PSET function is active, command signals Uext and Iext cannot be activated.

Setting Command
Syntax: **ANALOG_IN *txt1,txt2***
Parameter txt1/txt2: OFF/ON/SSET
Default setting
or after RESET (*RST): OFF

Query Command
Syntax: **ANALOG_IN?**
Sample response string: **ANALOG_IN OFF, OFF**

C_DYN, C_DYN? – Setting Current Regulating Dynamics
Menu

Function

This command makes it possible to adapt the control dynamics of the current regulator to inductive loads. Correct use of this command allows for optimization of the regulator for critical load circumstances.

Setting Command

Syntax: **C_DYN *txt***

Parameters List

Param-eter	Content	Meaning
txt	R	Full current regulating dynamics, for minimal inductive loads
	L	Reduced current regulating dynamics, for higher inductive loads or in case of parallel connection

Query Command

Syntax: **C_DYN?**
Sample response string: **C_DYN R**

CRA?, CRB? – Condition Register Query
Menu

Function

The condition register provides information concerning the momentary status of specific device functions at the time the query was executed. For example, if the output is switched to constant current regulation, the appropriate CCR bit is set in condition register A (CRA) (condition TRUE → condition bit = 1).

This bit remains set until the current regulating mode is exited. The condition register can be queried as often as desired during this time, without causing any change to its content. The corresponding bit is not reset until the output is no longer operating in the current regulating mode (condition FALSE → conditions bit = 0).

The device is furnished with an 8-bit condition register. It can be read out, but direct overwriting and deletion are not possible.

Designation	Query Command
Condition Register A (CRA)	CRA?
Condition register B (CRB)	CRB?

The response consists of a whole number 0 ≤ *n* ≤ 255, where *n* corresponds to the decimal equivalent of the register's content.

Query Command

Syntax: **CRA?**

Condition register A

D7:	SEQB	Sequence function active
D6:	OTP2A	Overtemperature shutdown (OTP LEVEL 2) active
D5:	OTP1A	Temperature signal (OTP LEVEL 1) active
D4:	OVPA	OVP signal active
D3:	OCPA	OCP signal active
D2:	OL	Overload
D1:	CCR	Output in current regulating mode
D0:	CVR	Output in voltage regulating mode

Query Command

Syntax: **CRB?**

Condition register B

D7:	TCB	TST or ADJUST/CAL function active
D6:	T2A	Signal at trigger input 2 of the analog interface active 2)
D5:	T1A	Signal at trigger input 1 of the analog interface active 2)
D4:	ACLL	AC LEVEL LOW (line voltage < 182 Vrms)
D3:	0	
D2:	S123A	Signal output SIG1 or/and signal output SIG2 or/and signal output SIG3 at the analog interface active
D1:	CMPC	Measured current value not within the current tolerance band specified by UI_C_SET w1.w2.w3.w4 divided by w3.w4; ENABLE: ?MINMAX ON?
D0:	CMPV	Measured voltage value not within the voltage tolerance band specified by UI_C_SET w1.w2.w3.w4 divided by w1.w2; ENABLE: ?MINMAX ON?

DCL, SDC – Device Clear Function
—

Function

The device clear command causes clearing of the input and output buffers at the computer interfaces (e.g. requested data which have not been picked up). Interface-internal waiting times and lockouts are cleared. The device is ready to receive data.

Addressing status	Unchanged
Input and output buffers	Cleared
Service request SRQ	Unchanged
Status byte register	MAV bit = 0, otherwise unchanged
Event registers ESR, ERA, ERB, ERC	Unchanged
Enable registers ESE, ERAE, ERBE, ERCE, SRE, PRE	Unchanged
Set and stored parameters	Unchanged

This command is processed:

a) As a device message via all computer interfaces (setting command) 'DCL' or 'SDC'

Syntax: **DCL**
or
Syntax: **SDC**

b) Via the IEC bus interface as addressed command SDC (SELECTED DEVICE CLEAR)

c) Via the IEC bus interface as universal command DCL (DEVICE CLEAR) for all bus users

DISPLAY, DISPLAY? – Function Switching for Displays A and B
Menu

Function

The display function makes it possible to control displays A and B separately in accordance with the table below.
If this view is exited, e.g. by selecting another parameter with SELECT, or with the rotary encoder or via the menu, the display returns to this configuration after the specified time has elapsed (DDC: see the table entitled "Adjustable Functions and Parameters" in chapter 10.1).

Setting Command

Syntax **DISPLAY *txt1,txt2***
Default setting
or after RESET (*RST): UO, IO

Parameters List

Status	Description	Display A txt1	Display B txt2	Menu
ON	7-segment display activated	X	X	dPY-Ab
OFF	7-segment display deactivated	X	X	dPY-Ab
UO	Output voltage Uout (default value)	X	—	dPY-A
US	Voltage setpoint Uset	X	—	dPY-A
PS	Power setpoint Pset	X	—	dPY-A
IO	Output current Iout (default value)	—	X	dPY-b
IS	Current setpoint Iset	—	X	dPY-b
PO	Output power Pout	—	X	dPY-b
–	Display switching time	—	—	ddc

The ON or OFF status does not change the selected display function.

Query Command

Syntax **DISPLAY?**
Sample response string: **DISPLAY UO,IS**

ERROR? – List of Error Messages
Menu

Function

The three last different error messages can be read out with this command. The content of the µC-RSTSRC registers is added as the fourth parameter

The error list can be reset with the ***CLS** command.

A description of the errors is included in the section entitled “System Messages”.

Query Command

Syntax **ERROR?**

Sample response string: **ERROR 031,098,000,001**
ERROR n1,n2,n3,n4

Explanation of the example:

Parameters List

Param-eter	Content	Meaning
n1	031	Command error, CME (last error)
n2	098	Max. limit overflow (next to last error)
n3	000	No further errors
n4	001	The content of internal register µC-RSTSRC is added as additional information, although bits D7 through D5 are irrelevant. The value is not influenced by the “*CLS” command.

FSET, FSET? – Sequence Function Parameter
Menu

Function

In addition to USET, ISET and TSET, FSET is the fourth parameter for defining the sequence memory.

It determines which function will be executed upon transition to the respective memory location.

Execution of the parameter is only possible during the course of a running sequence (similar to the TSET parameter).

When the FSET parameter is transmitted, the current FSET setting is determined and is saved to the respective specification by means of the SM_STORE command.

The parameters for the FSET command are also part of the STORE command.

Setting Command

Syntax: **FSET *txt***

Default setting
or after RESET (*RST): CLR

Query Command

Syntax: **FSET?**

Sample response string: **FSET NF**

Parameters List see at the top of the next column.

Parameters List

Param-eter	Content	Meaning
txt	CLR	Empty memory location, is ignored/skipped during execution. CLR in the data record of the stop address of a sequence switches the output off after the sequence has been completed.
	NF	Sequence values USET, ISET and TSET without additional function (switching function)
	RU	Voltage ramp, duration TSET or TDEF
	RI	Current ramp, duration TSET or TDEF
	SOFF	Additionally switches SSET to OFF
	S_ON	Additionally switches SSET to ON
	AUOF	Additionally switches analog input UEXT to OFF
	AUON	Additionally switches analog input UEXT to ON
	AUSS	Additionally switches analog input UEXT to SSET control
	AIOF	Additionally switches analog input IEXT to OFF
	AION	Additionally switches analog input IEXT to ON
	AISS	Additionally switches analog input IEXT to SSET control
	Rxx	Sequence chain; USET/ISET/TSET are ignored *; new device setup is loaded from setup memory xx (see ***RCL n** command) ! Thus all settings and parameters saved to Rxx apply. Additional chains are also possible, but without automatic return upon reaching the stop address. Value range: R01 to R12/15 **Note:** If a PSET function is active in the selected SETUP setting, the SEQUENCE function will be aborted.
	Sxx	Invoke subsequence; USET/ISET/TSET setting is ignored *; ! **Only** the START_STOP, REPETITION and TDEF parameters from setup memory xx are used. Automatic return to the main sequence when the stop address of the subsequence is reached after the specified number of repetitions has been completed. No return occurs if continuous repetition has been selected for the subsequence. Maximum nesting depth: 1, Value range: S01 to S12/15

* **Exception:** If the memory address is identical with the stop address of the sequence, the parameter values for USET and ISET are used as the final setting values when the sequence is completed or aborted.

GTL – GO-TO-LOCAL Function (as from Firmware Version 005)
ESC/LOCAL in „remote“ State

Function

The „GTL“ command leads to a return of device control to front plate operation, similar to activating the [LOCAL] key.

For serial interfaces (RS232 or USB), the command should not be chained with a query command as the remote state is restored in this case, i.e. when query data are issued.

This command is processed via all computer interfaces as device message.

Setting Command

Syntax: **GTL**

IFC – Resetting the IEC Bus Interface (interface clear)
—

Function

The IEC bus interface at the device is reinitialized with the IFC (INTERFACE CLEAR) bus interface command, and is returned to the standard default settings.

Addressing status	Not addressed
Input and output buffers	Unchanged
Service request SRQ	Unchanged
Status byte register STB	Unchanged
Event registers ESR, ERA, ERB, ERC	Unchanged
Enable registers ESE, ERAE, ERBE, ERCE, SRE, PRE	Unchanged
Set and stored parameters	Unchanged

Setting Command

Syntax: **IFC**

IL_H, IL_H? – Upper Limit Value for Current Setting
☞ Menu

Function

IL_H defines the upper setting limit (soft-limit) for current setpoint value Iset.

The limit can be used to assure that output current is not inadvertently set above a specified value.

The IL_H command corresponds to the ILIM command for the SSP6XN Konstanter series as an upper limit value.

Thus **IL_H** can also be replaced with **ILIM**.

When the **ILIM?** query is executed, **IL_H +XXX.XXX** is returned in response.

Values outside of the value range (Iset ≤ w ≤ Inom) are not accepted, and cause generation of an error message and setting of an error bit in event register ERC.2.

Inom is device-specific maximum nominal current.

Entered numeric values are rounded off to device-specific resolution.

Setting Command

Syntax: **IL_H *w***
Value range: Iset ≤ w ≤ Inom
Default setting
or after RESET (*RST): w = Inom

Query Command

Syntax: **IL_H?**
Sample response string: **IL_H +XXX.XXX**

Comments

The IL_H function is not active for setting output current by means of control signal Iext via the analog interface.

IL_L, IL_L? – Lower Limit Value for Current Setting
☞ Menu

Function

IL_L defines the lower setting limit (soft-limit) for current setpoint value Iset.

The limit can be used to assure that output current is not inadvertently set below a specified value.

Values outside of the value range (0 ≤ w ≤ Iset) are not accepted, and cause generation of an error message and setting of an error bit in event register ERC.2.

Inom is device-specific maximum nominal current.

Entered numeric values are rounded off to device-specific resolution.

Setting Command

Syntax: **IL_L *w***
Value range: 0 ≤ w ≤ Iset
Default setting
or after RESET (*RST): w = 0

Query Command

Syntax: **IL_L?**
Sample response string: **IL_L +XXX.XXX**

Comments

The IL_L function is not active for setting output current by means of control signal Iext via the analog interface.

IMAX? – Maximum Measured Current Value
☞ Menu

Function

The IMAX function reads out the highest output current value which was measured by the Iout measuring function and saved to Min-Max memory while the MINMAX function was set to ON.

If the measured current value has exceeded the measuring range limit at least once with the MINMAX function set to ON, “+OL” appears at the display for IMAX and “+999999.” is entered to the data string.

The Min-Max memory value can be reset to the momentarily measured value with **MINMAX RST** (for all 4 parameters at once).

Query Command

Syntax: **IMAX?**
Sample response string: **IMAX +XXX.XXX**

IMIN? – Minimum Measured Current Value
☞ Menu

Function

The IMIN function reads out the lowest output current value which was measured by the IOUT measuring function and saved to Min-Max memory while the MINMAX function was set to ON.

If the measured current value has fallen below the measuring range limit at least once with the MINMAX function set to ON, “–OL” appears at the display for IMIN and “–999999.” is entered to the data string. The Min-Max memory value can be reset to the momentarily measured value with MINMAX RST (for all 4 parameters at once).

Query Command

Syntax: **IMIN?**
Sample response string: **IMIN +XXX.XXX**

IOUT? – Querying the Momentary Current Value
☞ SELECT B

Function

The IOUT? function reads out the momentary measured value for output current.

Type	Current Measuring Range		Resolution
Nominal current	Min. [A]	Max. [A]	
60 A	–032.766	+098.300 A	2 mA
120 A	–065.532	+196.600 A	4 mA
180 A	–098.298	+294.900 A	6 mA

The upper range values may change minimally after balancing!

If the measuring range is exceeded or fallen short of, “+/–OL” is displayed or “+/–999999” is entered to the data string.

Query Command

Syntax: **IOUT?**
Sample response string: **IOUT +XXX.XXX**

ISET, ISET? – Current Setpoint
☝ SELECT B or rotary encoder Iset

Function

The output current setpoint is set with ISET. The ISET? query returns the momentarily selected current setpoint as a response.

Values outside of the value range (0 ≤ IL_L ≤ **w** ≤ IL_H ≤ Inom) are not accepted, and cause generation of an error message and setting of an error bit in event register ERC.2.

Entered numeric values are rounded off to device-specific resolution.

Setting Command

Syntax: **`ISET w`**
Value range: 0 ≤ IL_L ≤ **w** ≤ IL_H ≤ Inom
Default setting
or after RESET (*RST): w = 0

Query Command

Syntax: **`ISET?`**
Sample response string: **`ISET +XXX.XXX`**

Device Type	Setting Range		Setting Resolution	
Nom. Current [A]	Min. [A]	Max. [A]	Remote [A]	Manual [A]
60	0.000	60.000	0.001	0.001
120	0.000	120.000	0.002	0.002/0.010
180	0.000	180.00	0.003125	0.003125/0.0125

MEASURE, MEASURE? – Measuring Function (not currently used)
☝ Menu

MEAS_LPF, MEAS_LPF? – Low-Pass Filter for Measured Value Acquisition
☝ Menu

Function

Selection can be made from amongst four time constants for evaluation of the measuring signal. This selection applies equally to the measured quantities for both voltage and current.

Setting Command

Syntax: **`MEAS_LPF n`**
Value range: n = 1, 2, 3, 4
Default setting
or after RESET (*RST): n = 3

Query Command

Syntax: **`MEAS_LPF?`**
Sample response string: **`MEAS_LPF n`**

Parameters List

Parameter	Content	Meaning, Time Constant
n	1	1 ms
	2	10 ms
	3	50 ms
	4	400 ms

MINMAX, MINMAX? – Min-Max Storage for Measured U and I Values
☝ Menu

Function

The MINMAX function makes it possible to save minimum and maximum measured voltage and current values to memory. The saved values, UMIN, UMAX, IMIN and IMAX, can then be displayed or queried via the interfaces.

The “MINMAX ON” setting is also a prerequisite for the “tolerance band function”
(setting command `UI_C_SET w1,w2,w3,w4` for the reference values).

Setting Command

Syntax: **`MINMAX txt`**
Parameter txt: OFF/ON/RST
Default setting
or after RESET (*RST): **`OFF`**

Query Command

Syntax: **`MINMAX?`**
Sample response string: **`MINMAX OFF`**

Parameters List

txt	Description
OFF	Storage of Min-Max values deactivated, stored values remain unchanged
ON	Storage of Min-Max values activated, enables tolerance band function for CRB.0/1, ERC.0/1. If the SIG outputs are correspondingly configured, a switching signal can be generated at the analog interface.
RST	Contents of Min-Max memory are reset, i.e. are replaced with the momentary measured value for the corresponding parameter: Umin = Uout Umax = Uout Imin = Iout Imax = Iout

MODE? – Momentary Control Mode of the Power Output
☝ LED

Function

The device responds with the momentarily active operating mode (control mode) in response to the MODE? query command.

Query Command

Syntax: **`MODE?`**
Sample response string: **`MODE CV`**

Parameters List

Parameter	Content	Meaning	LED ☝
txt	**OFF**	Output deactivated	—
	CV	Constant voltage regulating mode	CV + OUTPUT
	CC	Constant current regulating mode	CC + OUTPUT
	CP	Constant power regulating mode Overload (power limiting)	PLim + OUTPUT

OCP, OCP? – Overcurrent Protection
Menu, LED

Function

The OCP function (**o**ver **c**urrent **p**rotection) determines how the power output will respond if load current climbs to the selected OCSET value.

The OCP function is used in addition to current regulation, whose setpoint is specified with ISET or via the analog control input.

The OCP function protects connected power consumers against continuous overcurrent, although a higher current value is required intermittently. The function also makes it possible to activate another device configuration in case of overcurrent.

Load current is compared with the OCSET value generated with an integrated D-A converter by means of an autonomous comparator, and is evaluated.

The ensuing reaction is shown in the following table.

Activation of the OCP function is indicated at the front panel by means of the "OCP ON" LED. If OCP has caused shutdown, this is additionally indicated by the "OCP" LED.

Setting Command

Syntax: **OCP *txt***
Parameter txt: OFF/ON/R01 ... R12/15
Default setting
or after RESET (*RST): OFF

Query Command

Syntax: **OCP?**
Sample response string: **OCP OFF**

Parameters List

Param-eter	Content	Meaning
txt	**OFF**	OCP function is inactive
	ON	OCP function activated: The output is shut down if output current is equal to or exceeds the specified OC_SET limit value for a duration of OC_DELAY.
	Rxx	Instead of a shutdown, recall of a device configuration from setup memories 01 through 12/15 can be activated with R01 ... R12/15.

OCSET, OCSET? – Overcurrent Protection Trigger Value
SELECT B, Menu

Function

The triggering threshold reference value required for the OCP function is set with OCSET.

Setting Command

Syntax: **OCSET *w***
Value range: OCSETmin ≤ w ≤ OCSETmax
Default setting
or after RESET (*RST): OCSETmax

Device Type	Setting Range		Setting Resolution	
Nom. Current [A]	OCSETmin. [A]	OCSETmax. [A]	Remote [A]	Manual [A]
60	3.00	80.00	0.02	0.02
120	6.00	160.00	0.05	0.05
180	9.00	240.0	0.1	0.1

Query Command

Syntax: **OCSET?**
Sample response string: **OCSET +080.000**

OC_DELAY, OC_DELAY? – Overcurrent Protection Trigger Delay
Menu

Function

Desired response delay for the OCP function is set with OC_DELAY. Delay time is specified in seconds.

If output current drops to below the OCSET value before OC_DELAY expires, the shutdown sequence is interrupted and restarted the next time the threshold is exceeded.

Setting Command

Syntax: **OC_DELAY *w***
Value range: 0 ≤ w ≤ 65,535
Default setting
or after RESET (*RST): 0

Query Command

Syntax: **OC_DELAY?**
Sample response string: **OC_DELAY XX.XXX**

OUTPUT, OUTPUT? – Switching the Power Output On and Off
OUTPUT / LED

Function

The power output can be activated and deactivated with the OUTPUT function.

Activation: OUTPUT ON:

Current and voltage values of “0” are specified initially for a period of approximately 2 ms **with activated output** for the transition from the “highly resistive” condition. The output is then adjusted to the selected voltage and current setpoints.

Deactivation: OUTPUT OFF:

The power output is deactivated and rendered highly resistive with the OUTPUT OFF command. Differentiation must be made as to whether the internal dynamic sink is on or off (setting command: SINK on / SINK OFF).

However, the output terminals are not electrically enabled.

OUTPUT OFF with SINK ON

The setpoints for voltage and current are set to 0 V and 0 A. The sink is activated for approximately 300 ms. The sink discharges the output capacitors as far as possible. The sink is then switched off and the output becomes highly resistive as a result.

OUTPUT OFF with SINK OFF

The setpoints for voltage and current are set to 0 V and 0 A. The power output is deactivated and becomes highly resistive as a result.

The output capacitors are discharged via the connected load only. Output voltage is correspondingly reduced.

Setting Command

Syntax: **OUTPUT *txt***
Parameter txt: OFF/ON
Default setting
or after RESET (*RST): OFF

Query Command

Syntax: **OUTPUT?**
Sample response string: **OUTPUT ON**

Parameters List

Parameter	Content	Meaning
txt	**OFF**	Output is switched off, OUTPUT LED off, control mode LEDs are off
	ON	Output is switched on, OUTPUT LED lights up, control mode LED lights up

Comments

If the output is switched off by a trigger signal in the “T_MODE OUT” operating mode, i.e. in the off state, the signal has higher priority.

An OUTPUT ON command is not executed, and bit 4 is set in event register B (OUTE).

“Err 073” also appears briefly at the display as a warning in the event of manual operation.

Additional functions which may influence the status of the output include:

- OTP, overtemperature protection
- OVP, overvoltage protection
- OCP with activated “OCP ON” parameter
- SEQUENCE function
- T_MODE function
- POWER_ON
- *RCL

OVP, OVP? – Overvoltage Protection
Menu, LEDs

Edit Formulation Function

The OVP function (**o**ver **v**oltage **p**rotection) specifies how the power output will respond if output voltage is equal to or exceeds the selected OVSET value.

The OVP function is an overriding protective function and is independent of the voltage and current regulators.

The OVP function protects connected power consumers against continuous overvoltage, although higher voltage is required intermittently. The function also makes it possible to activate another device configuration in case of overvoltage.

Output voltage is compared with the OVSET value from the OVP-DAC by an autonomous comparator.

The ensuing reaction is shown in the following table, and execution can be delayed by means of OV_DELAY.

Where OV_DELAY = 0, the power output is switched off directly by the OVP comparator.

Activation of the OVP function is indicated at the front panel by means of the “OVP ON” LED.

If OVP has caused shutdown, this is additionally indicated by the “OVP” LED.

Setting Command

Syntax: **OVP *txt***
Parameter txt: OFF/ON/R01 ... R12/15
Default setting
or after RESET (*RST): ON

Query Command

Syntax: **OVP?**
Sample response string: **OVP OFF**

Parameters List

Parameter	Content	Meaning
txt	**OFF**	OVP function inactive
	ON	OVP function activated: The output is shut down if output voltage is equal to or exceeds the specified OV_SET limit value for a duration of OV_DELAY.
	Rxx	Instead of a shutdown, recall of a device configuration from setup memories 01 through 12/15 can be activated with R01 ... R12/15.

OV_DELAY, OV_DELAY? – Overvoltage Protection Triggering Delay
Menu

Function

Desired response delay for the OVP function is set with OV_DELAY. Delay time is specified in seconds.

If output voltage drops to below the OVSET value before OV_DELAY expires, the shutdown sequence is interrupted and restarted the next time the threshold is exceeded.

Where OV_DELAY = 0, the OVP comparator switches the power output off directly as well.

Setting Command

Syntax: **OV_DELAY *w***
Value range: $0 \leq w \leq 65{,}535$
Default setting
or after RESET (*RST): 0

Query Command

Syntax: **OV_DELAY?**
Sample response string: **OV_DELAY XX.XXX**

OVSET, OVSET? – Overvoltage Protection Trigger Value
SELECT A and Menu

Function

The triggering threshold reference value required for the OVP function is set with OVSET.

Setting Command

Syntax: **OVSET *w***
Value range: OVSETmin ≤ w ≤ OVSETmax
Default setting
or after RESET (*RST): OVSETmax

Query Command

Syntax: **OVSET?**
Sample response string: **OVSET +080.000**

Parameters List

Parame-ters	For: Device Type	Setting Range		Setting resolution	
	Nom. Voltage [V]	OVSETmin. [V]	OVSETmax. [V]	Remote [V]	Manual [V]
w	60	3.00	80.00	0.02	0.02

Comments

Amongst other causes, overvoltage protection can be triggered by:

- USET ≥ OVSET (due to manual setting, programming command, memory recall, sequence run or Uset control signal to the analog interface)
- Sensing leads with reversed polarity
- Interrupted output lead during sensing mode operation
- Interference from the power consumer
- Parallel connected voltage sources
- Dynamic output voltage overshooting
- Device malfunction or defect

POUT? – Querying Momentary Output Power
SELECT B and Menu

Function

The POUT? function reads out momentary output power as the product of output voltage and output current.

Query Command

Syntax: **POUT?**
Sample response string: **POUT** +**XXXXX.X**

Measuring range: Due to the fact that the UOUT and IOUT measuring functions are utilized, the respective measuring ranges apply for power measurements as well. If one or both of the measured quantities UOUT and IOUT violate their respective measuring ranges, the product of POUT (UOUT x IOUT) is displayed as "–OL" or "OL", or "+/–999999" is entered to the data string.

POWER_ON, POWER_ON? – Response After Power On
Menu

Function

The POWER_ON function determines the status of device settings after mains power has been switched on.

Setting Command

Syntax: **POWER_ON *txt***
Parameter txt: RST/SBY/RCL/R01 ... R12/15
Default setting
or after RESET (*RST): RST

Query Command

Syntax: **POWER_ON?**
Sample response string: **POWER_ON RST**

Parameters List

Param-eter	Content	Meaning
txt	**RST**	RESET: Defined default settings are utilized → default settings
	SBY	STANDBY: Same device settings as before shutdown, but the power output remains inactive (OUTPUT OFF)
	RCL	RECALL: Same device settings as before shutdown – power output remains in previous state
	Rxx	Recall a device configuration saved to setup memory under XX

PSET, PSET?
SELECT A

Function

The PSET Function[1] is activated by preselecting a PSET parameter value < Pnom.

The PSET operating mode is indicated by the active green „CP-LED“[1], query „MODE?“ leads to reply „MODE CP“.
(The condition and event register queries „CRA?“ and „ERA?“ invariably supply the control status of the power section and are to be interpreted accordingly.)

By using the measuring functions, setting values for voltage and current are temporarily calculated and read out to the digital-analog converters for the specified load. The „digital control range“ is limited by settings USET and ISET. If the setpoint value PSET cannot be achieved for the connected load, it is additionally indicated by the LED „CV“ or „CC“.

Attention!
Activation of PSET **automatically** switches off the analog command inputs Uext and Iext, i. e. corresponding to „ANALOG_IN OFF, OFF“. The PSET function cannot be combined with the SEQUENCE function!

Setting Command

Syntax: **PSET *w***
Value range: 0 ≤ w ≤ Pnom
w = Pnom (no power control)
Default setting
and/or after RESET (*RST): w = Pnom [2]

Query Command

Syntax: **PSET?**
PSET +XXXXX.X
Sample response string: **PSET +01499.9**

[1] „Power control“, available as from firmware version 004
[2] After „*RST“, the maximum possible output power of the device can be queried with query command PSET?. Depending on whether the device is operated with 115 Vac or 230 Vac mains power, the query supplies Pnom/2 or Pnom.

REPETITION, REPETITION? – Number of Repetitions for Sequence Function

Menu

Function

The REPETITION parameter determines how many times a sequence will be repeated, which is defined by the current START and STOP addresses.

i is an optional parameter which addresses the setup memory (1 to 12/15) to which the repetition value will be written, and from which it will be read.

Setting Command

Syntax:	**REPETITION *n(,i)***
Value range:	0 ≤ n ≤ 255
Default setting or after RESET (*RST):	0

Query Command

Syntax:	**REPETITION? *(i)***
Sample response string:	**REPETITION n**

Parameters List

Parameter	Content	Meaning
n	0	Continuous repetition
	1 to 255	Number of sequence repetitions

RLOAD? – Load Resistance

Menü

Function

The RLOAD function supplies the value of the current load resistance as a quotient of output voltage and output current.

Query Command

Syntax:	**RLOAD?**
Sample response string:	**RLOAD +XXX.XXX**

Measuring range: As the UOUT and IOUT measuring functions are used, the corresponding measuring range limits apply.

If the output is inactive (OUTPUT OFF) or one (or both) measuring quantities UOUT and/or IOUT exceed or fall short of the measuring range limits or if the mathematical value cannot be displayed in the numerical format „XXX.XXX“, RLOAD = UOUT / IOUT is shown for the quotient in the „OL“ display and „999999.“ is entered in the data string.

SEQUENCE, SEQUENCE? – Automatic Sequential Recall of Stored Setting Values, Sequence Status Query

Menu

Function

The sequence function makes it possible to generate voltage and current profiles over a period of time, for example in order to create test signals.

The required setting values and parameters are saved to the appropriate memory to this end.

Values are saved with the commands **SM_STORE ADR** or **STORE ADR,USET,ISET,TSET,FSET.** 1536/1700 memory locations are available for this function. If dwell time is set to TSET = 0, an overriding TDEF becomes effective.

The following control commands determine the course of the sequence. The sequence is defined by means of START and STOP addresses (**START_STOP xxxx,xxxx**), and the number of repetitions (**REPETITION n**).

Note: With appropriate configuration, sequence control (GO/STOP or START/STEP) is also possible via the trigger inputs (analog interface).
The SEQUENCE function cannot be combined with the PSET function!

Setting Command (sequence control command)

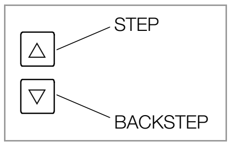
Syntax:	**SEQUENCE *txt***

Control Parameters List

If an addressed memory location is empty (no executable content), the sequence jumps to the next higher executable memory location.

Parameter	Content	Meaning
txt	**OFF**	Jump to stop address and end the sequence run or step-by-step control; same as stop. If there is no content (CLR), the power output is switched (OUTPUT OFF).
	GO	Start sequence run as of start address
	HOLD	Pause, suspend sequence at current memory location
	CONT [2]	Resume automatic sequence run with next executable memory location
	STRT [1]	Jump to start address and execute its content. Power output is switched on, step-by-step control is possible.
	STEP [1, 2]	Execute the next valid memory location. In the case of step-by-step control, the “repetition” parameter is ignored, i.e. a subsequence, for example, is executed only once.
	BSTP [1]	The “repetition” parameter is ignored, subsequences are skipped, ramp functions are executed just like “NF”
	STOP [1]	Jump to stop address and end the sequence run or step-by-step control. If there is no content (CLR), the power output is switched (OUTPUT OFF).
	ESC	Sequence is ended using the momentary setting without jumping to the final value.

1 **Step-by-step control (remote / manual)**
If the **T_MODE** parameter is set to “RCL”, **the step pulse can be specified by means of an external signal applied to the appropriate trigger input at the analog interface.**



2 A memory address can be specified as an additional, optional parameter for these commands, as of which sequence execution is started or resumed.
Example:
SEQUENCE CONT,n where start address ≤ n ≤ stop address

Query Command (sequence status)

Syntax:	**SEQUENCE?**
Sample response string:	**SEQUENCE txt,n1,n2,n3**

Query parameters list

Parameter	Content	Meaning – Sequence Status
txt	**RDY**	Device in initial state, sequence run completed
	HOLD	Sequence run paused
	RUN	Sequence run is active
n1	000 001 ... 012/015	The run is part of the main sequence. The run is part of a subsequence; defined in the specified setup memory location (1 to 12/15).
n2	001 ... 255 999	Remaining number of repetitions, continuous repetition
n3	0001 ... 1536/1700	Momentarily executed memory location

SIG123, SIG123? – Analog Interface Signal Outputs
Menu

Function
Two **floating** signal outputs (SIG 1 and SIG 2) and one signal output with reference to AGND 2 (SIG 3) are provided at the analog interface. They can be used to trigger control functions in the application. Different device functions and statuses can be assigned to these signals.

Setting Command
Syntax: **`SIG123`** ***`txt1,txt2,txt3`***
Default setting
or after RESET (*RST): OFF

Query Command
Syntax: **`SIG123?`**
Sample response string: **`SIG123 txt1.txt2.txt3`**

Parameters List

Param-eter	Content	Meaning – Assignment	Level
txt n	OFF	SIG n: direct off	Passive high
	ON	SIG n: direct on	Active low
	OUT	OUTPUT ON OUTPUT OFF	Passive high Active low
	MODE	OFF or CV CC or OL	Passive high Active low
	SEQ	READY/STOP RUN	Passive high Active low
	SSET	OFF ON	Passive high Active low
	U_LO [1]	$U_{meas} \geq w1$ $U_{meas} < w1$	Passive high Active low
	U_HI [1]	$U_{meas} \leq w2$ $U_{meas} > w2$	Passive high Active low
	I_LO [1]	$I_{meas} \geq w3$ $I_{meas} < w3$	Passive high Active low
	I_HI [1]	$I_{meas} \leq w4$ $I_{meas} > w4$	Passive high Active low

[1] The signal outputs can be logically linked using the comparison function. The reference values are defined by parameters **w1**, **w2**, **w3** and **w4** from the UI_C_SET command. Momentary measured voltage and current values are compared with these parameters and evaluated.

Para-meter	Meaning in UI_C_SET Command
w1	Lower voltage reference value
w2	Upper voltage reference value
w3	Lower current reference value
w4	Upper current reference value

SINK, SINK? – Sink Function On/Off
Menu

Function
The device is equipped with a sink function for improved dynamic characteristics, which can be activated or deactivated as desired. After an OUTPUT OFF command, the sink is deactivated (if initially activated) after a specified period of time (300 ms).

Setting Command
Syntax: **`SINK`** ***`txt`***
Parameter txt: OFF/ON
Default setting
or after RESET (*RST): ON

Query Command
Syntax: **`SINK?`**
Sample response string: **`SINK txt`**

SM_LOAD – Load Sequence Memory Location
Menu

Function
The content of a memory location can be loaded in a targeted fashion with the SM_LOAD command. The USET, ISET, TSET and FSET parameters are entered to the current device settings during this procedure. USET and ISET are read out at the power output in the case of OUTPUT ON.

Setting Command
Syntax: **`SM_LOAD`** ***`n`***
Value range: 1 ≤ n ≤ 1536/1700

SM_STORE – Store to Sequence Memory Location
Menu

Function
The contents of the USET, ISET, TSET and FSET parameters from the current device settings can be written to the specified memory location with the SM_STORE command.

The range of memory locations between the start and stop addresses can be cleared with the **`SM_STORE 0`** command.

These memory locations are then in the empty state (CLR).

Setting Command
Syntax: **`SM_STORE`** ***`n`***
Value range: 1 ≤ n ≤ 1536/1700
Special case n = 0 (delete range)

SSET, SSET? – Command for an Assigned Switching Function (signal level switching function)
Menu, SSET Key

Function
The SSET switching status can be controlled with the SSET setting command or with the corresponding FSET parameter (S_ON/SOFF) of the sequence function. The SSET switching function can then be linked with analog interface functions for switching the signal outputs SIGx (command: SIG123) and/or for controlling the analog inputs Uext and Iext (command: ANALOG_IN).

Setting Command
Syntax: **`SSET`** ***`txt`***
Parameter txt: OFF/ON
Default setting
or after RESET (*RST): OFF

Query Command
Syntax: **`SSET?`**
Sample response string: **`SSET txt`**

START_STOP, START_STOP? – Memory Location Start and Stop Addresses for the Sequence Function

☞ Menu

Function

The start and stop addresses of the sequence to be executed are defined with the START_STOP command. The STOP address must be equal to or greater than the START address.

i is an optional parameter which addresses the setup memory (1 to 12/15) to which the START-STOP values will be written, and from which they will be read.

Setting Command

Syntax: **START_STOP** ***n1,n2*****(,*****i*****)**
Value range: 1 ≤ n1 ≤ n2 ≤ 1536/1700
Default setting
or after RESET (*RST): 1.1

Query Command

Syntax: **START_STOP? (*****i*****)**
Sample response string: **START_STOP n1,n2**

STORE, STORE? – Transferring Parameters Directly to Memory

☞ (Menu – in sequential order of entry)

Function

This command is used to write the USET, ISET, TSET and FSET parameters directly to a memory location in order to set up a sequence. The parameters must be entered one after the other via the edit menu.

Setting Command

Syntax: **STORE** ***n,w1,w2,w3,txt***

Parameters List

Param-eter	Content	Formats / Meaning
n	**1** to **1536/1700**	Memory address
w1	0 ≤ w1 ≤ Unom	+nnn.nnn [V] voltage setpoint USET
w2	0 ≤ w2 ≤ Inom	+nnn.nnn [A] current setpoint ISET
w3	0 0 [s] < w3 ≤ 65.535 [s]	w3 = 0: TSET executes TDEF nn.nnn [s] dwell time TSET
txt	Content from table for FSET	FSET function This parameter is identical to the setting options for the FSET command.

Query Command

Syntax: **STORE?**
Syntax: **STORE?** ***n***
Syntax: **STORE?** ***n1,n2***
Syntax: **STORE?** ***n1,n2,tab***

The response includes the entire parameter set for each memory location: **STORE n,w1.w2.w3.txt**

Parameters List

Depending upon which query command is selected, one of the following responses is be generated:

Command	Value Range	Meaning – Response
Store?		Query contents of a memory range from the start address to the stop address of the current sequence
Store? n	n = 1 to 1536/1700	Query contents of memory location n
Store? n1,n2	n1, n2 = 1 to 1536/1700 n2 ≥ n1	Query contents of a memory range from address n1 to address n2
Store? n1,n2,tab	n1, n2 = 1 to 1536/1700 n2 ≥ n1	Query contents of a memory range from address n1 to address n2 Delimiter between output parameters: tabulator character (hex code: 09h), decimal delimiter = decimal comma (hex code: 2Ch), line break (hex code: 0Ah)

TDEF, TDEF? – Default Time for SEQUENCE Function

☞ Menu

Function

The TDEF parameter setting defines the dwell time default setting for a voltage-current value pair to be recalled.
TDEF is used instead of TSET if TSET has not been set to any specific value, but rather to 0 [s].

Note: Use of TDEF is advantageous if one or several identical dwell times occur within a given sequence whose values need to be changed frequently.

i is an optional parameter which addresses the setup memory (1 to 12/15), to which the TDEF value will be written, and from which it will be read.

Setting Command

Syntax: **TDEF** ***w*****(,*****i*****)**
Value range: 0.001 ≤ w ≤ 65.535 [s]
Default setting
or after RESET (*RST): 0.001

Query Command

Syntax: **TDEF? (*****i*****)**
Sample response string: **TDEF w**

TIMEDATE, TIMEDATE? – Programmable System Clock (RTC)

☞ Menu

Function

System date and time in accordance with ISO 8601 can be entered to the device with this command. The date entered here is used for device balancing (ADJUST command).

Setting Command

Syntax: **TIMEDATE** ***yyyy-mm-ddThh:mm:ss***
Default setting
or after RESET (*RST): Remains unchanged

Query Command

Syntax: **TIMEDATE?**
Sample response string: **TIMEDATE yyyy-mm-ddThh:mm:ss**
TIMEDATE 2007-10-01T08:00:05

The specified format must be adhered to:

yyyy: year (2000 ...)

– Delimiter (“–”)

mm: month (01 ... 12)

– Delimiter (“–”)

dd: day (01 ... 31)

T: delimiter (“T”)

hh:mm:ss hours:minutes:seconds

T_MODE, T_MODE? – Function Selection for the Trigger Inputs Menu

Function

Two floating trigger inputs are provided at the analog interface, whose action can be defined independent of each other. In this way, control functions can be triggered at the device from the application.

Depending upon which function is selected, the trigger input is level or edge controlled.

Note: Detailed descriptions of the control level are included in the section entitled “Analog Interface”.

Setting Command

Syntax: **T MODE *txt1,txt2***
Default setting
or after RESET (*RST): OFF

Query Command

Syntax: **T MODE?**
Sample response string: **T MODE txt1.txt2**

Parameters List

Param-eter	Content	Meaning	Level controlled	LED [1]
txt n	**OFF**	Trigger input function deactivated	X	
	OUT	Trigger input acts upon the output: output on/off	X	OUTPUT
	SQS	RECALL: memory recall (step-by-step), edge controlled, time dependent (functions like SEQUENCE STEP)		SEQ STS
	SEQ	SEQUENCE: sequential memory recall (functions like SEQUENCE GO)	X	SEQ STS
	LLO	LOCAL LOCKED: front panel disabling	X	LCL LOCKED
	MIN	MINMAX: min-max memory for measured values	X	
	AIX	Analog input UEXT, IEXT	X	Uext ON
	AIU	Analog input UEXT	X	Uext ON
	AII	Analog input IEXT	X	Iext ON

[1] The associated TRGx LED lights up along with the selected trigger input if the trigger parameter is not set to OFF and the trigger input is active.

TSET, TSET? – Memory Location Specific Dwell Time for the SEQUENCE Function Menu

Function

The TSET setting parameter defines the memory location specific dwell time for reading out a pair of voltage and current values for a sequence. If no specific value, but rather 0 [s], is assigned to TSET, TDEF is used as a default value for execution of the sequence function.

Setting Command

Syntax: **TSET *w***
Value range: 0,000 ≤ w ≤ 65,535 [s]
Default setting
or after RESET (*RST): 0.000

Query Command

Syntax: **TSET?**
Sample response string: **TSET w**

Comments

If dwell times of greater than 65.535 seconds are required, this can be achieved by specifying the same voltage and current values for several consecutive memory locations.

Another possibility is to invoke subsequences with the corresponding number of repetitions.

UI_C_SET, UI_C_SET? – Reference Values for Uout/Iout Tolerance Band Function Menu

Attention!
While uploading the basic settings using the „write to device“ function in the „Notes“ tab of the Soft Front Panel the saved parameters of the function „UI_C_SET“ will be replaced by the current configuration.

Function

This function makes it possible to set up reference values for voltage and current, which are continuously compared with momentary measured values. In this way, for example, checking is possible in order to determine whether or not actual voltage and current values lie within the specified range (tolerance band function). The results of this comparison can be queried in condition register CRB?, bits 0 and 1, and in event register ERC?, bits 0 and 1. The results can also be assigned to signal outputs SIG123 at the analog interface with the help of the **SIG123 txt1.txt2.txt3** command.

Setting Command

Syntax: **UI_C_SET *w1,w2,w3,w4***
Value range w1, w2: 0 ≤ w1 < w2 ≤ Unom [V]
Value range w3, w4: 0 ≤ w3 < w4 ≤ Inom [A]
Default setting
or after RESET (*RST): 0,Unom,0,Inom

Query Command

Syntax: **UI_C_SET?**
Sample response string: **UI_C_SET w1,w2,w3,w4**

Parameters List

Parameters	Format	Meaning
w1	**nnn.nnn** [V]	Lower voltage reference value
w2	**nnn.nnn** [V]	Upper voltage reference value
w3	**nnn.nnn** [A]	Lower current reference value
w4	**nnn.nnn** [A]	Upper current reference value

UL_H, UL_H? – Upper Limit Value for Voltage Setting Menu

Function

UL_H defines the upper setting limit (soft-limit) for voltage setpoint value Uset. The limit can be used to assure that output voltage is not inadvertently set above a specified value.

The UL_H command corresponds to the ULIM command for the SSP6XN Konstanter series as an upper limit value.

Thus **UL_H** can also be replaced with **ULIM**.

When the **ULIM?** query is executed, **UL_H +XXX.XXX** is returned as a response. Values outside of the value range (Uset ≤ w ≤ Unom) are not accepted, and cause generation of an error message and setting of an error bit in event register ERC.2. Unom is the device-specific maximum nominal voltage. Entered numeric values are rounded off to device-specific resolution.

Setting Command

Syntax: **UL_H *w***
Value range: Uset ≤ w ≤ Unom
Default setting
or after RESET (*RST): w = Unom

Query Command

Syntax: **UL_H?**
Sample response string: **UL_H +XXX.XXX**

Comments

The UL_L function is not active for setting output current by means of control signal Iext via the analog interface.

UL_L, UL_L? – Lower Limit Value for Voltage Setting
Menu

Function

UL_L defines the lower setting limit (soft-limit) for voltage setpoint value Uset.

The limit can be used to assure that output voltage is not inadvertently set below a specified value.

Values outside of the value range (0 ≤ w ≤ Uset) are not accepted, and cause generation of an error message and setting of an error bit in event register ERC.2.

Unom is the device-specific maximum nominal voltage.

Entered numeric values are rounded off to device-specific resolution.

Setting Command

Syntax: **UL_L *w***
Value range: 0 ≤ w ≤ Uset
Default setting
or after RESET (*RST): w = 0

Query Command

Syntax: **UL_L?**
Sample response string: **UL_L +XXX.XXX**

Comments

The UL_L function is not active for setting output voltage by means of control signal Uext via the analog interface.

UMAX? – Maximum Measured Voltage Value
Menu

Function

The UMAX function reads out the highest output voltage value which was measured by the Uout measuring function and saved to Min-Max memory while the MINMAX function was set to ON.

If the measured voltage value has exceeded the measuring range limit at least once with the MINMAX function set to ON, "+OL" appears at the display for UMAX and "+999999." is entered to the data string.

The Min-Max memory value can be reset to the momentarily measured value with **MINMAX RST** (for all 4 parameters at once).

Query Command

Syntax: **UMAX**?
Sample response string: **UMAX +XXX.XXX**

UMIN? – Minimum Measured Voltage Value
Menu

Function

The UMIN function reads out the lowest output voltage value which was measured by the Uout measuring function and saved to Min-Max memory while the MINMAX function was set to ON.

If the measured voltage value has fallen below the measuring range limit at least once with the MINMAX function set to ON, "–OL" appears at the display for UMAX and "–999999." is entered to the data string.

The Min-Max memory value can be reset to the momentarily measured value with **MINMAX RST** (for all 4 parameters at once).

Query Command

Syntax: **UMIN?**
Sample response string: **UMIN +XXX.XXX**

UOUT? – Querying the Momentary Voltage Value
SELECT A

Function

The UOUT? function reads out the momentary measured value for output voltage.

Type	Voltage Measuring Range		Resolution
Nominal voltage	Min. [V]	Max. [V]	
60 W	-016.384	+098.300 A	2 mV

The upper range values may change minimally after balancing!

If the measuring range is exceeded or fallen short of,
"+/–OL" is displayed or "+/–999999" is entered to the data string.

Query Command

Syntax: **UOUT?**
Sample response string: **UOUT +XXX.XXX**

USET, USET? – Voltage Setpoint Value
SELECT A and Rotary Encoder Uset

Function

The output voltage setpoint is set with USET. The USET? query returns the currently selected voltage setpoint as a response.

Values outside of the value range (0 ≤ UL_L ≤ **w** ≤ UL_H ≤ Unom) are not accepted, and cause generation of an error message and setting of an error bit in event register ERC.2.

Entered numeric values are rounded off to device-specific resolution.

Setting Command

Syntax: **USET *w***
Value range: 0 ≤ UL_L ≤ **w** ≤ UL_H ≤ Unom
Default setting
or after RESET (*RST): w = 0

Query Command

Syntax: **USET?**
Sample response string: **USET +XXX.XXX**

Device Type	Setting Range		Setting Resolution	
Nom. Voltage [V]	Min. [V]	Max. [V]	Remote [V]	Manual [V]
60	0.000	60.000	0.001	0.001

WAIT – Additional Waiting Time
—

Function

Command for specifying an additional waiting time between execution of the two commands. This function can be used to add additional waiting time within a data string (linked commands) during processing/execution.

For example, this allows for defined programming of a specified power-on status within a command string with execution time in the ms range.

Setting Command

Syntax: **WAIT *w***
Value range: 0.001 s ≤ w ≤ 65.535 s

Caution

During the execution of waiting time receive data are not processed and the input buffer is blocked, i.e. displays are not refreshed during waiting time.

Example

```
ISET 5; OUTPUT ON; USET 10; WAIT 0.100; USET 5
```

9 Status and Events Management

The device is equipped with special registers which can be queried by the controller in order to detect programming errors (e.g. receipt of an incorrect command), device states (e.g. output set to voltage regulating mode) or occurred events (e.g. output deactivated by a protective function).

Structure

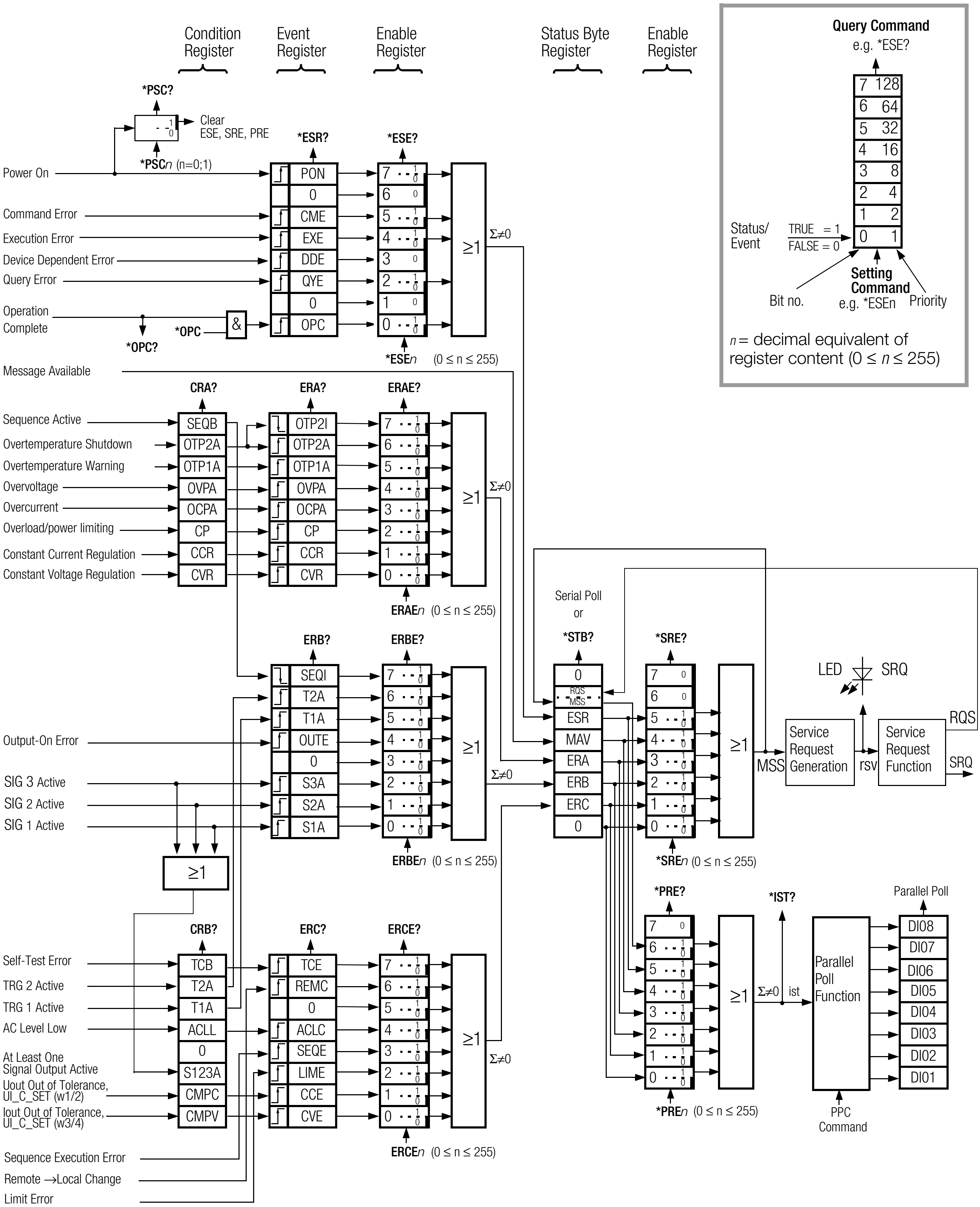


Figure 9: Status and Events Management

Meaning of Register Contents

Register Name	Meaning
ACLC	AC-LEVEL CHANGED (line voltage range has changed H → L, L → H)
ACLL	AC level Low (line voltage < 182 V_{rms})
CCE	Measured current values are outside of the tolerance band specified by UI_C_SET w1.w2.w3.w4 divided by w3.w4; ENABLE: “MINMAX ON”
CCR	Output is (was) in current regulating mode.
CVR	Output is (was) in voltage regulating mode.
CME	Unknown error, syntax error, standardized value limits for numeric parameters have been exceeded.
CMPC	Compare current: current value not within current tolerance band specified by UI_C_SET w1.w2.w3.w4 divided by w3.w4; ENABLE: “MINMAX ON”
CMPV	Compare voltage: voltage value not within voltage tolerance band specified by UI_C_SET w1.w2.w3.w4 divided by w1.w2; ENABLE: “MINMAX ON”
CVE	Measured voltage values outside of tolerance band specified by UI_C_SET w1.w2.w3.w4 divided by w1.w2; ENABLE: “MINMAX ON”
DDE	Internal device error is pending
EXE	Command-specific parameter limits exceeded, incompatibility of a command or a parameter with a current operating state.
LIME	Limit error: Error message after setting command for USET, ISET, UL_L, UL_H, IL_L, IL_H: a) Setting range UL_L ≤ USET ≤ UL_H or IL_L ≤ ISET ≤ IL_H exceeded; or b) Measuring range exceeded during voltage or current measurement c) Limit errors may also occur during a sequence. Note regarding examination of limit and setting values.
MAV	Finished message after query command: The requested information is ready for pick-up at the data output buffer.
OCPA	Output deactivated by overcurrent protection (OCP function). Switch back on with OUTPUT ON.
CP	Overload message: Power limiting has been triggered.
OPC	Finished message: The commands preceding the *OPC command have been processed (synchronization).
OTP1A	Overtemperature warning: The device is overheated, e.g. due to inadequate ventilation. If overheating is further increased, the output is switched off when the OTP2A threshold is reached. The OTP2A shutdown threshold is approximately 5° C higher than the OTP1A warning threshold.
OTP2A	Overtemperature message and shutdown: The device is overheated, e.g. due to inadequate ventilation. The output is deactivated when this message is generated. The OUTPUT ON setting command is ignored as long as this condition persists, and causes setting of the OTP2A bit in the event register.
OTP2I	Ready message after OTP2A overtemperature message: The device has cooled back down. If the POWER-ON function is set to standby or reset, the output remains deactivated; if set to recall, automatic restart ensues.
OUTE	Output error: Error message, power output can not be activated. Activation of the output is disabled by an internal hardware status, or is locked by means of the OUTPUT OFF signal at the trigger input of the analog interface. Display: “Err 73”
OVPA	Overvoltage protection has been triggered, the output has been deactivated. Switch back on with OUTPUT ON.
PON	Device was intermittently switched off, or an intermittent mains failure has occurred.
QYE	Error message after addressing as talker: A message is not (yet) ready for pick-up at the output buffer.
REMC	Status change: REMOTE → LOCAL (manual operation ensues)
S1A	SIG 1, active signal has occurred
S2A	SIG 2, active signal has occurred
S3A	SIG 3, active signal has occurred
S123A	Signal output SIG 1 or/and SIG 2 or/and SIG 3 at the analog input is active
SEQB	Status message: The sequence function is active (run, halt).
SEQI	Finished message: The sequence function is finished or has been aborted (inactive) (ready).
SEQE	Error message resulting from the sequence function.
T1A	A signal has occurred at trigger input TRG 1 of the analog interface with a setting of: trigger mode ≠ oFF
T2A	A signal has occurred at trigger input TRG 2 of the analog interface with a setting of: trigger mode ≠ oFF
TCB	TST or ADJUSTCAL function active
TCE	Self-test error or error during ADJUST has occurred

Description of the Registers

Condition Registers (CRA, CRB)

The individual bits in the conditions registers reflect the current status of a specific device function:

0 = status does not apply (FALSE)

1 = status applies (TRUE)

The content of the condition register can be read out with the help of a query command, but cannot be directly edited or cleared.

Event Registers – Standard Event Register (ESR), Event Registers (ERA, ERB, ERC)

The event registers acquire and save changes to specific device functions. The corresponding bit in the event register is set (1 = TRUE) if the associated function:

– Changes from FALSE to TRUE (with input ⌐⌐) or

– Changes from TRUE to FALSE (with input ¬L).

The four event registers can be queried individually. The content of an event register is cleared when it is queried. An enable register is assigned to each event register.

Enable Registers – Standard Event Enable Register (ESE), Event Enable Registers (ERAE, ERBE, ERCE), Service Request Enable Register (SRE), Parallel Poll Enable Register (PRE)

The enable registers determine which bit(s) from the associated register or status byte register is (are) capable of influencing the respective group message (masking). The respective group message remains set (1 = TRUE), as long as at least one bit enabled to this end has a status of TRUE.

The six enable registers can be written to and queried separately. The content of the registers is not changed by queries. Enable registers ERAE, ERBE and ERCE are set to zero when the device is switched off. Enable registers ESE, SRE and PRE are only cleared as a result of shutdown if the PSC bit is set to 1.

Status Byte Register (STB)

The status byte register contains:

– The statuses of the group messages from the three event registers with bits 1, 2, 3 and 5

– The status of the data output buffer with bit 4 (empty → MAV = 0, not empty → MAV = 1)

– The status of group message MSS consisting of bits 1, 2, 3, 4 and 5, masked by enable register SRE, with bit 6

– Bits 0 and 7 are not used and are always set to “0”.

Register contents can be read out:

– With the **`*STB?`** query command or

– In the case of IEC bus control, with the “Serial Poll” interface command. In this case, bit 6 shows the RQS status, which is reset (0) after serial polling has been completed.

The **`*CLS`** setting command clears all of the event registers and the status byte register, with the exception of the MAV bit, and cancels any pending SRQ message.

Power-On Status Clear Bit Error

The power-on status clear bit determines whether or not the content of enable registers ESE, SRE and PRE will be cleared when the device is switched off.

The PSC bit can be set and queried:

Set: **`*PSC`** *n* *n* = 0: ESE, SRE and PRE are not cleared
n = 1: ESE, SRE and PRE are cleared

Query: **`*PSC?`** Response: “0” or “1”

The PSC bit setting also remains unchanged after the device is switched off, or after the **`*CLS`** command has been executed.

Operation Complete Bit (OPC)

See *OPC and *OPC? commands for a description of the respective function.

10 Table of Operating and Query Commands

10.1 Adjustable Functions and Parameters

Setting Command	Parameter	Meaning	Value Range / Selection	Default Setting After RESET *RST	Manual	Remote	
Display and Interface Settings [1] **(see chapter 6, main menu level SETUP DISPLAY & INTERFACE)**							
Addr	n	Set device address for IEEE 488 (interface configuration)	0 ≤ n ≤ 30	unv	X		
bAUd	txt	**RS 232** transmission speed	Set via menu selection, default setting: 9600 baud. The following values can be selected manually: 1200, 1800, 2400, 3600, 4800, 7200, 9600, 14,400, 19,200, 28,800, 38,400, 57,600 or 115,200 [baud]	unv	X		
DB		**RS 232** data bits	7 or 8, set via selection menu, default setting: 8	unv	X		
PB		**RS 232** parity bit	Set via menu selection, default setting: none The following values can be selected manually: nonE, EVEn or odd	unv	X		
SB		**RS 232** stop bit	1 or 2, Default setting: 1	unv	X		
bAUd	txt	**USB** transmission speed (DB = 8, PB = no, SB = 1)	Set via menu selection, default setting: 115,200 baud. The following values can be selected manually: 9600, 14,400, 19,200, 28,800, 38,400, 57,600 or 115200 [baud]	unv	X		
DDC	n	Display switching time	Set via menu selection, default setting: 10 s. The following values can be selected manually: 5, 10, 15, 20, 30, 45, 90 or 180 [s]	unv	X		
General Commands and Settings							
***CLS**		Clear Status		—		X	
***DDT**	txt	Define Device Trigger	txt Command string with up to 80 characters, delimiter for commands is slash (/) instead of semicolon (;)	—		X	
***ESE**	n	Standard Event Status Enable	0 ≤ n ≤ 255, n = decimal equivalent of register content	—		X	
***OPC**		Operation Complete		—		X	
***PRE**	n	Parallel Poll Enable Register Enable	0 ≤ n ≤ 255, n = decimal equivalent of register content	—		X	
***PSC**	n	Power-On Status Clear	n = 0, 1	—		X	
***RCL**	n	Recall a device setting stored to a setup memory location (1 through 12/15)	1 ≤ n ≤ 12/15*; Special case n = 99 means undo after *RST, *RCL #	—	X	X	
***RST**		Reset device to default values		Default	X	X	
***SAV**	n	Save current device settings to a setup memory location (1 through 12/15)	1 ≤ n ≤ 12/15*	—	X	X	
***SRE**	n	Service Request Enable	0 ≤ n ≤ 255, n = decimal equivalent of register content	—		X	
***TRG**		Trigger for executing *DDT functions		—		X	
***WAI**		Wait to continue		—		X	
DCL / SDC		Device clear function		—		X	
ERAE	n	Device Dependent Event Register A Enable	0 ≤ n ≤ 255, n = decimal equivalent of register content	—		X	
ERBE	n	Device Dependent Event Register B Enable	0 ≤ n ≤ 255, n = decimal equivalent of register content	—		X	
ERCE	n	Device Dependent Event Register C Enable	0 ≤ n ≤ 255, n = decimal equivalent of register content	—		X	

* /15 or /1700, respectively as from firmware version 004

Setting Command	Parameter	Meaning	Value Range / Selection	Default Setting After RESET *RST	Manual	Remote	
Devise-Specific Settings							
ADJUST (CAL)	txt(,w)	Balancing/calibration function	UOFF / UFS / IOFF / IFS / (EXIT), 0 ≤ w ≤ respective balancing limit. The specified order for the procedure must be adhered to! “EXIT” → UNCAL, abort with error message	—	X	X	
ANALOG_IN	txt1,txt2	Connection of analog control inputs U(Uext), U(Iext)	OFF / ON / SSET	OFF	X	X	
C_DYN	txt	Setting for current regulating dynamics	R / L	R	X	X	
DISPLAY	txt1,txt2	Digital display function switching	txt1: ON / OFF / UO /US / PS txt2: ON / OFF / IO / IS / PO	UO IO	X	X	
FSET	txt	Sequence function parameter	CLR / NF / RU / RI / SOFF / S_ON / AUOF / AUON / AUSS / AIOF / AION / AISS / R01 ... R12/15* / S01 ... S12/15*	CLR	X	X	
IL_H (**ILI**M)	w	Upper limit value for current setting	Iset ≤ w ≤ Inom [A]	Inom	X	X	
IL_L	w	Lower limit value for current setting	0 ≤ w ≤ Iset [A]	0	X	X	
ISET	w	Current setpoint [A]	IL_L ≤ w ≤ IL_H [A]	0	X	X	
MEAS_LPF	txt	Low-pass filter for measured value acquisition	1 / 2 / 3 / 4	3	X	X	
MINMAX	txt	Min-max storage for measured U and I values	OFF / ON / RST “ON” → enable tolerance band function for CRB.0/1, ERC.0/1, SIGx_OUT	OFF	X	X	
OC_DELAY	w	Overcurrent protection triggering delay	0.000 ≤ w ≤ 65.535 [s]	0	X	X	
OCP	txt	Overcurrent protection	OFF / ON / R01 ... R12/15*	OFF	X	X	
OCSET	w	Overcurrent protection trigger value	OCSETmin (3) [A] ≤ w ≤ OCSETmax (80 A) [A]	80 A	X	X	
OUTPUT	txt	Switch power output on and off	OFF/ ON	OFF	X	X	
OV_DELAY	w	Overvoltage protection triggering delay	0.000 ≤ w ≤ 65.535 [s]	0	X	X	
OVP	txt	Overvoltage protection	OFF / ON / R01 ... R12/15*	ON	X	X	
OVSET	w	Overvoltage protection trigger value	3 [V] ≤ w ≤ OVSETmax (80 V) [V]	80 V	X	X	
POWER_ON	txt	Response after power on	RST / SBY / RCL / R01 ... R12/15*	RST	X	X	
PSET	w	Power setpoint [W]	0 ≤ w ≤ Pnom (1500, 3000, 4500) [W] (PSET = PNOM) → P-REG. OFF)	Pnom	X	X	
REPETITION	n(,i)	Number of repetitions for sequence function	0 ≤ n ≤ 255; 0 means continuous repetition. i is an optional parameter for the setup memory location (1 through 12/15), which should be written directly with REPETITION.	0	X	X	
SEQUENCE	txt(,n)	SEQUENCE control command	OFF / GO / HOLD / CONT(,n) / STRT / STEP (,n) / BSTP / STOP / ESC n is an optional parameter from start address to stop address	—	X	X	
SIG123	txt1,txt2,txt3	Analog interface signal outputs	OFF / ON / OUT / MODE / SEQ / SSET / U_LO / U_HI / I_LO / I_HI	OFF	X	X	
SINK	txt	Sink function on/off	OFF / ON	ON	X	X	
SM_LOAD	n	Load sequence memory location USET,ISET,TSET,FSET	1 ≤ n ≤ 1536/1700*	—	X	X	
SM_STORE	n	Write current USET,ISET,TSET,FSET to sequence memory location	1 ≤ n ≤ 1536/1700* n = 0: clear contents from start to stop address	—	X	X	
SSET	txt	Command for an assigned switching function	OFF / ON	OFF	X	X	
START_STOP	m,n(,i)	Start and stop address	1 ≤ n1 ≤ n2 ≤ 1536/1700* i is an optional parameter for the setup memory location (1 through 12/15), which should be written directly with START_STOP.	1.1	X	X	
STORE	n,w1,w2,w3,txt	Transfer parameters directly to memory	1 ≤ n ≤ 1536/1700* , memory location address 0 ≤ w1 ≤ Unom [V] 0 ≤ w2 ≤ Inom [V] 0 ≤ w3 ≤ 65.535 [s], 0 means Tdef txt, see “FSET”	—	X	X	
T_MODE	txt1,txt2	Function selection for trigger inputs	OFF / OUT / SQS / SEQ(,n) / LLO / MIN (,n) / AIX / AIU / AII	OFF	X	X	
TDEF	w(,i)	Default time rate for SEQUENCE function	0.001 ≤ w ≤ 65.535 [s] i is an optional parameter for the setup memory location (1 through 12/15*), which should be written directly with TDEF.	0.001	X	X	
TIMEDATE	txt	Set system clock (RTC)	yyyy-mm-ddThh:mm:ss	unv	X	X	
TSET	w	Memory location-specific dwell time for sequence function	0.000 = Tdef, 0.001 ≤ w ≤ 65.535 [s]	0.000	X	X	
UI_C_SET	w1,w2,w3,w4	Reference values for Uout/Iout, tolerance band function	w1, w2: 0 ≤ w1 < w2 ≤ Unom [V] w3, w4: 0 ≤ w3 < w4 ≤ Inom [A]	0,Unom, 0, Inom	X	X	
UL_H (**ULI**M)	w	Upper limit value for voltage setting	Uset ≤ w ≤ Unom [V]	Unom	X	X	
UL_L	w	Lower limit value for voltage setting	0 ≤ w ≤ Uset [V]	0	X	X	
USET	w	Voltage setpoint [V]	UL_L ≤ w ≤ UL_H [V]	0	X	X	
WAIT	w	Additional waiting time	0.001 ≤ w ≤ 65.535 [s]	—		X	

Abbreviating commands: Abbreviated commands are identified with boldface letters. Letters not printed in boldface can be omitted. Example: “**OU**TPUT ON” = “OU ON”
As a rule, letters can be entered in upper or lower case.
Stringing commands together: Several commands is a single data string must be separated by semicolons (;). Example: “USET 12; ISET 8.5; OUTPUT ON”
Formats for numeric parameters: *m, n:* Whole number (integer);
w: Whole number, fixed or floating decimal point number with or without exponent. Examples: “12.5”, “0012.5”, “1.25E1”, “+1.25 e+01”

* /15 or /1700, respectively as from firmware version 004

10.2 Queriable Functions and Parameters

Query Command	Meaning	Response Parameter	Values / Format	Manual	Remote	Sample Response	Response String Length
General Query Commands							
***DDT?**	Define device trigger	txt	Delimiter for commands: ";"		X	`USET 5.123;ISET 10;OUTPUT ON`	≤ 80
***ESE?**	Standard event status enable query	n	0 ≤ n ≤ 255		X	`127`	3
***ESR?**	Standard event status register query	n	0 ≤ n ≤ 255		X	`0`	1
***IDN?**	Query device ID	txt			X	`GMC-I GOSSEN-METRAWATT,PSP1500 P060RU060P,0-Series No 008 ,01. B01`	63
***IST?**	Individual status query	n	n = 0, 1		X	`0`	1
***LRN?** (i)	Query device settings (LEARN) i is an optional parameter for the setup memory (location 1 through 12/15), which should be read out directly.	txt			X		
	Sample response for *LRN?					`OUTPUT OFF;USET +010.000;ISET` `+010.000;PSET +01500.0;UL_L +0` `00.000;UL_H +060.000;IL_L +000` `.000;IL_H +060.000;OVP  ON;OVS` `ET +080.000;OV_DELAY 00.000;OC` `P OFF;OCSET +080.000;OC_DELAY` `00.000;POWER_ON RST;T_MODE OFF` `,OFF;ANALOG_IN  OFF, OFF;SINK` ` ON;C_DYN R;MEAS_LPF 3;MINMAX` `OFF;SIG123  OFF, OFF, OFF;SSET` ` OFF;FSET   NF;TDEF 01.000;TSE` `T 00.000;START_STOP 0001,0005;` `REPETITION 000;DISPLAY  UO, IO`	390
***OPC?**	Operation complete query	n	n = 0, 1		X	`1`	1
***PRE?**	PPOLL enable register enable query	n	0 ≤ n ≤ 255		X	`40`	2
***PSC?**	Power-on status clear query	n	n = 0, 1		X	`0`	≤ 3
***SRE?**	Service request enable query	n	0 ≤ n ≤ 255		X	`32`	≤ 3
***STB?**	Read status byte query	n	0 ≤ n ≤ 127		X	`16`	≤ 3
***TST?**	Self-test function	n	n = 0, 1		X	`0`	1
CRA?	Condition register A	n	0 ≤ n ≤ 255	X	X	`1`	≤ 3
CRB?	Condition register B	n	0 ≤ n ≤ 255	X	X	`0`	≤ 3
ERA?	Device dependent event register A query	n	0 ≤ n ≤ 255	X	X	`1`	≤ 3
ERAE?	Device dependent event register A enable query	n	0 ≤ n ≤ 255		X	`240`	≤ 3
ERB?	Device dependent event register B query	n	0 ≤ n ≤ 255	X	X	`0`	≤ 3
ERBE?	Device dependent event register B enable query	n	0 ≤ n ≤ 255		X	`128`	≤ 3
ERC?	Device dependent event register C query	n	0 ≤ n ≤ 255	X	X	`64`	≤ 3
ERCE?	Device dependent event register C enable Query	n	0 ≤ n ≤ 255		X	`0`	≤ 3
Device-Specific Functions and Queries							
ANALOG_IN**?**	Connection of analog control inputs U(Uext), U(Iext)	txt1,txt2	OFF / ON / SSET	xx	X	`ANALOG_IN   ON, OFF`	19
C_DYN**?**	Setting for current regulating dynamics	txt	R / L	X	X	`C_DYN R`	7
DISPLAY**?**	Digital display function switching	txt1,txt2	txt1: ON / OFF / UO /US / PS txt2: ON / OFF / IO / IS / PO	xx	X	`DISPLAY  UO, PO`	15
ERROR**?**	List of error messages	n1,n2,n3,n4	n1,n2,n3: last error n4: µC-RSTSRC register	X 1)	X	`ERROR 032,031,000.001`	21
FSET**?**	Sequence function parameter	txt	CLR / NF / RU / RI / SOFF / S_ON / AUOF / AUON / AUSS / AIOF / AION / AISS / R01 ... R12/15* / S01 ... S12/15*	X	X	`FSET   NF`	9
IL_H? (**ILI**M**?**)	Upper limit value for current setting	w	+XXX.XXX [A]	X	X	`IL_H +060.000`	13
IL_L?	Lower limit value for current setting	w	+XXX.XXX [A]	X	X	`IL_L +000.000`	13
IMAX**?**	Max. measured current value	w	+XXX.XXX [A]	X	X	`IMAX +000.212`	13
IMIN**?**	Min. measured current value	w	+XXX.XXX [A]	X	X	`IMIN +000.204`	13
IOUT**?**	Presently measured current value	w	+XXX.XXX [A]	X	X	`IOUT +000.208`	13
ISET**?**	Selected current setpoint	w	+XXX.XXX [A]	X	X	`ISET +015.000`	13
MEAS_LPF**?**	Low-pass filter for meas. value acquisition	txt	1 / 2 / 3 / 4	X	X	`MEAS_LPF 3`	10

1) manual: last error only; xx: manual: division into partial functions

Query Command	Meaning	Response Parameter	Values / Format	Manual	Remote	Sample Response	Response String Length
MINMAX**?**	Min-Max storage for measured U and I values	txt	OFF / ON “ON” → enable tolerance band function for CRB.0/1, ERC.0/1, SIGx_OUT	X	X	MINMAX OFF	10
MODE**?**	Momentary control mode of the power output	txt	CV / CC / CP / OL / OFF	LED	X	MODE CV	8
OC_DELAY**?**	Overcurrent protection triggering delay	w	0.000 ≤ w ≤ 65.535 [s]	X	X	OC_DELAY 00.000	15
OCP?	Overcurrent protection	txt	OFF / ON / R01 ... R12/15*	X	X	OCP OFF	7
OCSET**?**	Overcurrent protection trigger value	w	+XXX.XXX [A]	X	X	OCSET +080.000	15
OUTPUT**?**	Output on-off status	txt	OFF/ ON	LED	X	OUTPUT ON	10
OV_DELAY**?**	Overvoltage protection triggering delay	w	XX.XXX [s] 0 ≤ w ≤ 65,535 [s]	X	X	OV_DELAY 00.000	15
OVP?	Overvoltage protection	txt	OFF / ON / R01 ... R12/15*	X	X	OVP ON	7
OVSET**?**	Overvoltage protection trigger value	w	+XXX.XXX [V]	X	X	OVSET +080.000	15
POU**T?**	Current output power	w	+XXXXX.X [W]	X	X	POUT +00002.1	14
POWER_ON**?**	Response after power on	txt	RST / SBY / RCL / R01 ... R12/15*	X	X	POWER_ON SBY	12
PSET?	Power setpoint [W]	w	+XXXXX.X [W] W = Pnom (Pnom/2 for 115 Vac) 1) W ≤ Pnom (Pset<Pnom/2 for 115 Vac) 2)	X	X	PSET +01500.0	13
REPETITION**?** (i)	Number of repetitions for sequence function i is an optional parameter for the setup memory location (1 through 12/15*), which should be read out directly.	n	0 ≤ n ≤ 255; 0 means continuous repetition	X	X	REPETITION 000	15
RLOAD?	Momentary load resistance [Calculated value R = U/I]	w	+XXX.XXX [Ω]	X	X	RLOAD +030.833	14
SEQUENCE**?**	SEQUENCE Status	txt,n1,n2,n3	txt: RDY / HALT / RUN n1: 000 ≤ n1 ≤ 012/15* (setup memory) n2: 001 ≤ n2 ≤ 255 (remaining repetitions), n2 = 999 = continuous n3: 0001 ≤ n3 ≤ 1536/1700* (memory location)	xx	X	SEQUENCE RDY,000.999,0005	26
SIG123**?**	Analog interface signal outputs	txt1,txt2,txt3	OFF / ON / OUT / MODE / SEQ / SSET / U_LO / U_HI / I_LO / I_HI	X	X	SIG123 MODE, OUT, OFF	21
SINK?	Sink function on/off	txt	OFF / ON	X	X	SINK ON	8
SSET**?**	Status of an assigned switching function	txt	OFF / ON	X	X	SSET OFF	8
START_STOP**?** (i)	Start and stop address i is an optional parameter for the setup memory location (1 through 12/15), which should be read out directly.	m,n	1 ≤ n1 ≤ n2 ≤ 1536/1700*	xx	X	START_STOP 0001.0005	20
STORE**?** (m(,n(,tab)))	Read data from sequence memory See “Descriptions of Operating Commands” for further details.	n,w1,w2,w3, txt	n: memory location address w1: +XXX.XXX [V] w2: +XXX.XXX [A] w3: XX.XXX [s] txt: “FSET”	xx	X	STORE 0003,+020.000,+015.000,00.000, NF	40
T_MODE**?**	Function status for trigger inputs 1 and 2	txt1,txt2	OFF / OUT / SQS / SEQ(,n) / LLO / MIN (,n) / AIX / AIU / AII	X	X	T_MODE OUT,LLO	15
TDEF**?** (i)	Default time for sequence function i is an optional parameter for setup memory (1 through 12/15), which should be read out directly.	w	0.001 ≤ w ≤ 65.535[s]	X	X	TDEF 01.000	12
TIMEDATE**?**	System clock time/date (RTC)	txt	yyyy-mm-ddThh:mm:ss	xx	X	TIMEDATE 2007-10-08T12:27:13	28
TSET**?**	Memory location-specific dwell time for sequence function	w	0.000 ≤ w ≤ 65.535[s] 0.000 = Tdef,	X	X	TSET 00.000	12
UI_C_SET**?**	Reference values for Uout/Iout, tolerance band function	w1,w2,w3,w4 [V][V][A][A]	w1, w2: 0 ≤ w1 < w2 ≤ Unom [V] w3, w4: 0 ≤ w3 < w4 ≤ Inom [A]	xx	X	UI_C_SET +000.000,+060.000,+000.000,+060.000	44
UL_H? (**ULI**M?)	Upper limit value for voltage setting	w	+XXX.XXX [V]	X	X	UL_H +060.000	13
UL_L?	Lower limit value for voltage setting	w	+XXX.XXX [V]	X	X	UL_L +000.000	13
UMAX?	Max. measured voltage value	w	+XXX.XXX [V]	X	X	UMAX +010.004	13
UMIN**?**	Minimum measured voltage value	w	+XXX.XXX [V]	X	X	UMIN +009,992	13
UOUT**?**	Presently measured voltage value	w	+XXX.XXX [V]	X	X	UOUT +009.998	13
USET**?**	Selected voltage setpoint	w	+XXX.XXX [V]	X	X	USET +010.000	13

Terminating device messages: The following end-of-text characters can be used for data receipt: With IEC bus control: NL (hex: 0A) or NL & EOI or DAB & EOI;
With RS 232C control: NL or CR (hex: 0D) or ETB (hex: 17) or ETX (hex: 03).

The following end-of-message character is used when transmitting the response string: With IEC bus control: NL & EOI;
With RS 232C control: last received end-of-message character.

Abbreviating commands: Abbreviated commands are identified with boldface letters. Letters not printed in boldface can be omitted. Example: “**OU**TPUT ?” = “OU?”
As a rule, letters can be entered in upper or lower case.

Stringing commands together: Several commands is a single data string must be separated by semicolons (;). Example: “USET?; ISET?; OUTPUT?”

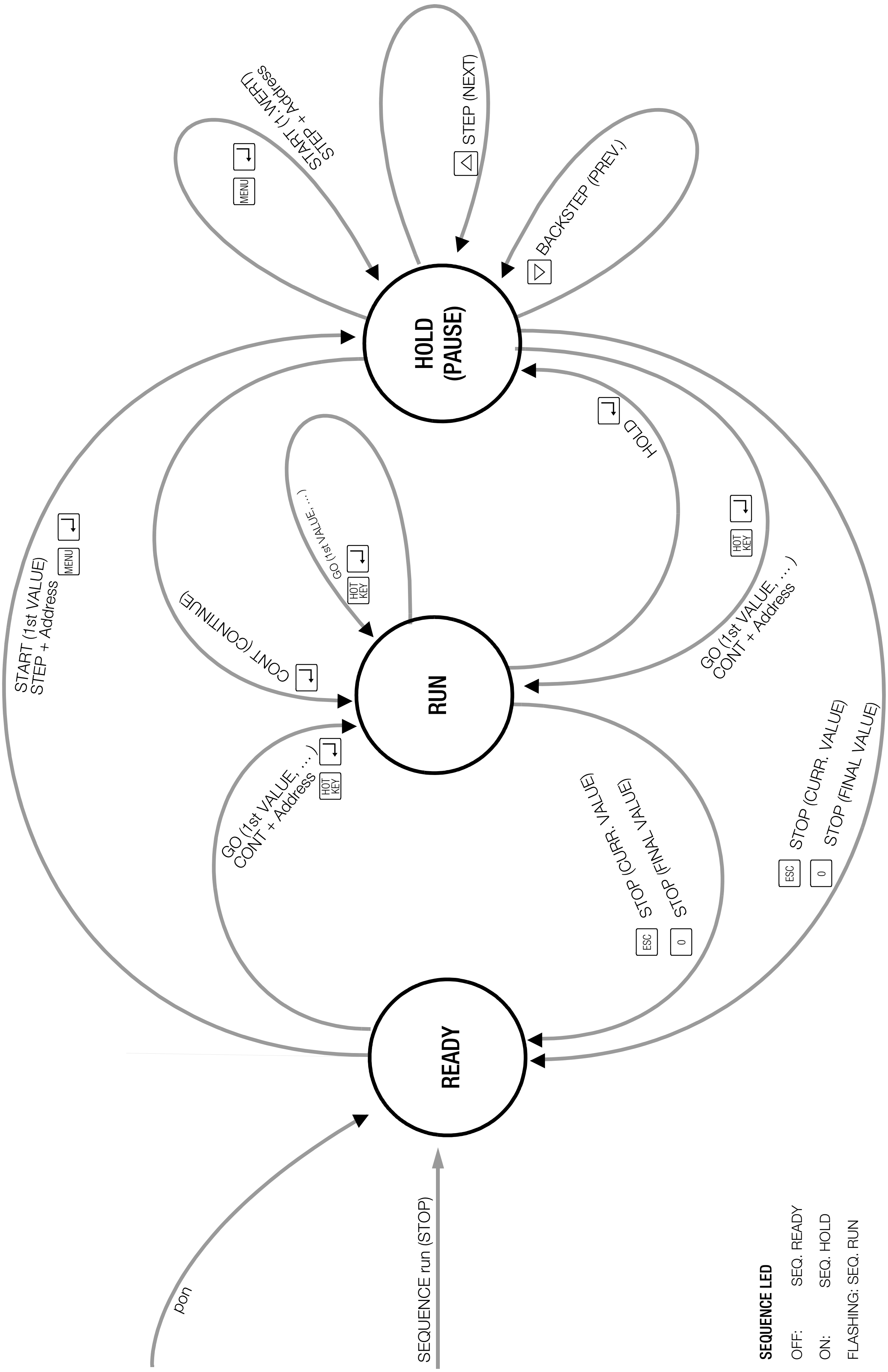
1) Constant voltage and/or constant current mode

2) Constant power mode

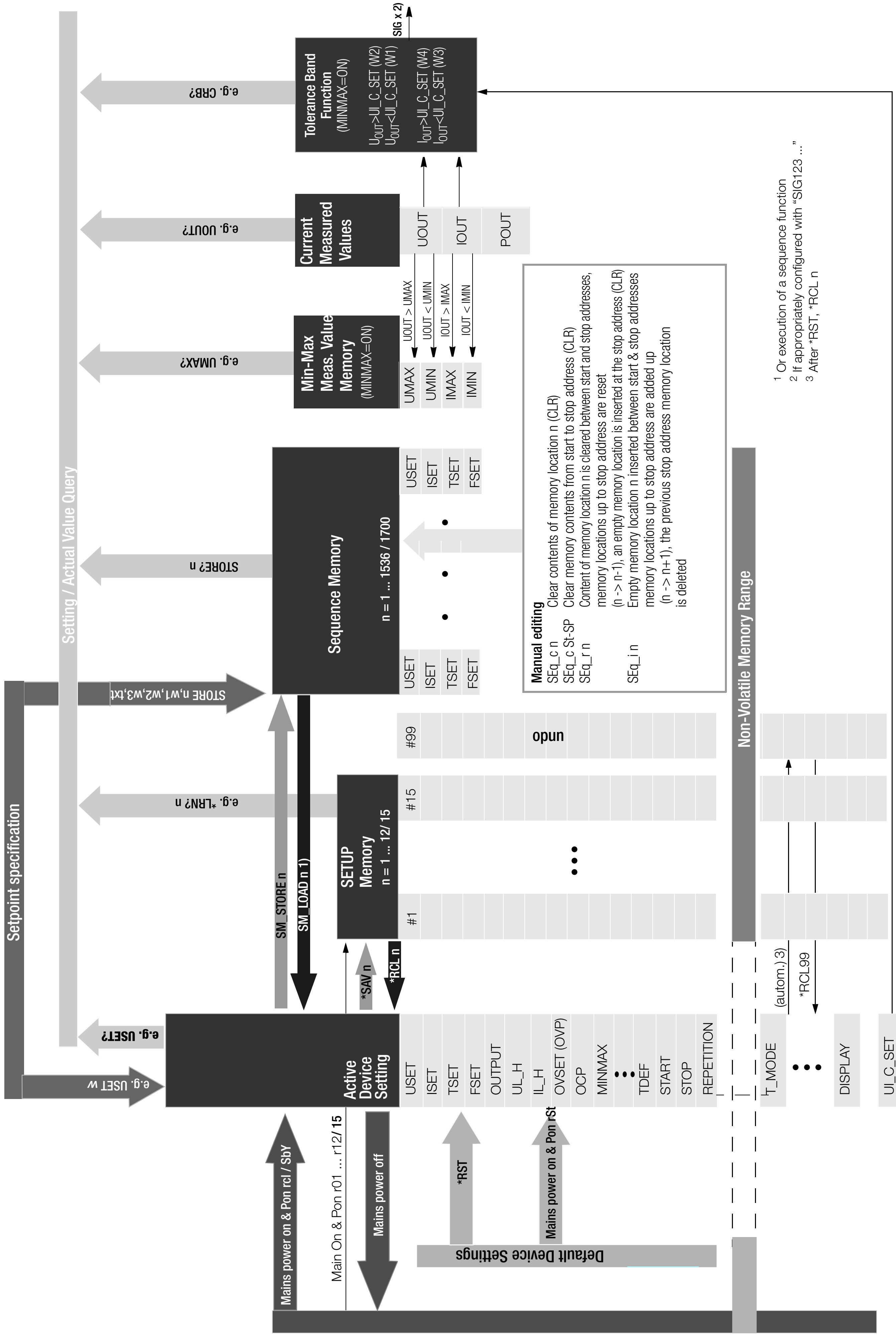
* /15 or /1700, respectively as from firmware version 004

xx: manual: division into partial functions

10.3 Sequence Status Diagram



10.4 Memory Structure



11 System Messages

Procedures and entries are monitored in order to provide the user with support.

The device is capable of detecting and reading out a great variety of defective procedures.

In the case of manual operation, the error appears directly at the display for a brief period of time. In addition to this, the last error message can be viewed with the help of the appropriate menu function.

Err appears at the left-hand display, and the three digit error code at the right-hand display.

In the case of operation with a PC, the last three error messages can be accessed by executing the ERROR? command (see **ERROR?** command in the section entitled "Descriptions of Operating Commands".

Code Err...	Meaning / Cause	Remedy
00	No error	
01	TYPE (BZ) detection	For internal production process only
05	UNKNOWN KEYCODE, or in case of "LCL LOCKED", [ESC] has been briefly activated for enabling	
12	CMD buffer overflow	Overflow at internal CMD buffer
21	USET, ISET, PSET (parameter error)	
22	UL,IL (parameter error)	
29	DDTE *DDT command string > 80 characters or ?*TRG? within *DDT ...	
31	CME command error	General
32	EXE execution error	General
	Interface	
51	RS 232, PB, parity bit	
52	RS 232, SB, stop bit	
53	PB + SB, RS 232	
54	RS232, FRAME OVERFLOW (impermissible combination DB/PB/SB)	Only occurs during manual configuration
55	Active talker state but no listener present	Only possible with IEEE 488 interface option
56	IEC$LATA$ERR (active listener and active talker)	Only possible with IEEE 488 interface option
61	ADJUST parameter error	
62	ADJUST order impermissible (REMOTE)	
63	[U/I]-OFFSET/FULL SCALE -> (!) [CV/CC] MODE	Corresponding operating mode required!
64	ADJUST LIMITs or OFFSET (MEASUREMENT NEGATIVE or OVERFLOW)	
66	CALIBRATION ERROR/EXIT (-> UNCAL)	
69	MEMORY DATA (-> ERROR) ?)	Faulty data, possible cause: low battery
71	Table values (#): USET<UL_L, USET>UL_H, ISET<IL_L, ISET>IL_H	Limit error during sequence execution
73	OUTE: "OUTPUT ON" =/= Tx MODE "OUT" & Tx-SIG "OUT OFF"	Trigger mode power output and signal blocked (=OFF!)
74	TRGE: "MINMAX ON" =/= Tx MODE "MIN" & Tx-SIG "MINMAX OFF"	Min-max control for the trigger mode and signal blocked (=OFF!)
75	TRGE: "SEQUENCE ON" =/= Tx MODE "SEQ" & Tx-SIG "SEQUENCE STOP"	Sequence control for the trigger mode and signal blocked (=OFF!)
76	TRGE: "ANALOG INP" =/= Tx MODE "AI?" & Tx-SIG (UEXT,IEXT)	Uext, Iext control for the trigger mode and signal blocked (=ON!)
81	RCL n (no data): SETUP memory n: invalid or no data	
82	START -> STOP - INVALID VALUES	
83	START-ADR > STOP-ADR	
84	Not (STOP_ADR < MEM < START_ADR) or SUBSEQUENCE (cond.)	Address range or storage address is out of actual start-stop-address range or is an active subsequence. Specify the sequence range for delete and repeat command.
85	CONTINUE (no initialization, status =/= "HALT")	
86	SUBSUBSEQUENCE impermissible	
89	"SEQUENCE OFF" required for current command	
91	SELFTEST (*TST?)	
96	MIN LIMIT UNDERFLOW, direct entry of a numerical value	requires > UL_L and/or > IL_L
93	Current command not permissible for power control!	Impermissible combination of functions
96	MIN LIMIT UNDERFLOW	Numerical direct entry of a numerical value > UL_L and/or > IL_L necessary
97	MIN LIMIT UNDERFLOW	
98	MAX LIMIT OVERFLOW	
99	OVERLOAD / OVERFLOW	

DISPLAY left	right	Meaning/Cause	Remedy
Err	**PFC**	PFC Error	Inadequate/unstable line voltage or device error, not ready for operation, device controls disabled, shutdown (OUTPUT OFF)
Err	**AC-H**	Change from AC-LOW to AC-HIGH	Transition from the „lower“ line voltage range (= status after power ON) AC_L to the „upper“ range AC_H generates message „ERR AC-H“. Please note: Pnom value is not automatically raised in the process! A **new „Power ON“** is required for this purpose, including: – automatic RESET (parameter setting: „POWER_ON RST“) or – subsequent „RESET“ (manual operation/interface) or – Recall of a suitable SETUP memory (which has not been saved under power derating conditions!) (Pnom is the reference quantity for the PSET function!)
Err	**AC-L**	Change from AC-HIGH to AC-LOW	**up to and including firmware 004:** Transition from the „upper“ line voltage range to the „lower“ range generates message „ERR AC-L“ and **results in a shutdown** if no power derating has been active (operation disabled, „Power ON“ required!) Transition from the „upper“ line voltage range AC_H to the „lower“ range AC_L generates message „ERR AC-L“ **without shutdown** if power derating has already been active. **as from firmware 005:** Transition from the „upper“ line voltage range to the „lower“ range generates the message „ERR AC-L“ and results in power derating, as long as the status „AC LOW“ „lower“ line voltage range applies. Upon reversal of the line voltage to the „upper“ line voltage range (status „AC HIGH“), the power derating is cancelled.
Err	**AC-F**	AC-FAIL	Inadequate/unstable line voltage or device error, not ready for operation, device controls disabled, shutdown (OUTPUT OFF) **as from firmware 010:** Temporary deactivation for the purpose of device protection. If insufficient/instable line voltage is present or a device error occurs, the instrument shuts down (OUTPUT OFF) and is not ready for operation during this time. After approximately 0.25 s, an automatic restart is performed by the instrument in accordance with the settings for POWER_ON (standby, reset, recall).

RSTSRC (RESET SOURCE REGISTER):

Description / Text per Data Sheet no. C8051F122

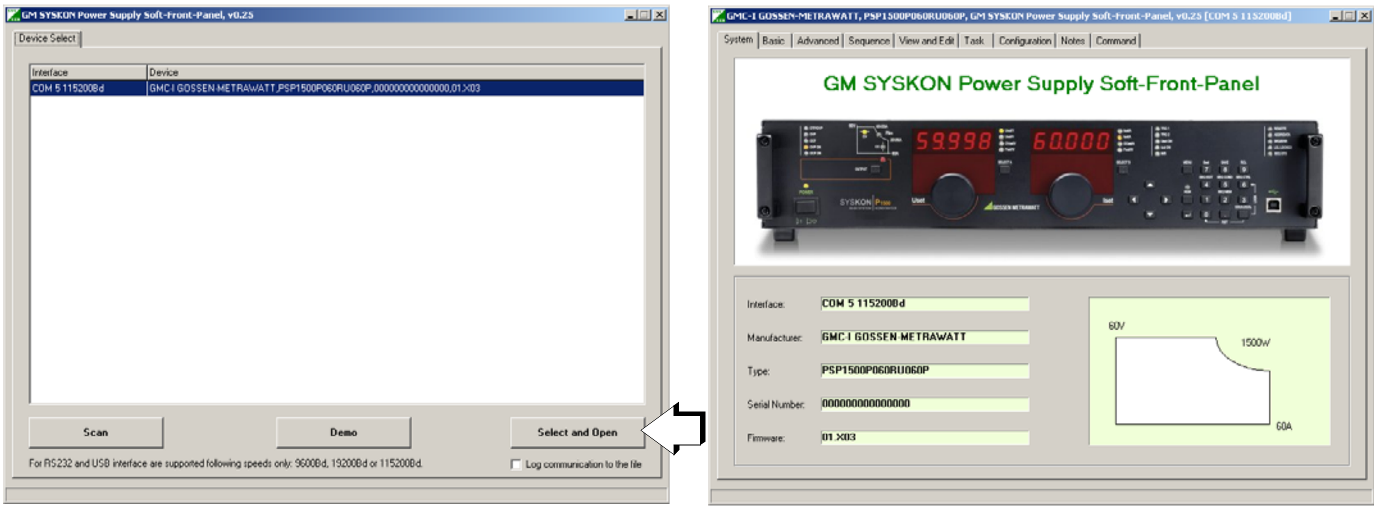
D7	(80H): RESERVED
D6	(40H): CNVRSEF: (CONVERT START 0 RESET SOURCE FLAG)
D5	(20H): CORSEF: (COMPARATOR 0 RESET FLAG)
D4	(10H): SWRSF: SOFTWARE RESET FLAG
D3	(08H): WDTRSF: WATCHDOG TIMER RESET FLAG
D2	(04H): MCDRSF: MISSING CLOCK DETECTOR FLAG
D1	(02H): PORSF: POWER-ON RESET FLAG
D0	(01H): PINRSF: HW PIN RESET FLAG

12 Operating Software

Comprehensive operating software is provided for the SYSKON Konstanter (on the included CD-ROM, or can be downloaded from our website).

The software is started by running the EXE file; no further installation is required.

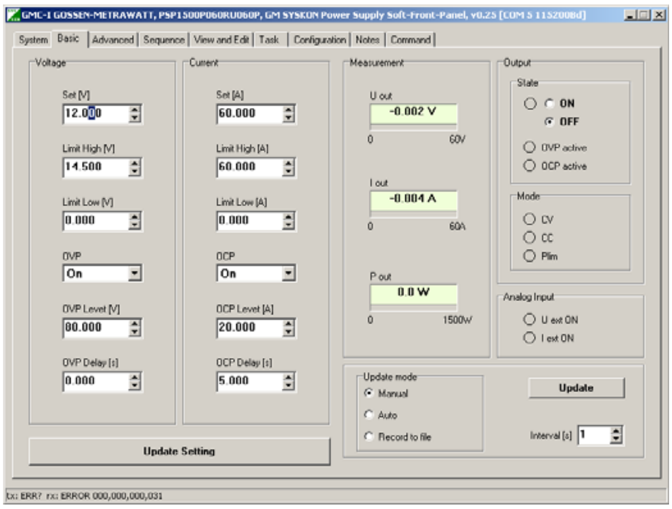
The software detects devices which are connected to the various possible interfaces including USB, RS 232 and GPIB. Devices detected by the software are identified and can be selected. If more than one device is connected, the software can be started several times in order to operate them.



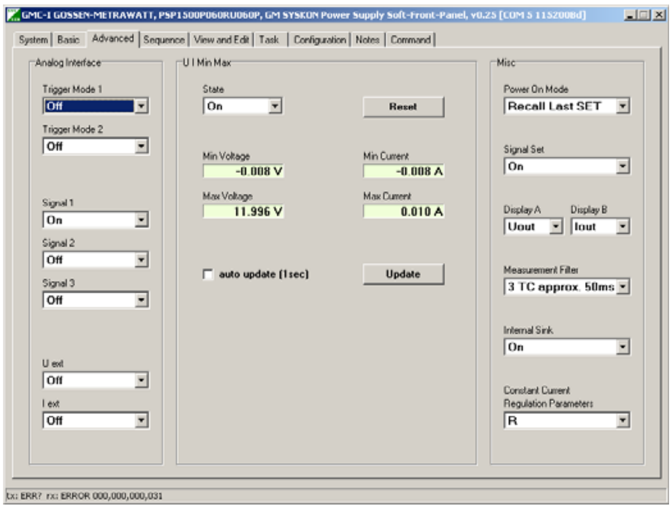
The activated device logs on via the soft front panel and is thus unequivocally recognized.

Sub-menus

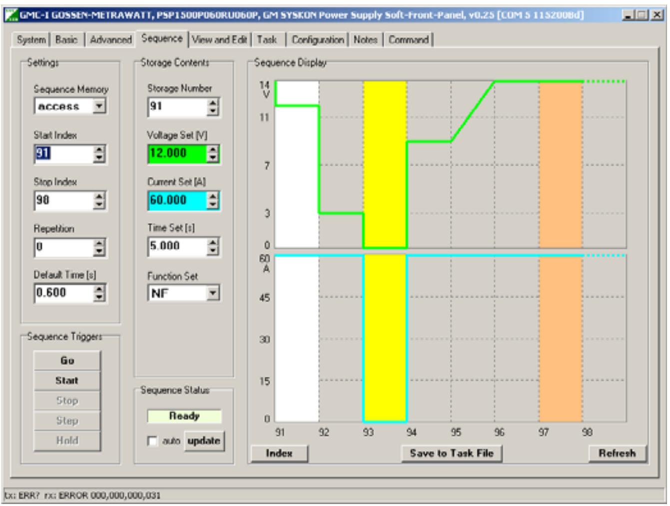
Further operation can be carried out as shown in the figures.



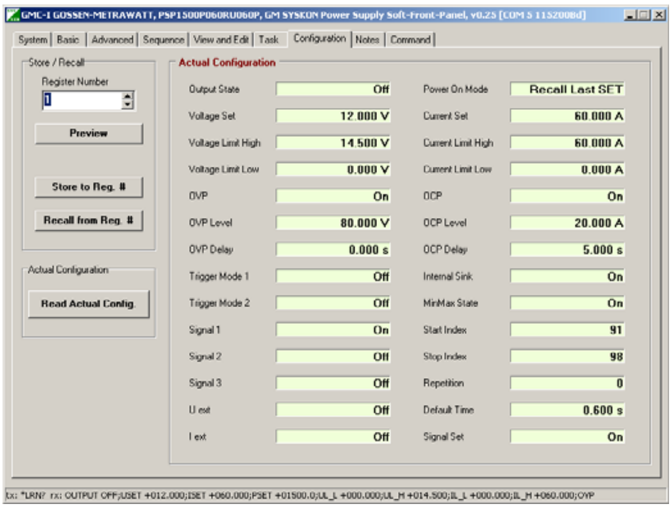
Basic panel



Advanced panel

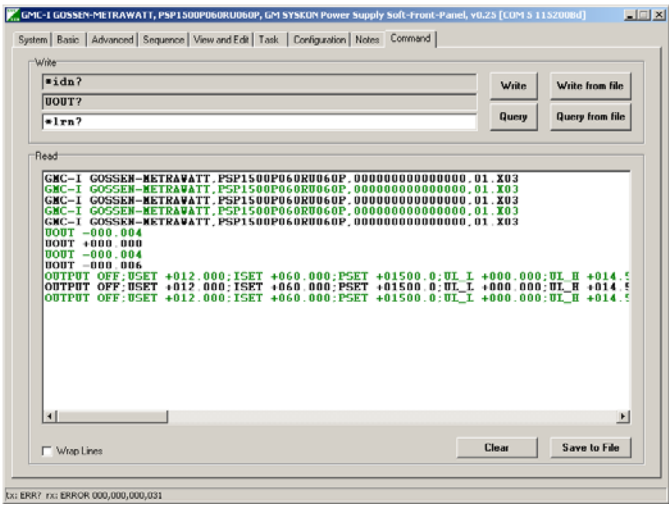


Sequence panel



Configuration panel

Task panel



Command panel

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14 Order Information

Description (abbreviated name)	Article Number
SYSKON P500-060-030 SYSTEM KONSTANTER	K346A
SYSKON P800-060-040 SYSTEM KONSTANTER	K347A
SYSKON P1500-60-60 SYSTEM KONSTANTER	K353A
SYSKON P3000-060-120 SYSTEM KONSTANTER	K363A
SYSKON P4500-060-180 SYSTEM KONSTANTER	K364A
Option IEEE 488 interface for SYSKONKONSTANTER	K384A

Software

Further information regarding operating software and drivers is available for download on the internet:

http://www.gossenmetrawatt.com

Accessories

Description	Note	Article No.
RS 232 bus cable, 2 m	For connecting a device to an RS 232 interface (extension cable, 9-pin socket / 9-pin plug connector)	GTZ32410 00R0001

15 Repair and Replacement Parts Service Calibration Center* and Rental Instrument Service

If required please contact:

GMC-I Service GmbH
Service Center
Beuthener Straße 41
90471 Nürnberg, Germany
Phone: +49 911 817718-0
Fax: +49 911 817718-253
e-mail service@gossenmetrawatt.com
www.gmci-service.com

This address is only valid in Germany. Please contact our representatives or subsidiaries for service in other countries.

* **DAkkS Calibration Laboratory for Electrical Quantities D-K-15080-01-01 accredited per DIN EN ISO/IEC 17025**

Accredited quantities: direct voltage, direct current value, direct current resistance, alternating voltage, alternating current value, AC active power, AC apparent power, DC power, capacitance, frequency, temperature

Competent Partner

GMC-I Messtechnik GmbH is certified in accordance with DIN EN ISO 9001.

Our DAkkS calibration laboratory is accredited by the Deutsche Akkreditierungsstelle GmbH (National accreditation body for the Federal Republic of Germany) in accordance with DIN EN ISO/IEC 17025 under registration number D-K-15080-01-01.

We offer a complete range of expertise in the field of metrology: from **test reports** and **factory calibration certificates**, right on up to **DAkkS calibration certificates**.

Our spectrum of offerings is rounded out with free test equipment management.

Our service department includes an **on-site DAkkS calibration bench**. If errors are discovered during calibration, our specialized personnel are capable of completing repairs using original replacement parts.

As a full service calibration lab, we can calibrate instruments from other manufacturers as well.

16 Product Support

If required please contact:

GMC-I Messtechnik GmbH
Product Support Hotline
Phone: +49 911 8602-0
Fax: +49 911 8602-709
e-mail: support@gossenmetrawatt.com

17 Manufacturer's Guarantee

The SYSKON Konstanter is guaranteed for a period of 2 years after shipment. The manufacturer's guarantee covers materials and workmanship. Damages resulting from use for any other than the intended purpose, as well as any and all consequential damages, are excluded.

Calibration is guaranteed for a period of 12 months.

GOSSEN METRAWATT

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